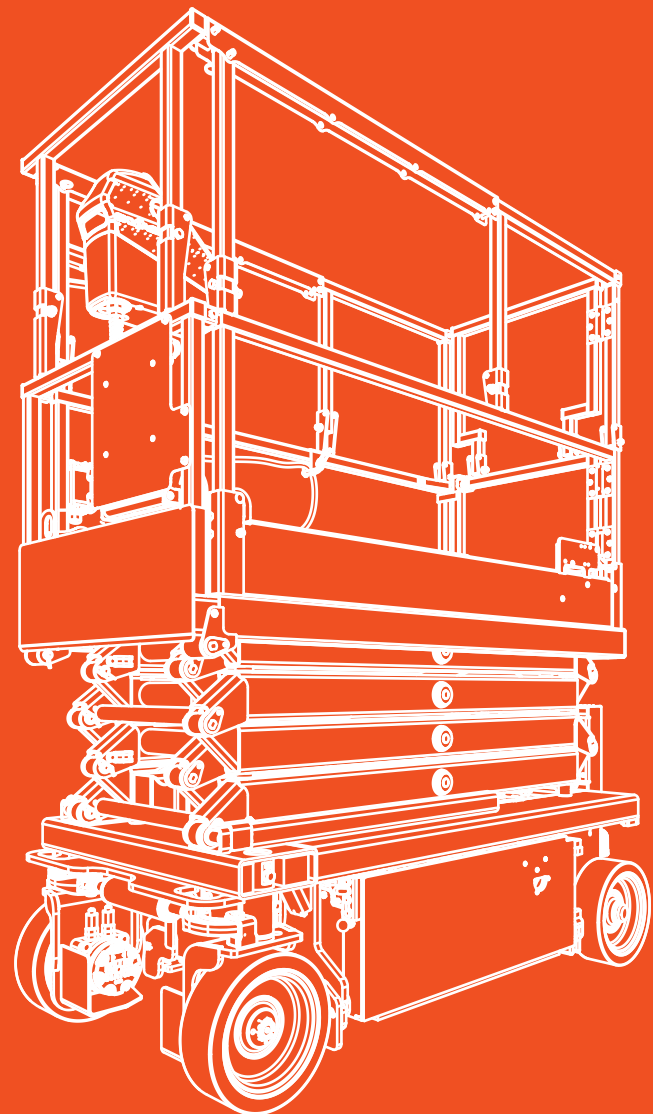




SERVICE MANUAL

SJ3215, SJ3219

DC ELECTRIC SCISSORS



212508AGA

November 19 2025

ANSI/CSA, CE, AS, KC

This manual is for MEWPs with serial numbers:

SJ3215: A100 000 001 - A100 039 999

SJ3215: C100 000 001 - C100 039 999

SJ3219: A100 000 001 - A100 039 999

SJ3219: C100 000 001 - C100 039 999

Please refer to the website (www.skyjack.com) for contact information, other serial numbers, the most recent technical manuals, animations, and USB software.

The original instructions are in English.

THIS SAFETY ALERT SYMBOL MEANS ATTENTION!



BECOME ALERT! YOUR SAFETY IS INVOLVED.

The Safety Alert Symbol identifies important safety messages on MEWPs, safety signs in manuals or elsewhere. When you see this symbol, be alert to the possibility of personal injury or death. Follow the instructions in the safety message.

 DANGER

DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

 WARNING

WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

 CAUTION

CAUTION indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury. It may also be used to alert against unsafe practices.

IMPORTANT

IMPORTANT indicates a procedure essential for safe operation and which, if not followed, may result in a malfunction or damage to the MEWP.

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Section 1 – Maintenance

1.1 Read and Heed

Skyjack is continuously improving and expanding product features on its equipment; therefore, specifications and dimensions are subject to change without notice.

1.1-1 Mobile Elevating Work Platform (MEWP) definition

A MEWP is a mobile machine intended for moving persons, tools, and material to working positions. It consists of a work platform with controls, an extending structure, and a chassis.

1.1-2 Purpose of equipment

The Skyjack DC Electric Scissor lifts are designed to move personnel, tools, and materials to working positions.

1.1-3 Use of equipment

The MEWP is a highly maneuverable, mobile work station. Only elevate the platform, or drive while elevated on a firm, level surface.

1.1-4 Service Policy and Warranty

Skyjack warrants each new product to be free of defective parts and workmanship for the first 2 years or 3000 hours, whichever occurs first. Your local Skyjack dealer will replace or repair any defective part, with no charge for parts or labour. In addition, all products have a 5-year structural warranty. Contact the Skyjack service department for warranty statement extensions or exclusions.

1.1-5 Ownership of MEWP

Notify Skyjack of MEWP ownership. If you sell or transfer the ownership of a MEWP, promptly notify Skyjack of the new owner's contact information.

Skyjack needs this information to inform the owner of any updates or additional activities that are necessary to keep the machine in proper working condition.

1.1-6 Optional equipment

This MEWP accepts a variety of optional equipment. Refer to the operation manual for a list of the optional accessories. Operating instructions for these options are in the operation manual.

For components or systems that are not standard, speak to the Skyjack service department. Give the model and serial number for each applicable MEWP.

1.2 General information

1.2-1 Owner's annual inspection record

The owner is responsible for the maintenance inspections and repairs. Keep a record of the annual inspection on the label on the scissor stack. Refer to [1.4 Owner's annual inspection record](#).

1.2-2 Replacement parts

Use only original replacement parts. Parts such as batteries, wheels, railings, etc. with weights and dimensions different from the original parts will affect the stability of the MEWP. They must not be used without the manufacturer's consent.

All replacement tires must be of the same size and load rating as the originally supplied tires to maintain the safety and stability of the MEWP.

WARNING

A unit that is damaged or not operating correctly must be immediately tagged and removed from service until repairs are completed.

1.2-3 Maintenance and service safety tips

1. Maintenance and repair should only be done by personnel who are trained and qualified to service this MEWP.
2. Do the maintenance and service procedures in a well-lit and well-ventilated area.
3. Anyone operating or servicing this MEWP must read and fully understand all operating instructions and safety hazards in both this manual and the operation manual.
4. Make sure all tools, supports, and lifting equipment are of the correct rated load and in good working condition.
5. Keep the work area clean and free of debris to avoid component contamination.
6. Make sure personnel are not below unsupported components or systems that are at risk of movement during maintenance.
7. All service personnel must be familiar with the employer and governmental regulations for servicing this type of equipment.
8. Keep sparks and flames away from flammable or combustible materials.
9. Correctly dispose of waste material such as lubricants, rags, and old parts in accordance with national, state/provincial/territorial, and local regulations.
10. Before you do any repair work, disconnect the main power connectors.

1.2-4 Hydraulic system & component maintenance and repair

WARNING

The fluid which escapes from a high-pressure hydraulic leak can damage your eyes, penetrate your skin, and cause serious injury. Wear the correct personal protective equipment at all times.

1. The hydraulic circuits include relief valves which limit pressure to safe operation values. They help to prevent the failure of hydraulic or structural components.
2. Make sure the hydraulic oil is completely clean. Even small amounts of dirt or unwanted materials in the system can damage components and cause unsatisfactory operation of the hydraulic system.
3. Drain and flush the entire system and replace the filter cartridges if you have any reason to believe there is contamination of the hydraulic system, or hydraulic system failure.
4. When you drain the hydraulic system, check the magnets in the hydraulic tank for metal particles. Metal particles can indicate imminent component failure. If metal particles are present, flush the entire system and change the hydraulic oil.
5. All containers and funnels used in handling the hydraulic oil must be completely clean. Use a funnel when necessary and fill the reservoir only through the filter opening. Do not use a cloth to strain the oil, as lint could get into the system.
6. When you remove a hydraulic component, cap and tag all of the hydraulic lines involved. Plug the ports of the removed components.
7. Disassemble hydraulic components in clean surroundings. Carefully identify the parts to make sure you reassemble them correctly. Clean all metal parts in a clean mineral oil solvent. Be sure to clean all internal passages fully. After the parts are dry, lay them on a clean, lint-free surface for inspection.
8. Replace all O-rings and seals when you overhaul a component. Lubricate all parts with clean hydraulic oil before you reassemble them. Use a small amount of petroleum jelly to hold O-rings in place during assembly.
9. Be sure to replace lost hydraulic oil after you install the repaired component. Bleed air from the system when required.
10. Keep all hydraulic connections tight. A loose connection in a pressure line allows the oil to leak or draw air into the system. Air in the system can damage components and cause noisy or erratic system operation.
11. Preventive maintenance is the easiest and least expensive type of maintenance.

1.2-5 Hydraulic oil maintenance

Draw samples of hydraulic oil from the reservoir annually and test them.

- Take these samples when the oil is warmed through normal operation of the system.
- Have the sample analyzed by a qualified lubrication specialist to determine if it is suitable for continued use.

Oil change intervals depend on the care used to keep the oil clean, and the operating conditions.

- Oil must be changed more often when there is dirt or moisture contamination.
- Under normal use and operating conditions, you should change the hydraulic oil every two years. Refer to Table 1.5 *Frequent/periodic/annual/pre-delivery inspection checklist* of this manual.

1.2-6 Hydraulic maintenance tips

1. Change the filters annually. Dirty, dusty, and high-moisture environments can cause the hydraulic system to be contaminated more quickly. You may need to change the filters more often.
2. Keep a sufficient quantity of clean hydraulic oil of the correct type and viscosity in the hydraulic tank.
3. Keep all hydraulic connections tight.

1.2-7 Railing maintenance and repair

Skyjack MEWPs have been designed to ensure compliance with the relevant design standards applicable for that particular unit at the time of manufacture. As such, any repairs made to the guardrail or basket structure need to ensure this compliance is not compromised and must return the structure to its original condition.

Any damage must be repaired by returning the railing assembly to its undamaged state. Damage includes, but is not limited to, the items listed below:

- bent/deformed guardrail sections
- cracks or broken welds in railing sections
- damaged pin connections
- missing pins or broken pin lanyards
- missing railing hardware
- loose or missing parts
- additional holes in guardrail sections other than those approved by Skyjack

Additionally, the guardrails must be properly positioned and secured, and the entry gate must be in good working order.

The strength of the guardrail system, and therefore its ability to provide fall protection for platform occupants, depends upon the design being secure and undamaged.

Skyjack railings are designed for modular replacement, and Skyjack recommends replacement of any damaged railing section. Skyjack-approved replacement parts will meet this requirement.

1.2-8 Multi-conduction control cable repair

If damage occurs to the outer casing of a multi-conductor control cable, you may use heat shrink tubing to case and protect the control cable casing.

Before you install the heat shrink, make sure there is no damage to the individual wires contained in the control cable, or to their insulation.

The heat shrink tubing selected and used should seal the electrical circuit from water intrusion, be suitable for the machine operating temperature range, and be suitably flexible to allow the required bending radius of the cable in its application.

1.3 Scheduled maintenance and inspections

1.3-1 Service bulletins

Before performing any scheduled maintenance inspection procedure, refer to the service bulletins found on our website: www.skyjack.com for updates related to the service and maintenance of this MEWP.

1.3-2 Maintenance and inspections

Death or injury can result if the MEWP is not kept in good working order. Inspection and maintenance should be done by competent personnel who are trained and qualified on maintenance of this MEWP.

WARNING

Failure to perform each procedure as presented and scheduled may cause death, serious injury, or substantial damage.



NOTE

Preventive maintenance is the easiest and least expensive type of maintenance.

- Unless otherwise specified, do each maintenance procedure with the MEWP in the following configuration:
 - Park the MEWP on a flat and level surface
 - Disconnect the batteries by disconnecting the main power connectors.
- Repair damaged or malfunctioning components before operating the MEWP.
- Keep records of all inspections.

1.3-3 Schedule and instructions

The actual operating environment of the MEWP may affect the maintenance schedule.

The inspection points covered in the [1.5 Frequent/periodic/annual/pre-delivery inspection checklist](#) indicate the areas of the MEWP to be maintained or inspected, and at what intervals the maintenance and inspections are to be done.

Inspection schedule frequency:

PDI/Frequent/ Periodic	B	Do a PDI before each delivery, or a Frequent Inspection every 200 days or 200 hours.
Annual	C	Do a Scheduled Maintenance Inspection every year.
Additional	*	Do this at time-sensitive maintenance intervals.

- Make copies of the maintenance and inspection checklist to be used for each inspection.
- Check the schedule on the checklist for the type of inspection to be done.
- Place a check mark in the appropriate box after each inspection procedure is done.
- Use the maintenance and inspection checklist and the step-by-step procedures in [1.6 Scheduled maintenance inspections](#).
- If an inspection receives a fail, tag and remove the MEWP from service.
- If a MEWP components has been repaired, do an inspection again before you remove the tag. Place a check mark in the repair column.

Legend

Pass	P
Not applicable	N/A

1.3-4 Function tests

Function tests are designed to discover malfunctions before a MEWP is put into service.

Refer to the “*Inspections before operation*” section of the operation manual for detailed instructions on how to do the function tests.















IMPORTANT

Never use a malfunctioning MEWP. If malfunctions are discovered, tag the MEWP and remove it from service.

1.3-5 Repairs

When repairs are made to a MEWP, the service technician must complete the full pre-operation inspection and function tests before putting the MEWP into service.

Table 1.4 Owner's annual inspection record

 Model _____ SN _____										
 Inspection Date										
	20	20	20	20	20	20	20	20	20	20
 Inspector Signature										

⚠ WARNING

Do not use the MEWP if there is no inspection recorded in the last 13 months. If you do not obey, there is a risk of death or serious injury.

IMPORTANT

The Owner's annual inspection record on the scissor assembly must be filled out after an annual inspection is completed.

1.5 Frequent/periodic/annual/pre-delivery inspection checklist

SKYJACK Frequent/Periodic/Annual/PDI Checklist Vertical Mast, Electric Scissor, Micro Scissor & Rough Terrain

Serial Number: Starting with serial number A/B/C000 000 000 or 09 000 000 and above

Product Owner: _____

Model: _____

Product User: _____

Date/Time: _____

Hourmeter Reading: _____

Inspection Type (Choose one): Pre-delivery Frequent Periodic Annual

Use this table for pre-delivery inspections (PDI) before each rental, lease or sale and as an instruction for all frequent inspections and annual inspections. Refer to the operation and service manuals for inspection instructions (for example, visual inspection and function tests, torque specs, engine oil, chain inspection intervals, and more).

Inspection Type Schedule		B - Do the pre-delivery inspection before the machine is sent out or during the frequent inspections at 200 days or 200 hour intervals. For more instructions, refer to the operation and service manuals.	P - Pass N/A - Not Applicable
PDI/Frequent/Periodic	B	C - Do the scheduled maintenance Inspections each year. For more instructions, refer to the operation and service manuals.	
Annual	B+C		

Put a check mark on the "Pass" column as you meet the requirements of the inspection of each item. Add a comment if the item does not pass inspection.

Items for Inspection	P	N/A
Service Bulletins. Make sure there are no open service bulletins.	B	
Annual Inspection. Make sure you complete it within 13 months.	B	
Labels. In place, correctly attached & you can read them.	B	
Limit Switches. Correctly installed & no obstructions or damage.	B	
BASE/ENGINE		
Engine and Components. Do a check on engine and components for any loose, missing, damaged, or failed items. Make sure you do not exceed the recommended fluid, oil and coolant change intervals.	B	
Engine and Components. Replace the engine oil and filter.	C	
Engine Intake Air Filter. No damage or missing component. Remove dirt & dust.	B	
Engine Intake Air Filter. Replace the air filter if necessary.	C	
Engine Oil. Oil level between "L" and "H". Make sure you do not exceed the oil change interval.	B	
Radiator. Correctly attached & no damage or missing components. Do a check of coolant level.	B	
Radiator. Do a check of coolant level & condition & replace if necessary.	C	
Fuel Tank & Lines. Filler cap, tank, fittings and hoses are tightly closed & no damage or leaks.	B	
Propane Tank & Lines. Straps are correctly installed to brackets & couplers are tight. Make sure there are no damage or leaks.	B	
Outriggers. No damage or missing components.	B	
Pothole Protection. Both sides have no obstructions, dirt or damage.	B	
Battery/Hydraulic Tray. Trays are latched tightly & no missing components.	B	
Batteries. No damage, tight connections & sufficient fluid levels. Clean terminals and cable ends.	B	
Battery Charger. Correctly attached & no damage.	B	
Steer Assembly. Correctly attached & no damage leaks or missing components.	B	
Wheel/Tire Assembly. Do a check of all tires for damage, missing parts, wear & correctly aligned.	B	
Wheel/Tire Assembly. Wheel nuts torqued as recommended.	C	
Axles. Correctly attached & no missing components. Tight fittings and hoses & no leaks.	B	
Axles. Do a check and replace oil if necessary.	C	
Hydraulic Tank, Pump, Motor & Lines. Filler cap, hoses, and other hydraulic components are closed tightly & no damage or leaks.	B	
Hydraulic Oil. Level at, or slightly above top mark.	B	
Hydraulic Oil. Do a check and replace oil and filters if necessary.	C	
Electrical Components. Do a check on all electrical components such as the motor controller if necessary. Correctly attached & no damage. Tight wire connections and fasteners.	B	

Items for Inspection	P	N/A
Manifolds. Tight fittings and hoses & no damage or leaks. Tight wire connections, no missing components & correctly working valves.	B	
Main Power Disconnect Switch. Cables tight & in working order.	B	
Base Controls. Operate switches and make sure they all operate correctly. No damage or missing components.	B	
Brakes. Correctly attached & no damage or leaks.	B	
Brakes. Do a check on disc wear and replace if necessary.	C	
Base Weldment. No deformation or cracks.	B	
Grease Points. No obstructions, dirt, or damage. Add grease if necessary.	B	
Ladder. Correctly attached & no damage.	B	
Tilt Sensor. Correctly attached & no damage.	B	
LIFTING MECHANISM - MAST/SCISSORS		
Maintenance Support(s). Correctly attached & no damage.	B	
Scissor Assembly & Bumpers. Correctly attached, no deformation/damage. Cables & wires installed with no damage.	B	
Sliders & Rollers. Correctly attached & no obstructions, dirt, or damage/wear.	B	
Lift Cylinder(s). No damage or missing components. Tight fittings and hoses & no leaks. Correctly installed.	B	
Height Sensor. Correctly attached & no damage.	B	
Scissor Pins. Correctly attached & no damage.	B	
Mast Assembly. No damage, cracks or deformation.	B	
Mast Assembly. Lubricate the mast as recommended.	C	
Chains, Rollers & Control Cables. No damage or missing components.	B	
Wear Pads. No damage/wear or missing components. Fasteners tight.	B	
PLATFORM		
Railings and Gate. Correctly attached & no damage or missing components.	B	
Fall-Protection Anchorage. Attachment rings correctly attached & no damage.	B	
AC Power Socket. No obstructions, dirt, or damage.	B	
Platform Control Console. Operate the switches and make sure they all operate correctly. No damage or missing components.	B	
Manual Storage Box. Manuals and documents are in storage box, in good condition, and you can read them.	B	
Powered Extension Control Console. Operate switches and make sure they all operate correctly. No damage or missing components.	B	
Extension Platform. Correctly attached & no damage or missing components.	B	
Function Tests. Refer to the operation manual for your serial number for information on how to run these tests.		PASS
		FAIL

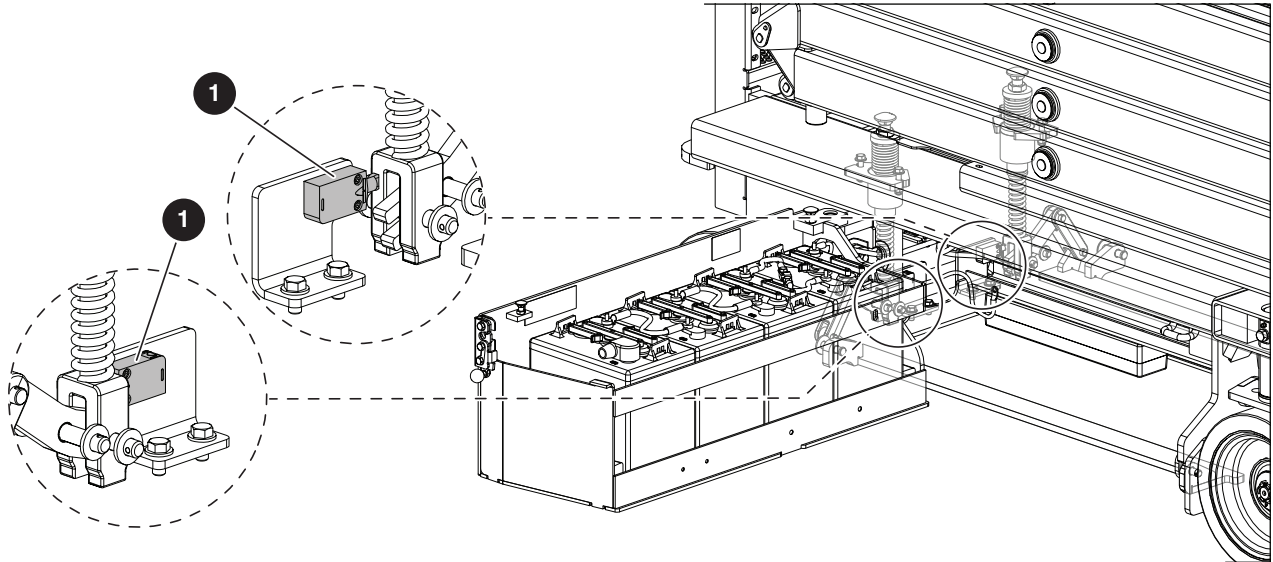
199341AFA

Comments: _____

The undersigned has made sure that all areas in the list have received an inspection.
The undersigned has told the machine owner of all inconsistencies in the inspection and corrected them before machine operation.

Owner: _____ Print Name _____ Signature _____ Date (DD/MM/YY) _____

User: _____ Print Name _____ Signature _____ Date (DD/MM/YY) _____



1.6 Scheduled maintenance inspections

Do an inspection of the MEWP in this sequence:

⚠ CAUTION

Make sure the MEWP is on a firm, level surface before you do the visual and daily maintenance inspections. If you do not obey, there is a risk of machine damage.

⚠ WARNING

Turn the main power disconnect switch to the off position before you do the visual and daily maintenance inspections. If you do not obey, there is a risk of death or serious injury.

⚠ WARNING

Do not operate a MEWP that does not function correctly. Lock and tag the MEWP, and remove it for servicing. Only a qualified service technician must repair the MEWP. If you do not obey, there is a risk of death or serious injury.

1.6-1 Service bulletins

(B) Go to www.skyjack.com and use your machine's serial number to find related open service bulletins.

1.6-2 Annual inspections

(B) Do a check on the machine's service record to find information about previous service performed.

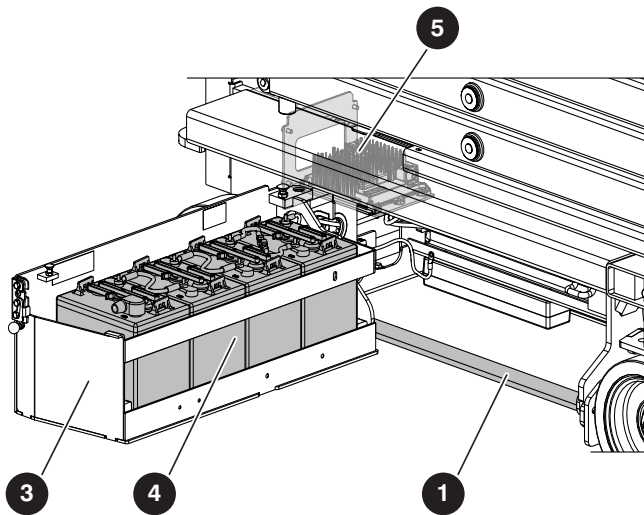
1.6-3 Labels

(B) Refer to the operation manual for the labels. Make sure all the labels are in the correct location, are in good condition, and you can read them.

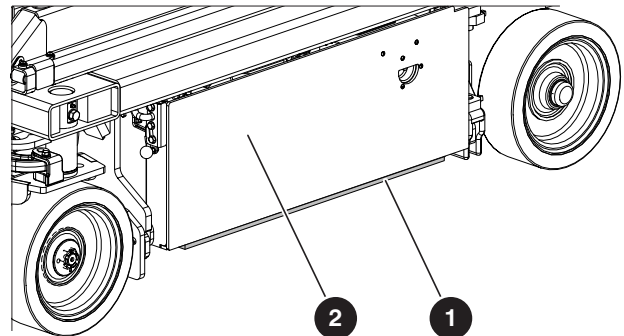
1.6-4 Limit switches

(B) Make sure the **pothole protection limit switches** **1** are correctly attached with no visible damage, and the movement is not blocked.

Example model SJ3219 Battery Tray



Example model SJ3219 Hydraulic Tray



1.6-5 Base

1 Pothole protection device (B)

- Make sure there are no loose or missing parts.
- Make sure there is no visible damage.
- Make sure there is no dirt and blockages.

2 Hydraulic and electric tray (B)

- Make sure that the hydraulic and electric tray latches correctly and is in good condition.

3 Battery tray (B)

- Make sure the battery tray latches correctly and is in good condition.

4 Batteries (B)

⚠ WARNING

Explosion hazard. Keep flames and sparks away. Do not smoke near the batteries. Batteries release explosive gas while you charge them. Charge the batteries in a well-ventilated area. If you do not obey, there is a risk of death or serious injury.

⚠ WARNING

Corrosion hazard. Do not touch battery acid. Wear the correct PPE. If the battery acid touches you, immediately flush the area with cold water and get medical aid.

1. Do an inspection of the battery case for damage.

2. Make sure all the battery connections are tight.

3. Clean the battery terminals and cable ends thoroughly with a terminal cleaning tool or wire brush.

4. If applicable, do a check on the battery fluid levels. If the plates do not have a minimum 13 mm (1/2 inch) of solution above them, add distilled or demineralized water.

5. Replace the battery if it is damaged or is not able to hold a lasting charge.

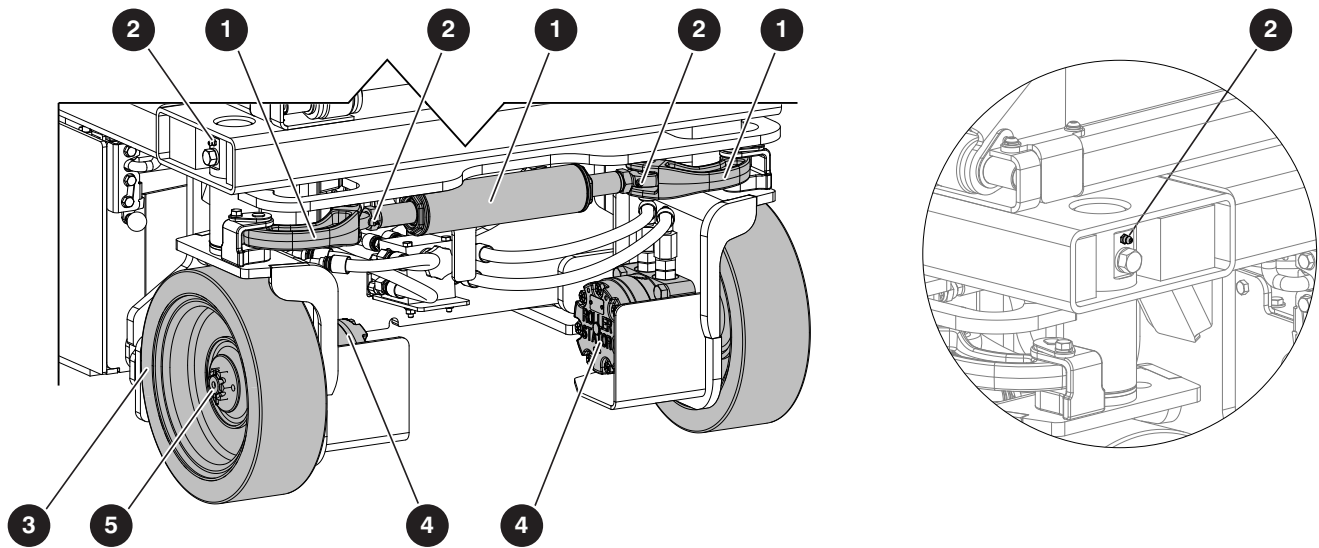
⚠ WARNING

Only use original or manufacturer-approved parts and components for the MEWP. If you do not obey, there is a risk of death, serious injury, or machine damage.

5 Battery charger (B)

- Make sure the battery charger is correctly installed, and in good condition.
- Make sure there is no visible damage.

Example model SJ3219



1 Steer assembly (B)

▪ **Steer cylinder assembly (B)**

- Make sure the steer cylinder assembly is correctly installed.
- Make sure there are no loose or missing fasteners.
- Make sure there is no visible damage.

▪ **Steer linkages (B)**

- Make sure there are no loose or missing fasteners and lock pins.
- Make sure the steer linkages and bushings are correctly attached.
- Make sure there is no visible damage.

2 Grease points (B)

- Make sure there is no visible damage.
- Make sure there is no dirt or blockages.
- Add grease if necessary.

3 Wheel/tire assembly (B)

A small amount of wear is permitted. But if any of the wear or damage meets the criteria mentioned below, the tire should be replaced.

⚠ WARNING

Do not use tires other than the tires that Skyjack specifies for this MEWP. Do not mix different types of tires or use tires that are not in good condition. Only replace the tires with the same types that are approved by Skyjack. The use of other tires can make the MEWP less stable. If you do not obey, there is a risk of death or serious injury.

The tire treads have been removed from the illustration for clarity.

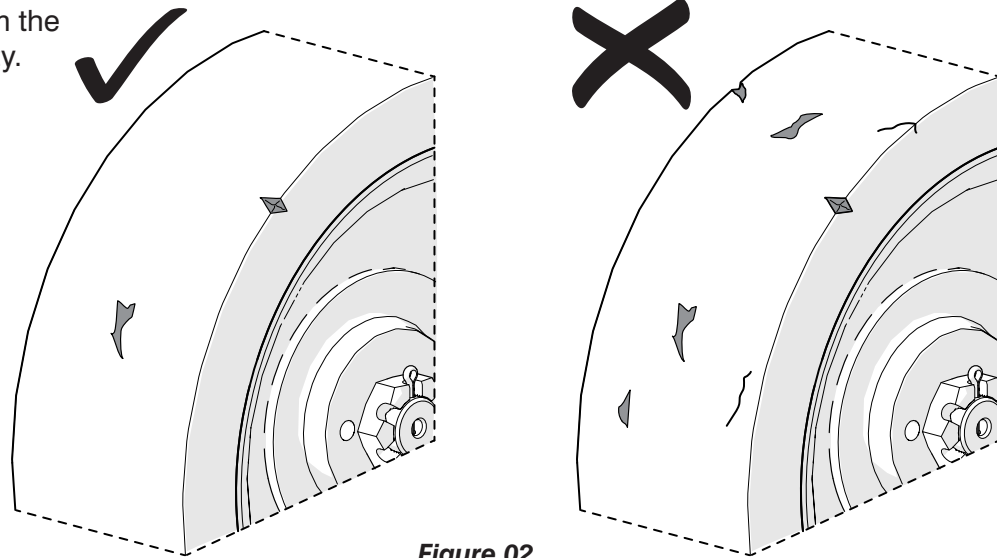


Figure 02

▪ **B - Frequent/periodic/pre-delivery inspection**

Do a check for damage or wear on each tire and rim.

- Look for damage or cracked welds on each rim. The rims should be round.
- Look for uneven or unusual wear on the tire.
- Look for flat spots on the tread face of the tire.
- The tire tread should be visible and not worn down completely. Refer to Figure 01.

Do a check for cuts or missing chunks in the edges and tread face of the tire. Refer to Figure 02.

- The cut or missing chunk must not extend more than 10 mm (3/8") towards the centre of the tire.
- Each cut or chunk should not be larger than 25 mm x 10 mm (1" x 3/8"), or deeper than 20 mm (3/4").
- There should be no more than 2 cuts or chunks in each 1/4 section of the tire. There must be no more than 6 cuts or chunks in total in the tire.
- There should be no embedded debris.

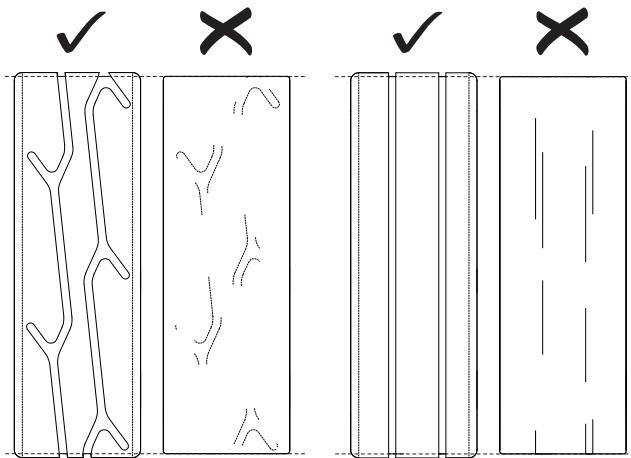


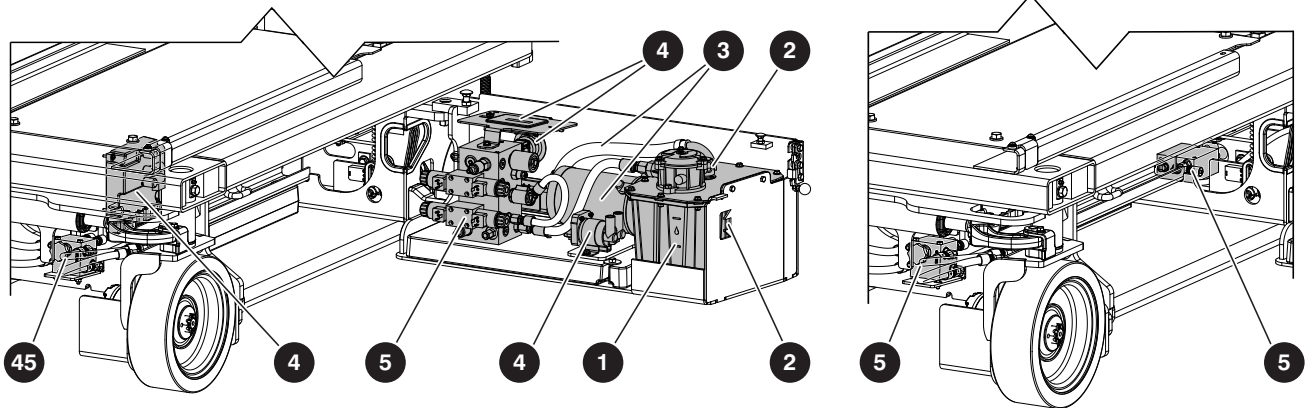
Figure 01

Do a check of the wheel components and mounts.

- Make sure the wheels are correctly aligned vertically and horizontally.
- Make sure the **wheel motors** ④ have no loose or missing parts and there is no visible damage.
- Make sure the **castle nuts** ⑤ are in position and are tight.
- Make sure the **cotter pins** are correctly installed.
- If the cotter pin is not installed, refer to [2.6 MEWP torque specifications for proper torque information](#).

Example model SJ3219 ANSI/CSA

SJ3219 CE, AS & KC Manifolds



1 Hydraulic tank (B)

- Make sure the hydraulic filler cap closes tightly.
- Make sure there is no visible damage or hydraulic leaks.

2 Hydraulic oil level (B, C)

- **B - Frequent/periodic/pre-delivery inspection**
 - Fully lower the platform.
 - Do a check on the gauge on the left side of the hydraulic oil tank. The hydraulic oil level must be at or a small distance above the top mark of the gauge.
- **C - Annual inspection**
 - Do a check of the hydraulic oil for contamination and make sure the filter is in good condition.
 - Replace the hydraulic oil and filters if necessary.

3 Hydraulic pump and motor (B)

- Make sure there are no loose or missing fasteners.
- Make sure there is no visible damage.

4 Electrical components (B)

- Do a check on these areas for chafed, corroded, and loose wires:
 1. Base to platform cables and wiring harness
 2. Battery tray wiring harnesses
 3. Hydraulic and electrical wiring harnesses.

Skycoded™ display panel (B)

- Make sure the panel is correctly attached, and there is no visible damage.

Motor controller (B)

- Make sure the motor controller is correctly attached, and there is no visible damage.
- Make sure there are no loose wires or missing fasteners.

Motor contactor (B)

- Make sure the motor contactor is correctly attached, and there is no visible damage.
- Make sure there are no loose wires or missing fasteners.

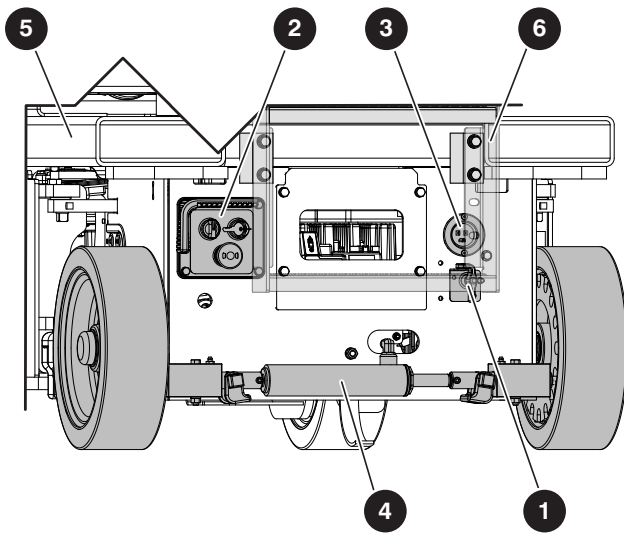
Emergency lowering switch (B)

- Make sure the emergency lowering switch is correctly attached, and there is no visible damage.
- Make sure the toggle switch operates correctly.
- Make sure there are no loose wires or missing fasteners.

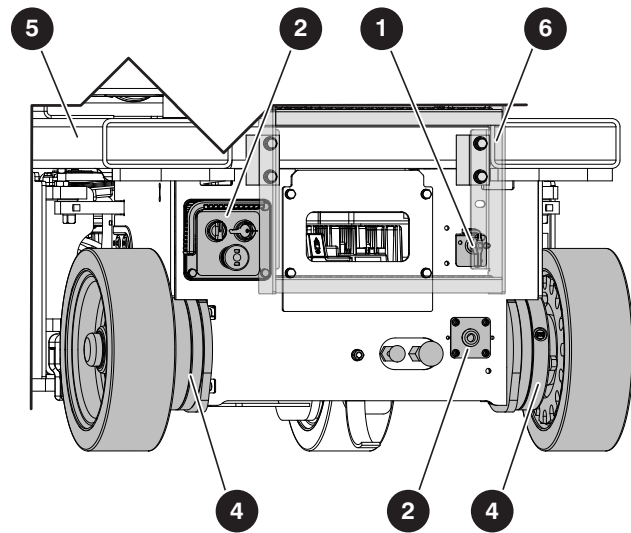
5 Manifolds (B)

- Make sure all fittings and hoses are correctly tightened.
- Make sure there is no indication of hydraulic leakage.
- Make sure there are no loose wires or missing fasteners.
- Make sure all the manual valves operate correctly and do not seize.

Example model SJ3219 ANSI/CSA



Example model SJ3219 CE, AS & KC

**1 Main power disconnect switch (B)**

- Turn the main power disconnect switch to the off position.
- Make sure the switch rotates and stays in the on and off positions.
- Make sure the cables are not loose.

2 Base control (B)

- Make sure there is no visible damage, and all the switches operate correctly.

3 AC power socket (B)

- Make sure the socket is free of dirt or blockages.

4 Brakes (B, C)

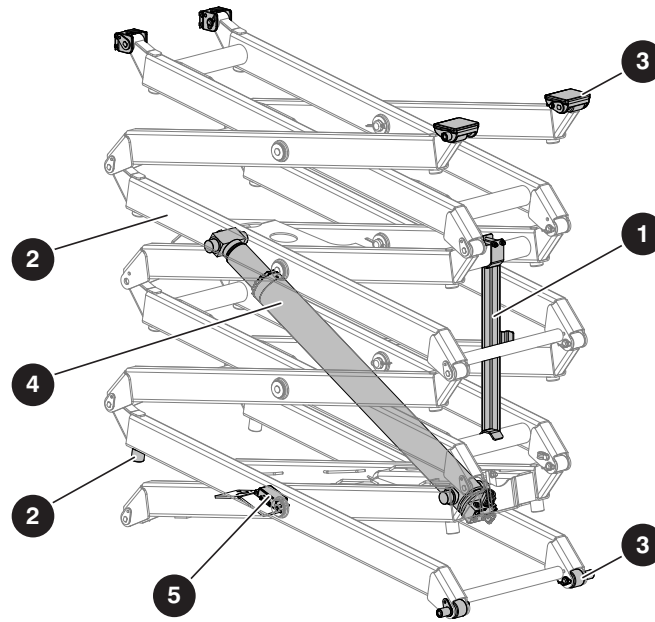
- **B - Frequent/periodic/pre-delivery inspection**
 - Make sure there are no loose or missing fasteners.
 - Make sure there is no visible damage.
- **C - Annual inspection**
 - Make sure that the disc or pin brakes show no signs of wear and/or physical damage.
 - Replace the disc or pin brakes if necessary.

5 Base weldment (B)

- Make sure that the base shows no signs of visible damage, deformation, or cracks in the weldments.

6 Ladder (B)

- Make sure there are no loose or missing parts.
- Make sure there is no visible damage.



1.6-9 Scissors

1. Raise the platform and deploy the maintenance supports.

1 Maintenance support (B)

- Make sure that the maintenance supports are correctly attached and show no visible damage.

2 Scissor assembly and bumpers (B)

- Make sure the scissor assembly shows no signs of visible damage, deformation, or cracks in the weldments.
- Make sure all the pins and fasteners are correctly installed.
- Make sure the cables and wires have the correct routing, and show no signs of wear or visible damage.
- Make sure the bumpers are correctly attached and have no visible damage.

3 Sliders and rollers (B)

- Make sure the sliders and rollers on the left and right sides of the MEWP are correctly attached.
- Make sure there is no visible damage.
- Make sure there is no dirt or blockages in the slider's and roller's travel paths.

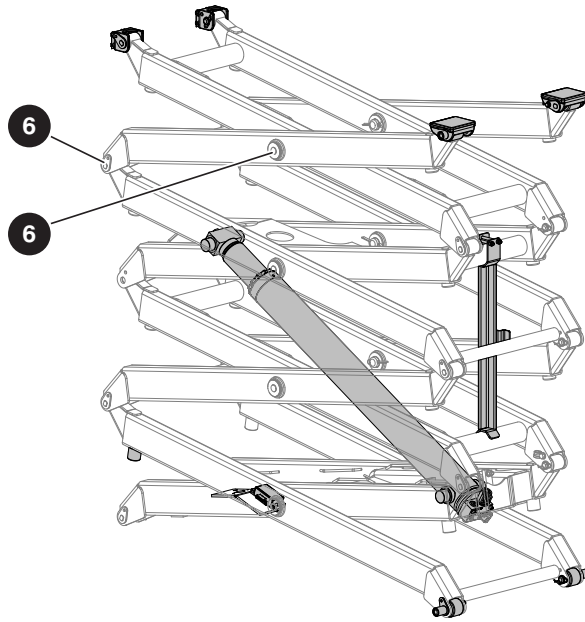
4 Lift cylinder (B)

- Make sure the lift cylinders are correctly installed.
- Make sure there are no loose or missing fasteners.
- Make sure there is no indication of leaks or damage.

5 angle transducer (B)

- Make sure that the angle transducer is correctly attached.

2. Fully lower the platform.



6 Scissor pin inspection (B)

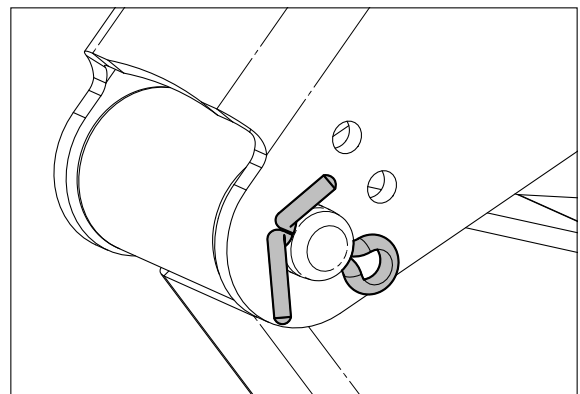
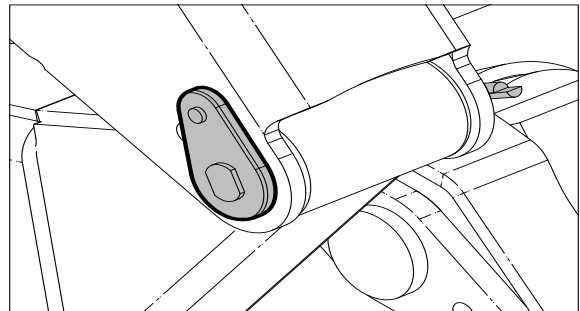
⚠ WARNING

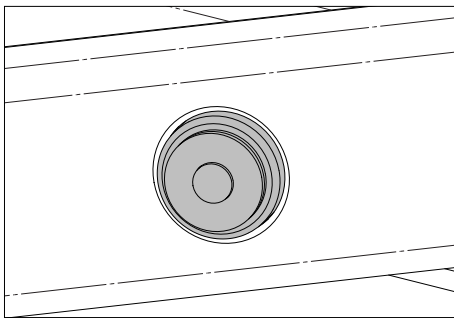
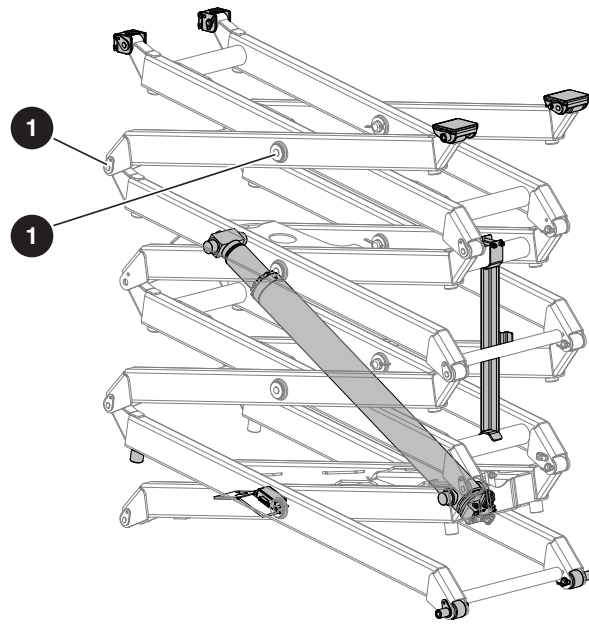
Units that show signs of damage must be immediately removed from service and repaired by a qualified technician. Speak to the Skyjack service department for directions on how to repair the unit.

1. Do an inspection of the scissor pin connections. Look for signs of damage on the pins and scissor arms. These signs can include:
 - Noise can be heard from seized pins.
 - Rust near the pin joint
 - Cracks in welds of adjacent metals
 - Dust or metal shaving from worn components
 - Broken or missing pin retainer bolts
 - Broken or missing pin retainers
 - Rotated pin
 - Elongated or enlarged pin hole
2. Remove damaged pins and bushings. Do an inspection of the scissor bore after removing the applicable pins and bushings. Look for signs of damage, elongation and ovality of the hole.
3. If there is no structural damage to the scissor arms, replace the pins and bushings with new components.

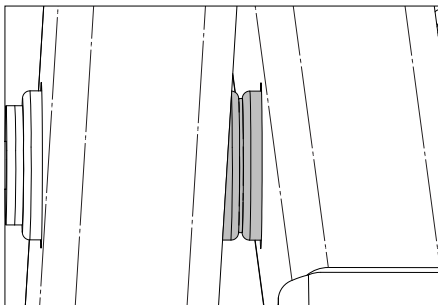
Examples of pivot pin connections with no damage:

- No rust
- Pin has not rotated
- Area is clear of dust or metal shavings
- Pin retainers are installed

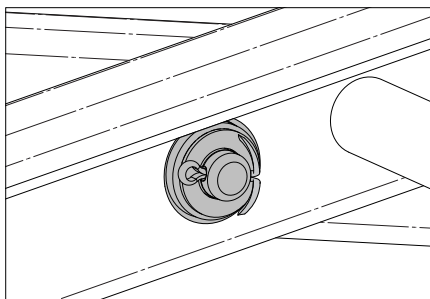




Center Pin - Outer



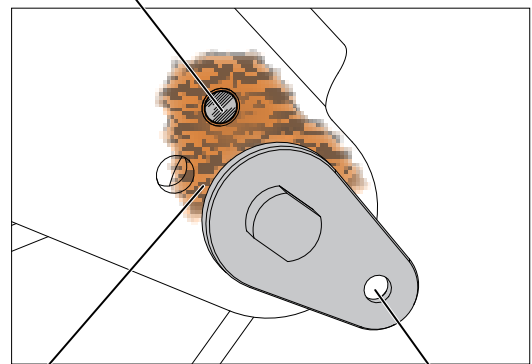
Center Pin - Middle



Center Pin - Inner

Examples of damaged pin connections:

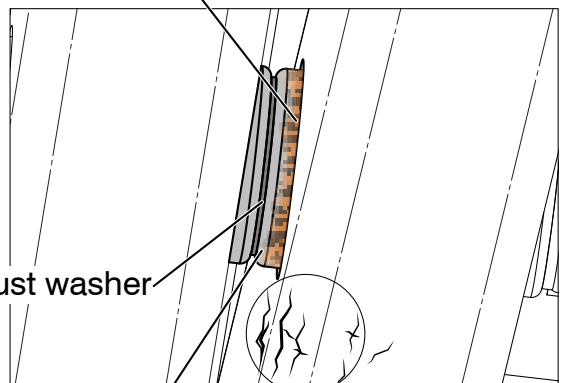
Broken retainer bolt



Rust around the pin

Rotated pin

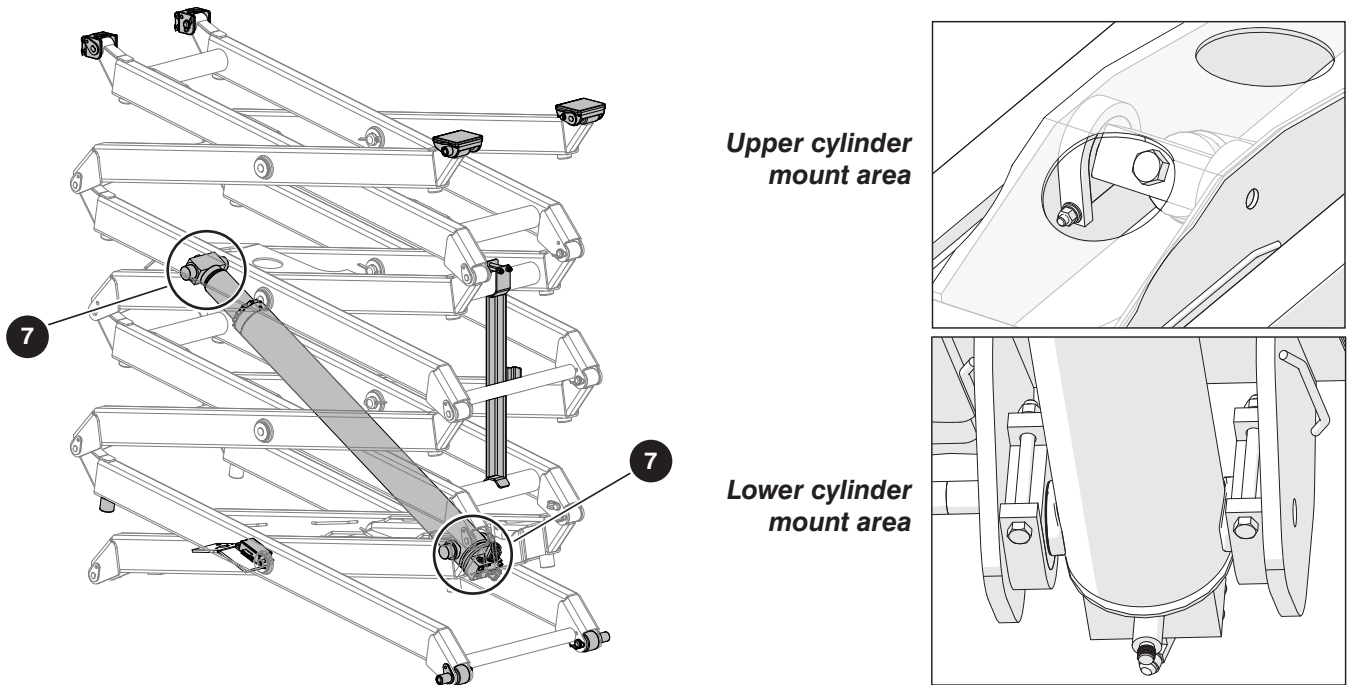
Rust around pin boss



Thrust washer

Broken pin boss

Stress cracks



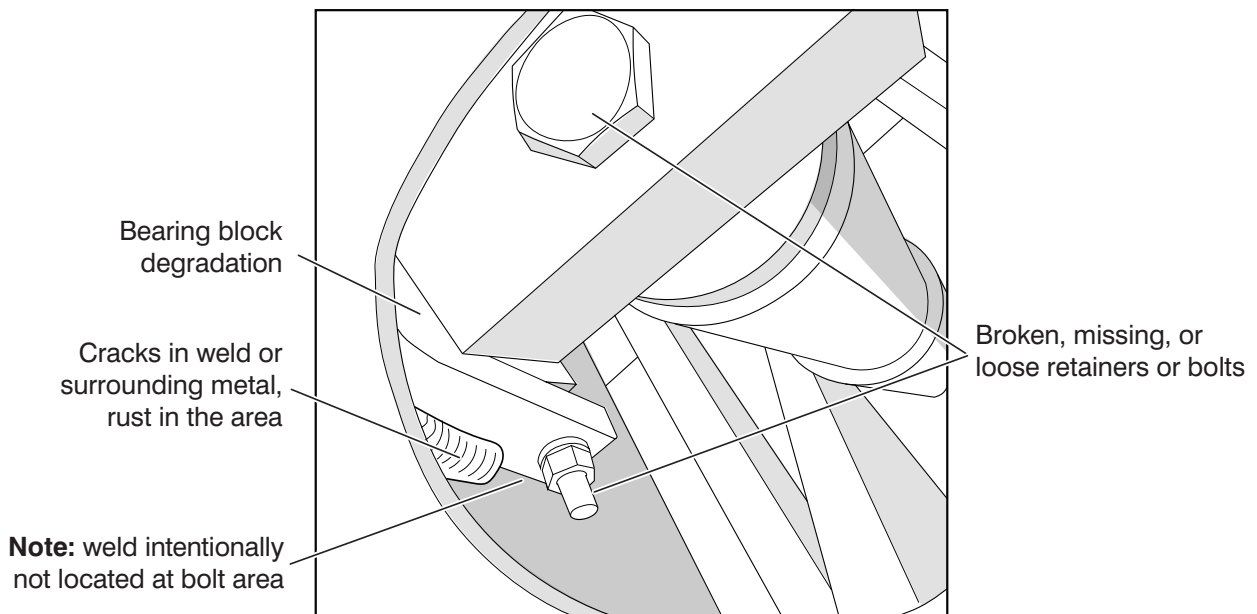
7 Cylinder mount inspection (B)

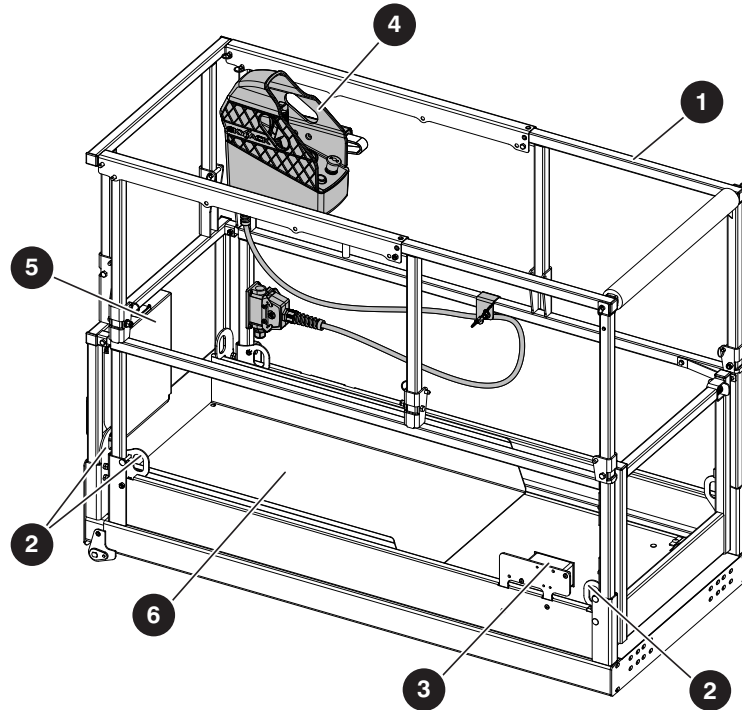
This inspection must be done as part of the scissor assembly inspection.

1. Do a structural inspection of the cylinder mount areas. Look for signs of damage to the mounts.

1. These signs can include:

- Broken, loose or missing retainers or bolts
- Bearing block degradation
- Cracks in welds or the surrounding metal, or rust forming in the area.





1.6-10 Platform inspection

⚠ WARNING

Fall hazard. Use the three points of contact principle when you use the MEWP to enter or exit the platform. If you do not obey, there is a risk of death or serious injury.

1. Enter the platform and close the gate.

1 Railings and gate (B)

- Make sure there are no loose or missing parts, and there is no visible damage.
- Make sure the lock pins and fasteners are correctly locked.
- Make sure the **platform railings** are in the correct position and locked with lock pins.
- Make sure the **gate** is in good condition and operates correctly.
- Refer to [1.2-7 Railing maintenance and repair](#) for the railing maintenance information.

2 Fall-protection anchorages (B)

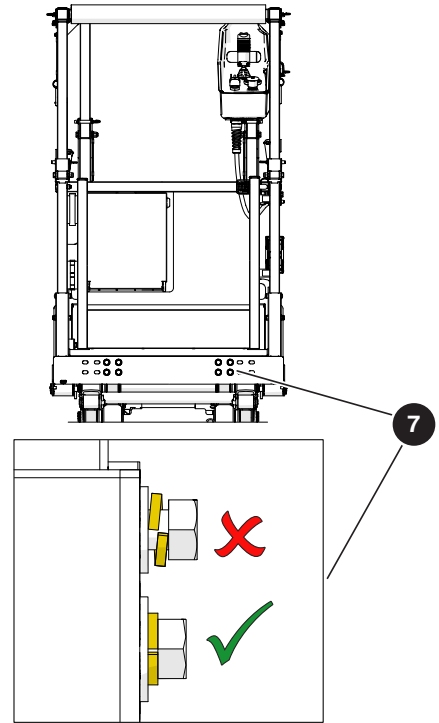
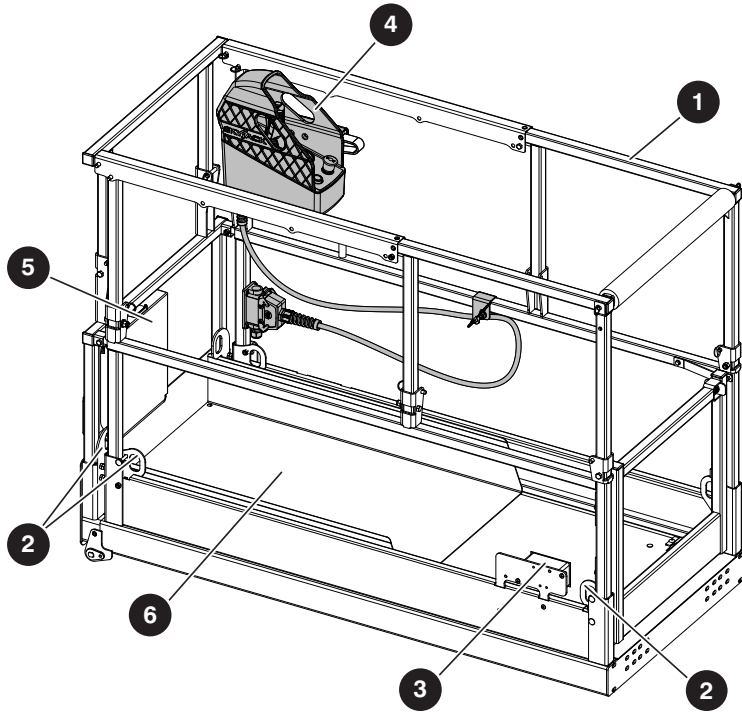
- Make sure the fall-protection anchorages are correctly installed.
- Make sure there is no visible damage.

3 AC power socket (B)

- Make sure the socket is free of dirt or blockages.

4 Platform control console (B)

- Make sure the control console is locked with the lock pin.
- Make sure the platform control cable is correctly locked, and there is no visible damage.
- Make sure all the switches operate correctly.



5 Manual storage box (B)

- Make sure the operation manual and other important documents are in the manual storage box.
- Make sure the documents are in good condition, and you can read them.
- Always put the manuals and other documents back in the storage box after use.

6 Extension platform (B)

- Make sure the extension platform is correctly installed.
- Make sure there is no visible damage or missing components.
- Make sure the lock pins are correctly attached.

2. Use the MEWP ladder to exit the platform.

7 Platform mounting hardware (B)

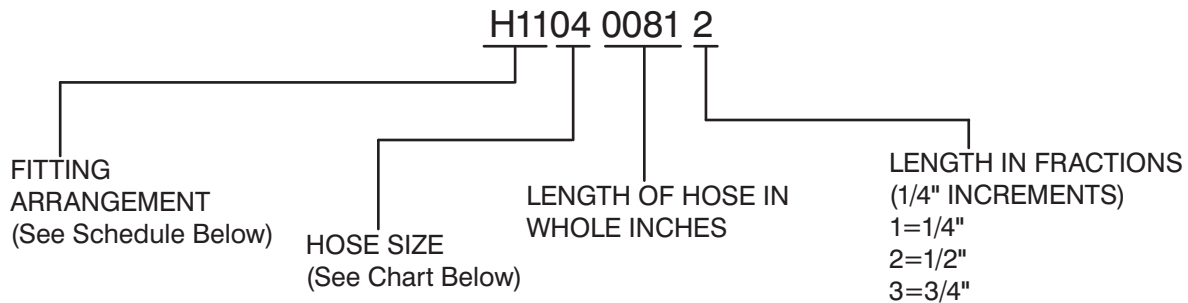
- Make sure the fasteners are correctly installed and there are no missing or loose bolts, flat washers, or spring washers.
- Make sure the spring washers are fully compressed.
- Make sure there is no damage on the platform surface next to the flat washers.
- If any of the above conditions are not met, immediately tag and lock the MEWP and remove it from service for repair.
- Refer to [5.2-3 Platform mounting hardware](#) for the maintenance/installation procedure.

1.7 Function tests

Do the function tests after you complete the inspections. Refer to [1.3-4 Function tests](#).

Section 2 – Maintenance Tables and Diagrams

Table 2.1 Standard hose numbering system



Using the number above as an example, H1104 0081 2, this hose requires a 37° JIC female swivel fitting on one end, and a medium length 90° JIC female swivel fitting for the other end. The hose must meet or exceed the S.A.E. 100R13 hose specification, and be a total of 81-1/2" long.



NOTE

Hose ends and hose must be from same manufacturer per S.A.E. J1273 Nov. '91, Sections 3.10 and 4.2. Hose ends and hose must be of the same size i.e. #4 size fittings must be used with #4 size hose.

Hose Size Chart														
Size	03	04	06	08	10	12	16	20	24	32	40	48	56	64
ID	3/16"	1/4"	3/8"	1/2"	5/8"	3/4"	1"	1-1/4"	1-1/2"	2"	2-1/2"	3"	3-1/2"	4"

Fitting Arrangement Schedule			
Hose Prefix	Hose End Fitting	Hose End Fitting	S.A.E. Hose Specification
H01	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H02	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R13
H03	FEMALE, 37° JIC, SWIVEL	45°, FEMALE, 37° JIC, SWIVEL	100R17
H04	FEMALE, 37° JIC, SWIVEL	45°, FEMALE, 37° JIC, SWIVEL	100R13
H05	FEMALE, 37° JIC, SWIVEL	LONG 90°, FEMALE, 37° JIC, SWIVEL	100R17
H06	FEMALE, 37° JIC, SWIVEL	SHORT 90°, FEMALE, 37° JIC, SWIVEL	100R17
H07	LONG 90°, FEMALE, 37° JIC, SWIVEL	LONG 90°, FEMALE, 37° JIC, SWIVEL	100R17
H08	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R4
H09	FEMALE, 37° JIC, SWIVEL	45°, FEMALE, 37° JIC, SWIVEL	100R4
H10	FEMALE, 37° JIC, SWIVEL	MALE PIPE THREAD FITTING	100R17
H11	FEMALE, 37° JIC, SWIVEL	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	100R13
H12	SHORT 90°, FEMALE, 37° JIC, SWIVEL	SHORT 90°, FEMALE, 37° JIC, SWIVEL	100R17
H13	FEMALE, 37° JIC, SWIVEL	REUSABLE MALE PIPE THREAD FITTING	300 PSI
H14	REUSABLE MALE PIPE THREAD FITTING	NO FITTING	300 PSI

Hose Prefix	Hose End Fitting	Hose End Fitting	S.A.E. Hose Specification
H15	REUSABLE FEMALE, 37° JIC, SWIVEL	REUSABLE FEMALE, 37° JIC, SWIVEL	300 PSI
H16	NO FITTING	NO FITTING	100R4
H17	NO FITTING	NO FITTING	300 PSI
H18	REUSABLE, FEMALE, 37° JIC, SWIVEL	NO FITTING	300 PSI
H19	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R13
H20	FEMALE, SHORT 37° JIC, SWIVEL	SHORT 90°, FEMALE, 37° JIC, SWIVEL	100R4
H21	FEMALE, SHORT 37° JIC, SWIVEL	SHORT 90°, FEMALE, 37° JIC, SWIVEL	100R2AT
H22	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R2AT
H23	FEMALE, LONG 37° JIC, SWIVEL	LONG 90°, FEMALE, 37° JIC, SWIVEL	100R2AT
H24	FEMALE, SHORT 37° JIC, SWIVEL	SHORT 90°, FEMALE, 37° JIC, SWIVEL	100R13
H25	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R4
H30	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H31	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H32	SHORT 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H33	MEDIUM 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H34	SHORT 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H35	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H36	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H37	SHORT 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R4
H38	SHORT 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R4
H39	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R4
H40	SHORT 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H43	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H51	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H52	SHORT 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H53	MEDIUM 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H54	SHORT 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H55	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H56	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H57	SHORT 45°, FEMALE, SAE ORFS, SWIVEL	FEMALE, SAE ORFS, SWIVEL	100R13
H58	FEMALE, SAE ORFS, SWIVEL	FEMALE, SAE ORFS, SWIVEL	100R13
H59	MEDIUM 90°, FEMALE, SAE ORFS, SWIVEL	FEMALE, SAE ORFS, SWIVEL	100R13
H60	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R17
H61	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H62	SHORT 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H63	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H64	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R16
H65	MEDIUM 67°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R12
H66	FEMALE, 37° JIC, SWIVEL	NO FITTING	100R4
H67	FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R19
H68	SHORT 45°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R19
H69	MEDIUM 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R19
H70	LONG 90°, FEMALE, 37° JIC, SWIVEL	FEMALE, 37° JIC, SWIVEL	100R19
H71	LONG 90°, FEMALE, SAE ORFS, SWIVEL	FEMALE, SAE ORFS, SWIVEL	100R15

Table 2.2 Torque Specifications for Fasteners (Metric)

When specific torque values are not provided within this manual for a task, use the torque values given in the table below.

Size	Torque Type	8.8		10.9	
		Dry	Lubed	Dry	Lubed
M5 x 0.80	(in-lb)	(54)	(41)	(78)	(59)
	Nm	6.1	4.6	8.8	6.7
M6 x 1.00	(in-lb)	(92)	(69)	(133)	(99)
	Nm	10.4	7.8	15	11.2
M7 x 1.00	(in-lb)	(156)	(116)	(222)	(167)
	Nm	17.6	13.1	25.1	18.9
M8 x 1.25	(in-lb)	(225)	(169)	(333)	(242)
	Nm	25.4	19.1	37.6	27.3
M10 x 1.50	ft-lb	37	28	53	40
	Nm	50	38	72	54
M12 x 1.75	ft-lb	65	49	93	69
	Nm	88	66	126	94
M14 x 2.00	ft-lb	104	78	148	111
	Nm	141	106	201	150
M16 x 2.00	ft-lb	161	121	230	172
	Nm	218	164	312	233
M18 x 2.50	ft-lb	222	167	318	238
	Nm	301	226	431	323
M20 x 2.50	ft-lb	314	235	449	337
	Nm	426	319	609	457
M22 x 2.50	ft-lb	428	321	613	460
	Nm	580	435	831	624
M24 x 3.00	ft-lb	543	407	776	582
	Nm	736	552	1052	789
M27 x 3.00	ft-lb	796	597	1139	854
	Nm	1079	809	1544	1158
M30 x 3.50	ft-lb	1079	809	1543	1158
	Nm	1463	1097	2092	1570
M33 x 3.50	ft-lb	1468	1101	2101	1576
	Nm	1990	1493	2849	2137
M36 x 4.00	ft-lb	1886	1415	2699	2024
	Nm	2557	1918	3659	2744

NOTE: Lubed includes lubricants such as lubrizing, oil, grease, and some uncured thread lockers. Refer to the specific thread locker manufacturer's instructions for specific torque adjustments.

1375AC

Table 2.3 Torque Specifications for Fasteners (US)

When specific torque values are not provided within this manual for a task, use the torque values given in the table below.

Size	Torque Type	SAE 2		SAE 5		SAE 8	
		Dry	Lubed	Dry	Lubed	Dry	Lubed
4-40	(in-lb)	(5)	(4)	(8)	(6)	(12)	(9)
	Nm	0.6	0.5	0.9	0.7	1.4	1.0
4-48	(in-lb)	(6)	(5)	(9)	(7)	(13)	(10)
	Nm	0.7	0.6	1.0	0.8	1.5	1.1
6-32	(in-lb)	(10)	(8)	(16)	(12)	(23)	(17)
	Nm	1.1	0.9	1.8	1.4	2.6	1.9
6-40	(in-lb)	(12)	(9)	(18)	(13)	(25)	(19)
	Nm	1.4	1.0	2.0	1.5	2.8	2.1
8-32	(in-lb)	(19)	(14)	(30)	(22)	(41)	(31)
	Nm	2.1	1.6	3.4	2.5	4.6	3.5
8-36	(in-lb)	(20)	(15)	(31)	(23)	(43)	(32)
	Nm	2.3	1.7	3.5	2.6	4.9	3.6
10-24	(in-lb)	(27)	(21)	(43)	(32)	(60)	(45)
	Nm	3.1	2.4	4.9	3.6	6.8	5.1
10-32	(in-lb)	(31)	(23)	(49)	(36)	(68)	(51)
	Nm	3.5	2.6	5.5	4.1	7.7	5.8
1/4-20	(in-lb) ft-lb	(66)	(50)	8	(75)	12	9
	Nm	7.5	5.6	11	8.5	16	12
1/4-28	(in-lb) ft-lb	(76)	(56)	10	(86)	14	10
	Nm	8.6	6.3	14	9.7	19	14
5/16-18	ft-lb	11	8	17	13	25	18
	Nm	15	11	23	18	34	24
5/16-24	ft-lb	12	9	19	14	25	20
	Nm	16	12	26	19	34	27
3/8-16	ft-lb	20	15	30	23	45	35
	Nm	27	20	41	31	61	47
3/8-24	ft-lb	23	17	35	25	50	35
	Nm	31	23	47	34	68	47
7/16-14	ft-lb	32	24	50	35	70	55
	Nm	43	33	68	47	95	75
7/16-20	ft-lb	36	27	55	40	80	60
	Nm	49	37	75	54	108	81
1/2-13	ft-lb	50	35	75	55	110	80
	Nm	68	47	102	75	149	108
1/2-20	ft-lb	55	40	90	65	120	90
	Nm	75	54	122	88	163	122

Size	Torque Type	SAE 2		SAE 5		SAE 8	
		Dry	Lubed	Dry	Lubed	Dry	Lubed
9/16-12	ft-lb	70	55	110	80	150	110
	Nm	95	75	149	108	203	149
9/16-18	ft-lb	80	60	120	90	170	130
	Nm	108	81	163	122	230	176
5/8-11	ft-lb	100	75	150	110	220	170
	Nm	136	102	203	149	298	230
5/8-18	ft-lb	110	85	180	130	240	180
	Nm	149	115	244	176	325	244
3/4-10	ft-lb	175	130	260	200	380	280
	Nm	237	176	353	271	515	380
3/4-16	ft-lb	200	150	300	220	420	320
	Nm	271	203	407	298	569	434
7/8-9	ft-lb	170	125	430	320	600	460
	Nm	230	169	583	434	813	624
7/8-14	ft-lb	180	140	470	360	660	500
	Nm	244	190	637	488	895	678
1-8	ft-lb	250	190	640	480	900	680
	Nm	339	258	868	651	1220	922
1-12	ft-lb	270	210	710	530	1000	740
	Nm	366	285	963	719	1356	1003
1-14	ft-lb	280	210	730	540	1020	760
	Nm	380	285	990	732	1383	1030
1 1/8-7	ft-lb	350	270	800	600	1280	960
	Nm	475	366	1085	813	1735	1302
1 1/8-12	ft-lb	400	300	880	660	1440	1080
	Nm	542	407	1193	895	1952	1464
1 1/4-7	ft-lb	500	380	1120	840	1820	1360
	Nm	678	515	1519	1139	2468	1844
1 1/4-12	ft-lb	550	420	1240	920	2000	1500
	Nm	746	569	1681	1247	2712	2034
1 3/8-6	ft-lb	670	490	1460	1100	2380	1780
	Nm	908	664	1979	1491	3227	2413
1 3/8-12	ft-lb	750	560	1680	1260	2720	2040
	Nm	1017	759	2278	1708	3688	2766
1 1/2-6	ft-lb	870	650	1940	1460	3160	2360
	Nm	1180	881	2630	1979	4284	3200
1 1/2-12	ft-lb	980	730	2200	1640	3560	2660
	Nm	1329	990	2983	2224	4827	3606

NOTE: Lubed includes lubricants such as lubrizing, oil, grease, and some uncured thread lockers. Refer to the specific thread locker manufacturer's instructions for specific torque adjustments.

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Table 2.4 Torque specifications for hydraulic couplings & hoses

Hydraulic Coupling Torque Chart O-Ring Port Connectors				
SAE Size	Steel Ports		Non-ferrous Ports	
	ft-lb	Nm	ft-lb	Nm
4	14-16	20-22	9-10	12-13
6	24-26	33-35	15-16	20-21
8	50-60	68-78	30-36	41-47
10	72-80	98-110	43-48	60-66
12	125-135	170-183	75-81	102-110
16	200-220	270-300	120-132	162-180
20	210-280	285-380	126-168	171-228
24	270-360	370-490	162-216	222-294
32	-	-	-	-

Hose End Torque Chart for JIC									
Size		Steel				Brass			
Dash	Frac.	ft-lb		Nm		ft-lb		Nm	
		Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.
-4	1/4"	10	11	13	15	5	6	6.75	9
-6	3/8"	17	19	23	26	12	15	17	20
-8	1/2"	34	38	47	52	20	24	27.66	33
-10	5/8"	50	56	69	76	34	40	46.33	55
-12	3/4"	70	78	96	106	53	60	72.33	82
-16	1"	94	104	127	141	74	82	100.5	111
-20	1 1/4"	124	138	169	188	75	83	101.5	113
-24	1 1/2"	156	173	212	235	79	87	107	118
-32	2"	219	243	296	329	158	175	214	237

Hose End Torque Chart for Flat-Face O-Ring Seal (Steel)					
Size		Torque Specification			
Dash	Frac.	ft-lb		Nm	
		Min.	Max.	Min.	Max.
-4	1/4"	10	12	14	16
-6	3/8"	18	20	24	27
-8	1/2"	32	40	43	54
-10	5/8"	46	56	60	75
-12	3/4"	65	80	90	110
-14	1"	65	80	90	110
-16	1 1/4"	92	105	125	240
-20	1 1/2"	125	140	170	190
-24	2"	150	180	200	245

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Table 2.5 Torque specifications for cartridges and coils

Valve Size	Cartridges						Coils
	8	38	58	10	12	16	All coil sizes
Torque (ft-lb) max	20	20	20	25	35	50	4 to 5
Torque (in-lb) max	240	240	240	300	420	600	48 to 60
Torque (Nm) max	27	27	27	34	47	68	5 to 6.5

Additional torque specifications may be found in Section 5.

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Table 2.6 MEWP torque specifications

Base	Torque (lb-ft)						Torque (Nm)	
Directional Valve Mounting Bolts	2.3-2.7 lb-ft (28-32 lb-in)						3.2 -3 .6 Nm	
Front Wheel Castle Nut	150 lb-ft*						203 Nm*	
Hydraulic Motor Mounting Bolts	85 lb-ft						115 Nm	
Rear Wheel Castle Nut - Pin Brakes	Finger tighten until snug*							
Rear Wheel Castle Nut - Wet Brakes	150 lb-ft*						203 Nm*	
Wheel Brake Mounting Bolts	85 lb-ft						115 Nm	
Platform	Torque (lb-ft)						Torque (Nm)	
Platform mounting bolts	23 ft-lb						31 Nm	
*See section 5 for the full torque procedure.								
Cartridge							Coils	
Valve Size	8	38	58	10	12	16	All coil sizes	
Torque (lb-ft) max	20	20	20	25	35	50	4 to 5	
Torque (lb-in) max	240	240	240	300	420	600	48 to 60	
Torque (Nm) max	27.12	27.12	27.12	33.9	47.46	67.8	5.42 to 6.78	
SAE Plugs								
Port Size	2	4	5	6	8	10	12	16
Torque (lb-ft) max	3	10	15	15	25	25	30	35

Newton-meter = Nm Pound-foot = lb-ft Pound-inch = lb-in 2008AC
 Additional Torque Specifications may be found in Section 5.

Table 2.7 Floor loading pressure

Model		Weights				Pressures			
		MEWP weight		Max weight per wheel		LCP**		OFL**	
		kg	lb	kg	lb	kPa	psi	kPa	psf
SJ3215 ANSI/CSA	min*	1148	2531	290	640	670	97	7.9	164
	max*	1420	3131	567	1250	1093	159	9.7	203
SJ3219 ANSI/CSA	min*	1476	3255	370	815	797	116	10.1	210.9
	max*	1703	3755	608	1340	1159	168	11.7	244.4
SJ3215 CE	min*	1148	-	290	-	670	-	7.9	-
	max*	1420	-	567	-	1093	-	9.7	-
SJ3219 CE	min*	1476	-	370	-	797	-	10.1	-
	max*	1703	-	608	-	1159	-	11.7	-
SJ3215 AS	min*	1148	-	290	-	670	-	7.9	-
	max*	1420	-	567	-	1093	-	9.7	-
SJ3219 AS	min*	1476	-	370	-	797	-	10.1	-
	max*	1703	-	608	-	1159	-	11.7	-
SJ3215 KC	min*	1148	-	290	-	670	-	7.9	-
	max*	1420	-	567	-	1093	-	9.7	-
SJ3219 KC	min*	1476	-	370	-	797	-	10.1	-
	max*	1703	-	608	-	1159	-	11.7	-

* **Min:** Minimum MEWP weight (Unloaded platform, no options/attachments) 2007AB
Max: Maximum MEWP weight (Platform loaded to capacity with options/attachments)

Wheel is the weight that can be experienced on one wheel.

Note: This is more than 25% of the machine weight due to possible weight distribution over the machine and platform.

** **LCP:** Local Concentrated Pressure is a measure of how hard the MEWP presses on the area in direct contact with the floor/tire.

OFL: Overall Floor Load (Pressure) is a measure of the average load the MEWP imparts on the whole surface directly underneath the chassis. This has been calculated by dividing the MEWP weight by the overall floor area occupied by the MEWP (on wheels).

Note: The floor covering (e.g., tile, carpet, etc.) or the structure (e.g., beams) of the operating surface must be able to withstand more than the values indicated above.

Note: The LCP or OFL that an individual surface can withstand varies from structure to structure and is generally determined by the engineer or architect for that particular structure.

Table 2.8 Specifications & features - SJ3215

	SJ3215		ANSI/CSA		CE	AS	KC
Weight & Dimensions	Weight*		2531 lb	1148 kg	1148 kg	1148 kg	1148 kg
	Overall width		32.28 in	0.82 m	0.82 m	0.82 m	0.82 m
	Overall length (Platform Retracted)		70.87 in	1.80 m	1.80 m	1.80 m	1.80 m
	Overall Length (Platform Extended)		N/A	N/A	2.64 m	2.64 m	2.64 m
	Platform Size Inside (Platform Retracted)		25.59 in x 60.63 in	0.65 m x 1.54 m	0.65 m x 1.54 m	0.65 m x 1.54 m	0.65 m x 1.54 m
	Platform Size Inside (Platform Extended)		25.59 in x 94.09 in	0.65 m x 2.39 m	0.65 m x 2.39 m	0.65 m x 2.39 m	0.65 m x 2.39 m
Height	Working Height		21 ft 2 in	6.27 m	6.44 m	N/A	6.44 m
	Platform Elevated Height		14 ft 4 in	4.44 m	4.44 m	4.44 m	4.44 m
	Stowed Height (Railings Down)		65.75 in	1.67 m	1.67 m	N/A	N/A
	Stowed Height (Railings Up)		79.92 in	2.03 m	2.03 m	1.88 m	1.92 m
	Elevated Drive Speed Trip Height		84 in	2.13 m	2.13 m	2.13 m	2.13 m
	Pothole Drive Cutout Height		86.5 in	2.20 m	2.20 m	2.20 m	2.20 m
	Drive Height		Full	Full	Full	Full	Full
Speed & Gradeability	Lift Time (No Load)		15 s		16 s	15 s	15 s
	Lift Time (Rated Load)		17 s		17 s	17 s	17 s
	Lower Time (No Load)		22 s		25 s	22 s	22 s
	Lower Time (Rated Load)		16 s		18 s	16 s	16 s
	Normal Drive Speed		2.1 mph	3.38 km/h	3.38 km/h	3.38 km/h	3.38 km/h
	Elevated Drive Speed (max)		0.7 mph	1.13 km/h	1.13 km/h	1.13 km/h	1.13 km/h
	Gradeability (Ramp Angle)		25%				
Tilt	Tilt Switch Setting - Front to Rear		3.5°				
	Tilt Switch Setting - Side to Side		1.5°				
Attributes	Hydraulic Oil Type		ATF Dexron III, Shell Naturelle HF-E 32				
	Hydraulic Tank Capacity	S/N A100 026 027 & above	2.1 gal	8 L			
		S/N A100 026 026 & below	2.6 gal	10 L			
	System Pressure**		3250 psi	224 bar			
	Lift Pressure**		2100-2200 psi	145-152 bar			
	Battery Pack Voltage		24 V				
	Tires (Solid Rubber)		12 x 4 x 8				
Sound pressure level at platform (max)		70 db(A)					

* Weight with standard 0.9 m extension platform. Refer to serial nameplate for specific applications.

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**Refer to Section 5 for the adjustment procedure.

Table 2.9 Specifications & features - SJ3219

	SJ3219	ANSI/CSA		CE	AS	KC
Weight & Dimensions	Weight*	3255 lb	1476 kg	1476 kg	1476 kg	1476 kg
	Overall width	32.28 in	0.82 m	0.82 m	0.82 m	0.82 m
	Overall length (Platform Retracted)	70.87 in	1.80 m	1.80 m	1.80 m	1.80 m
	Overall Length (Platform Extended)	104.33 in	2.65 m	2.64 m	2.64 m	2.64 m
	Platform Size Inside (Platform Retracted)	25.59 in x 60.63 in	0.65 m x 1.54 m	0.65 m x 1.54 m	0.65 m x 1.54 m	0.65 m x 1.54 m
	Platform Size Inside (Platform Extended)	25.59 in x 94.09 in	0.65 m x 2.39 m	0.65 m x 2.39 m	0.65 m x 2.39 m	0.65 m x 2.39 m
Height	Working Height	24 ft 6 in	7.48 m	7.61 m	N/A	7.65 m
	Platform Elevated Height	18 ft 6 in	5.65 m	5.61 m	5.65 m	5.65 m
	Stowed Height (Railings Down)	79.70 in	2.02 m	1.79 m	N/A	N/A
	Stowed Height (Railings Up)	84.25 in	2.14 m	2.14 m	1.99 m	2.03 m
	Elevated Drive Speed Trip Height	84 in	2.13 m	2.13 m	2.13 m	2.13 m
	Pothole Drive Cutout Height	108.5 in	2.76 m	2.76 m	2.76 m	2.76 m
	Drive Height	Full	Full	Full	Full	Full
Speed & Gradeability	Lift Time (No Load)	15 s		16 s	15 s	15 s
	Lift Time (Rated Load)	17 s		17 s	17 s	17 s
	Lower Time (No Load)	32 s		33 s	32 s	32 s
	Lower Time (Rated Load)	24 s		25 s	24 s	24 s
	Normal Drive Speed	2.1 mph	3.38 km/h	3.38 km/h	3.03 km/h	3.38 km/h
	Elevated Drive Speed (max)	0.7 mph	1.13 km/h	1.13 km/h	1.13 km/h	1.13 km/h
	Gradeability (Ramp Angle)	25%				
Tilt	Tilt Switch Setting - Front to Rear	3.5°				
	Tilt Switch Setting - Side to Side	1.5°				
Attributes	Hydraulic Oil Type	ATF Dexron III, Shell Naturelle HF-E 32				
	Hydraulic Tank Capacity	S/N A100 026 027 & above	2.1 gal	8 L		
		S/N A100 026 026 & below	2.6 gal	10 L		
	System Pressure**	3250 psi	224 bar			
	Lift Pressure**	2100-2200 psi	145-152 bar			
	Battery Pack Voltage	24 V				
	Tires (Solid Rubber)	12 x 4 x 8				
Sound pressure level at platform (max)	70 db(A)					

* Weight with standard 0.9 m extension platform. Refer to serial nameplate for specific applications.

**Refer to Section 5 for the adjustment procedure.

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Table 2.10 Maximum platform capacities (evenly distributed)

Model	Wind Rating	Total Platform Capacity		Extension Platform Capacity		Manual Force	Tilt Cutout Setting
SJ3215 ANSI/CSA	0 m/s [0 mph]	272 kg [600 lb]	2 Persons	113 kg [250 lb]	1 Person	400 N [90 lbf]	1.5° × 3.5°
	12.5 m/s [28 mph]		1 Person			200 N [45 lbf]	
SJ3219 ANSI/CSA	0 m/s [0 mph]	227 kg [500 lb]	2 Persons	113 kg [250 lb]	1 Person	400 N [90 lbf]	1.5° × 3.5°
	12.5 m/s [28 mph]		1 Person			200 N [45 lbf]	
SJ3215 CE	0 m/s	272 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	
SJ3219 CE	0 m/s	227 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	
SJ3215 AS	0 m/s	272 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	
SJ3219 AS	0 m/s	227 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	
SJ3215 KC	0 m/s	272 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	
SJ3219 KC	0 m/s	227 kg	2 Persons	113 kg	1 Person	400 N	1.5° × 3.5°
	12.5 m/s		1 Person			200 N	

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Section 3 – System Component Identification and Schematics

Table 3.1 Electrical symbol chart






























































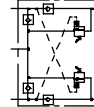













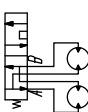


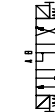


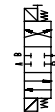



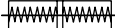
 CIRCUITS CROSSING NO CONNECTION	 HOURMETER	 KEY SWITCH	 LIMIT SWITCH N.O.
 CIRCUITS CONNECTED	 LIGHT	 FOOT SWITCH	 LIMIT SWITCH N.O. HELD CLOSED
 BATTERY	 HYDRAULIC VALVE COIL	 TOGGLE SWITCH	 LIMIT SWITCH N.C.
 GROUND	 PROPORTIONAL HYDRAULIC VALVE COIL	 PUSH BUTTON	 LIMIT SWITCH N.C. HELD OPEN
 FUSE	 ELECTRIC MOTOR	 ROTARY SWITCH	 SILICON CONTROLLED RECTIFIER
 CIRCUIT BREAKER	 HORN	 LIMIT SWITCH	 PROXIMITY SWITCH
 VOLT METER	 EMERGENCY STOP BUTTON	 CAM OPERATED LIMIT SWITCH	 PNP TRANSISTOR
 CAPACITOR	 RESISTOR	 TILT SWITCH	 NPN TRANSISTOR
 POTENTIOMETER	 LEVEL SENSOR	 SINGLE POLE SINGLE THROW RELAY	 PRESSURE/ VACUUM SWITCH
 SINGLE POLE DOUBLE THROW RELAY	 DOUBLE POLE SINGLE THROW RELAY	 DOUBLE POLE DOUBLE THROW RELAY	 TEMPERATURE SWITCH
 TRIPLE POLE DOUBLE THROW RELAY	 DIODE	 RHEOSTAT	

Table 3.2 Hydraulic symbol chart

 LINE CROSSING	 VARIABLE DISPLACEMENT PUMP	 SHUTTLE VALVE	 VELOCITY FUSE
 LINE JOINED	 HAND PUMP	 ACCUMULATOR, GAS CHARGED	 SINGLE ACTING CYLINDER
 HYDRAULIC TANK	 RELIEF VALVE	 CUSHION CYLINDER	 DOUBLE ACTING CYLINDER
 HYDRAULIC FILTER WITH BYPASS	 PRESSURE REDUCING VALVE	 PRESSURE SWITCH	 DOUBLE ACTING DOUBLE RODDED CYLINDER
 ELECTRIC MOTOR	 FIXED ORIFICE	 MOTION CONTROL VALVE	 SPRING APPLIED HYDRAULIC RELEASED BRAKE
 ENGINE	 ADJUSTABLE FLOW CONTROL	 FLOW DIVIDER COMBINER	 BRAKE CYLINDER
 FIXED DISPLACEMENT PUMP	 CHECK VALVE	 COUNTER BALANCE VALVE	 ROTARY ACTUATOR
 VARIABLE DISPLACEMENT HYDRAULIC MOTOR	 OIL COOLER	 VALVE COIL	 BI DIRECTIONAL HYDRAULIC MOTOR
 SERIES PARALLEL HYDRAULIC MOTOR	 TWO POSITION TWO WAY NORMALLY CLOSED VALVE	 TWO POSITION THREE WAY VALVE	 THREE POSITION FOUR WAY CLOSED CENTER OPEN PORT
 TWO POSITION TWO WAY NORMALLY OPEN VALVE	 TWO POSITION THREE WAY VALVE	 THREE POSITION FOUR WAY CLOSED CENTER CLOSED PORT	
 PRESSURE TRANSDUCER	 MAIN LINES Solid	 PILOT LINES Dashed	
 SERVO			

3.3 Wire number and colour code

WIRE NO.	WIRE COLOR	WIRE NO.	WIRE COLOR	WIRE NO.	WIRE COLOR	WIRE NO.	WIRE COLOR	WIRE NO.	WIRE COLOR
00	WHT	21	GRN/BLK	42	PNK/BLU	84	YEL/BRN	1002	RED/BLK
000	WHT	21	WHT/RED	43	PNK/RED	85	ORG/BLK/WHT	1003	ORG
B1	BLU/PINK	22	ORG/BLU	44	PNK/ORG	87	BRN/ORG	1006	BLU
01	PUR/BLK	23	BLK/WHT/RED	49	GRN	88	BRN/PNK	1008	GRY
02	WHT	23	BLK/WHT	50	BRN/WHT	89	BRN/GRN	1100	BLK
03	GRN/PUR	24	BLU/BLK	55	GRY/RED	99	PUR/RED	1103	ORG
04	RED/YEL	25	ORG/GRN	56	WHT/ORG	100	RED	2001	BRN
05	PUR/BLACK	26	GRN	57	BLK/WHT	101		2002	RED
06		27	BLK	59	ORG/BLK	102	PNK	2005	GRN/WHT
07	RED	28	GRN/RED	60	BLK/RED/GRN	103	RED	3008	GRY
08	PUR/WHT	29	BLU/YEL	71	BLU/RED	103B	BLK	4002	RED
09	ORG/RED	30	BRN	72	WHT/BLK/RED	103C	WHT	7002	RED
10	BLU/WHT	31	RED/WHT	73	WHT/RED/GRN	104	RED		
11	YEL/BLK	32	GRN/BLK	74	BLK/RED/GRN	105	GRN		
12	BRN/RED	33		75	WHT/RED/GRN	106	BLU		
13	ORG	34	GRN/WHITE	76	RED/GRN	200	BLK/WHT		
14	BLK	35	RED/BRN	77	GRN/BLK/WHT	203	ORG/BLK		
15	BLU	36	YEL	78	RED/BLK/WHT	205	GRN		
16	WHT/BLK	37	GRN/WHT	79	YEL/PNK	209	WHT/BLK		
17	BLU/RED	38		80	YEL/PUR	900	WHT		
18	RED/BLK	39	GRN/WHT	81	YEL/RED	902	WHT		
19	ORG/BLK	40	PNK/YEL	82	YEL/BLU	910	BLK		
20	BLK/WHT/RED	41	PNK	83	YEL/ORG	1001	BRN/WHT		

This table is to be used as a wire number/color reference for electrical drawings and schematics.

All wire numbers will retain their original color coding, for example if wire 7 is red, wire 7A, 7B, and 7C will also be red.

3.4 Hydraulic parts list

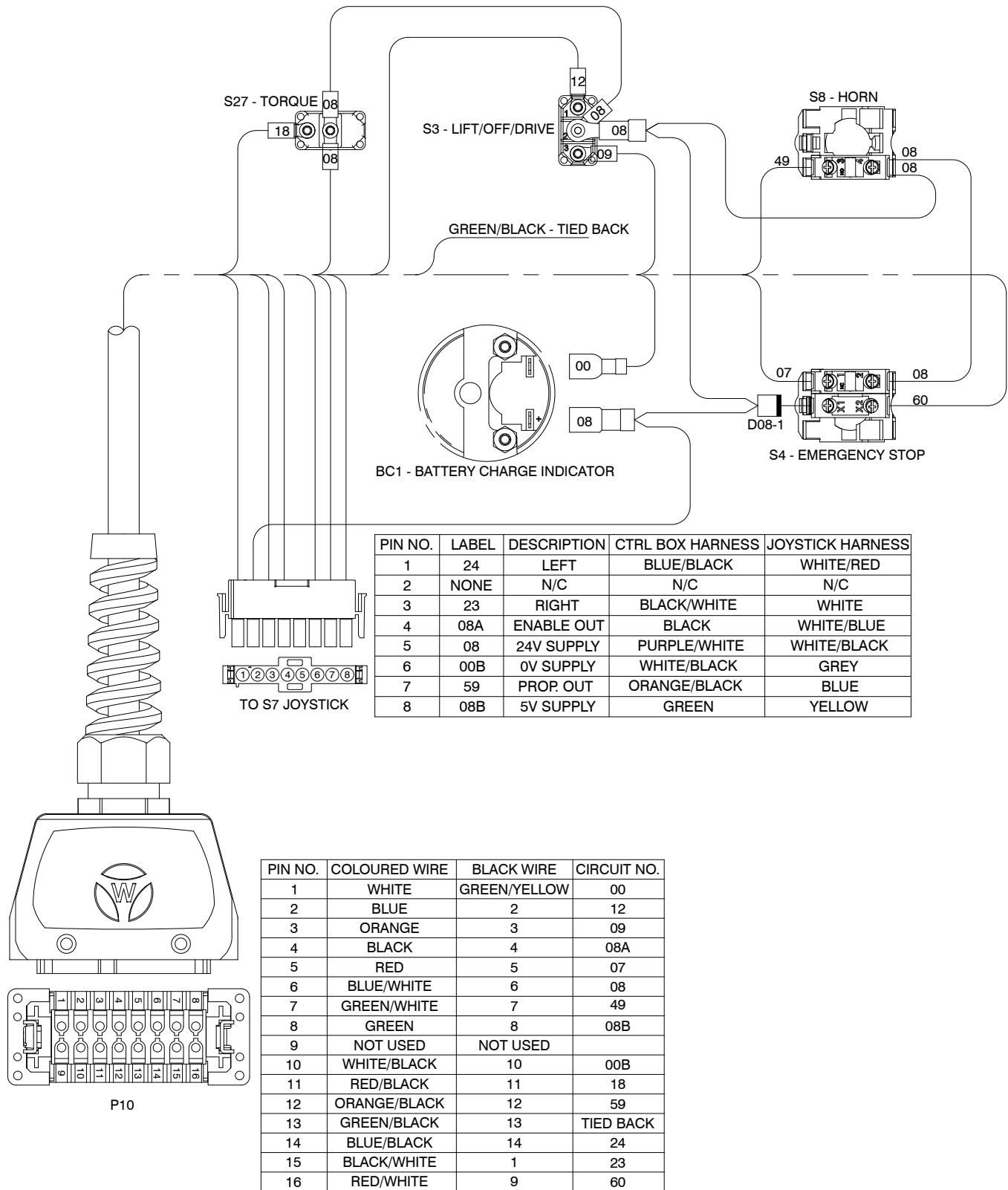
Index No.	Skyjack Part No.	Description
2H-13	103655	VALVE, Lower - SJ3219
2H-13C	207870	VALVE, Lower - SJ3215
3H-14	106273	VALVE, Lift
3H-17	103623	VALVE, Brake
4H-15	153334	VALVE, Reverse
4H-16	153334	VALVE, Forward
4H-23A	153334	VALVE, Steer Right
4H-24A	153334	VALVE, Steer Left
BR1	217960	BRAKE, Hydraulic - CE, AS & KC
BR2	217960	BRAKE, Hydraulic - CE, AS & KC
C1	226482	CYLINDER, Lift
C2	151733	CYLINDER, Steering
C3	204005	CYLINDER, Brake - ANSI/CSA
CB1	147888	COUNTERBALANCE, Motors
F1	109568	FILTER, Return
M1	161094	MOTOR, Left - ANSI/CSA, CE & KC
	194615	MOTOR, Left - AS
M2	161094	MOTOR, Right - ANSI/CSA, CE & KC
	194615	MOTOR, Right - AS
MB1	226496	MANIFOLD, Main - SJ3215 ANSI/CSA
	226497	MANIFOLD, Main - SJ3215 CE, AS & KC
	226479	MANIFOLD, Main - SJ3219 ANSI/CSA
	226481	MANIFOLD, Main - SJ3219 CE, AS & KC
MB2	138021	MANIFOLD, Free-Wheel
MB3	212912	MANIFOLD, Holding
MB4	209218	MANIFOLD, Brake Release - CE, AS & KC
01	310056	ORIFICE, Steer - 0.040" - SJ3215
02	310056	ORIFICE, Steer - 0.040" - SJ3215
03	226498	ORIFICE, 0.094" - SJ3215
	226477	ORIFICE, 0.059" - SJ3219
04	147656	ORIFICE, 0.024"
05	130407	ORIFICE, 0.051" - ANSI/CSA
P1	161936	PUMP, DC Motor
	165610	PUMP, DC Motor - ANSI/CSA EE-Rated
P2	146559	PUMP, DC Motor - CE, AS & KC
QD1	122420	QUICK DISCONNECT
R1	104534	RELIEF, System
R2	104534	RELIEF, Lift
SN1	210292	SNUBBER, 5um
V1	103136	VALVE, Free-Wheel
V2	146561	VALVE, Brake Override - CE, AS & KC

3.5 Electrical parts list

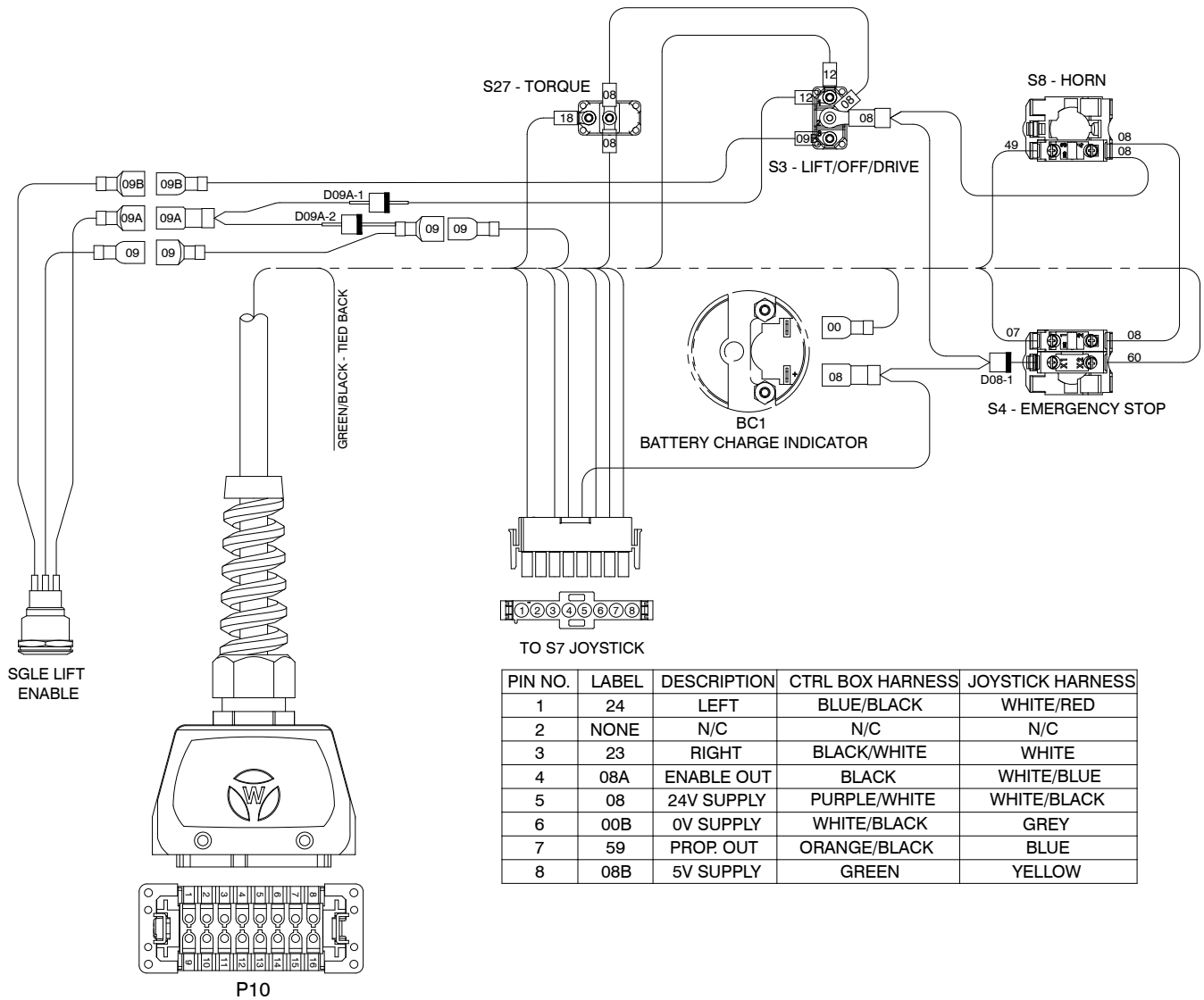
Index No.	Skyjack Part No.	Description
2H-13	104410	COIL, 12 Volt - Holding Valve
3H-14	105610	COIL, 24 Volt - Lift
4H-15	153334	COIL, 24 Volt - Reverse
4H-16	153334	COIL, 24 Volt - Forward
3H-17	103605	COIL, 24 Volt - Brake
4H-23A	153334	COIL, 24 Volt - Right Steer
4H-24A	153334	COIL, 24 Volt - Left Steer
AT1	220597	TRANSDUCER, Angle
B1-4	103480	BATTERY, 6V - US 2200
	106552	BATTERY, 6V - US 250
	160933	BATTERY, 6V - AGM
BC1	122093	INDICATOR, Battery Charge
BP29	170620	BEEPER, All Motion, Tilt & Overload
C1	146475	CONTACTOR, Motor
CB1	117325	BREAKER, Circuit - 15A
CB2	408526	BREAKER, Circuit - 10A
CM1	243650	CONTROLLER, Skycoded Module
DCM1	169260	MOTOR
DXX	102921	DIODE
F1	310517	FUSE, 300A
F2	146442	FUSE, 100A - Inverter - ANSI/CSA
FL-22	235775	LIGHT, Flashing
H1	146649	Horn
LS1	210226	LIMIT SWITCH, Pothole Protection - Hydraulic Tray Side
LS2	210227	LIMIT SWITCH, Pothole Protection - Battery Tray Side
LS7A	208038	LIMIT SWITCH, Anti-Overriding Posts - 64"
LS7B	208039	LIMIT SWITCH, Anti-Overriding Posts - 108"
LS7C	220080	LIMIT SWITCH, Anti-Overriding Posts - Additional Posts
LS7D	220080	LIMIT SWITCH, Anti-Overriding Posts - Additional Posts
PL-1	147061	LIGHT, Platform - Emergency Stop/Overload
PL-2	147061	LIGHT, Base - Emergency Stop/Overload
PT1	217934	TRANSDUCER, Pressure - 3000 PSI - SJ3219
	217933	TRANSDUCER, Pressure - 2000 PSI - SJ3215
S1	210051	SWITCH, Main Disconnect
S2	147054	SWITCH, Lift/Lower
S3	207741	SWITCH, Lift/Off/Drive
S4	147053	SWITCH, Platform - Emergency Stop
S5	220494	SWITCH, SGLE

Index No.	Skyjack Part No.	Description
S7	211751	JOYSTICK
S7-1	119725	SWITCH, Neutral
S7-2	159613	SWITCH, Right
S7-3	159613	SWITCH, Left
S7-6	159067	SWITCH, Enable
S8	147054	SWITCH, Horn
S10	149536	SWITCH, Key - Idle/Platform/Base - ANSI/CSA, AS & KC
	147057	SWITCH, Key - Idle/Platform/Base - CE
S27	115574	SWITCH, Torque
S28	147053	SWITCH, Base - Emergency Stop
S51	212204	SWITCH, Emergency Lowering

3.6 Platform control box wiring

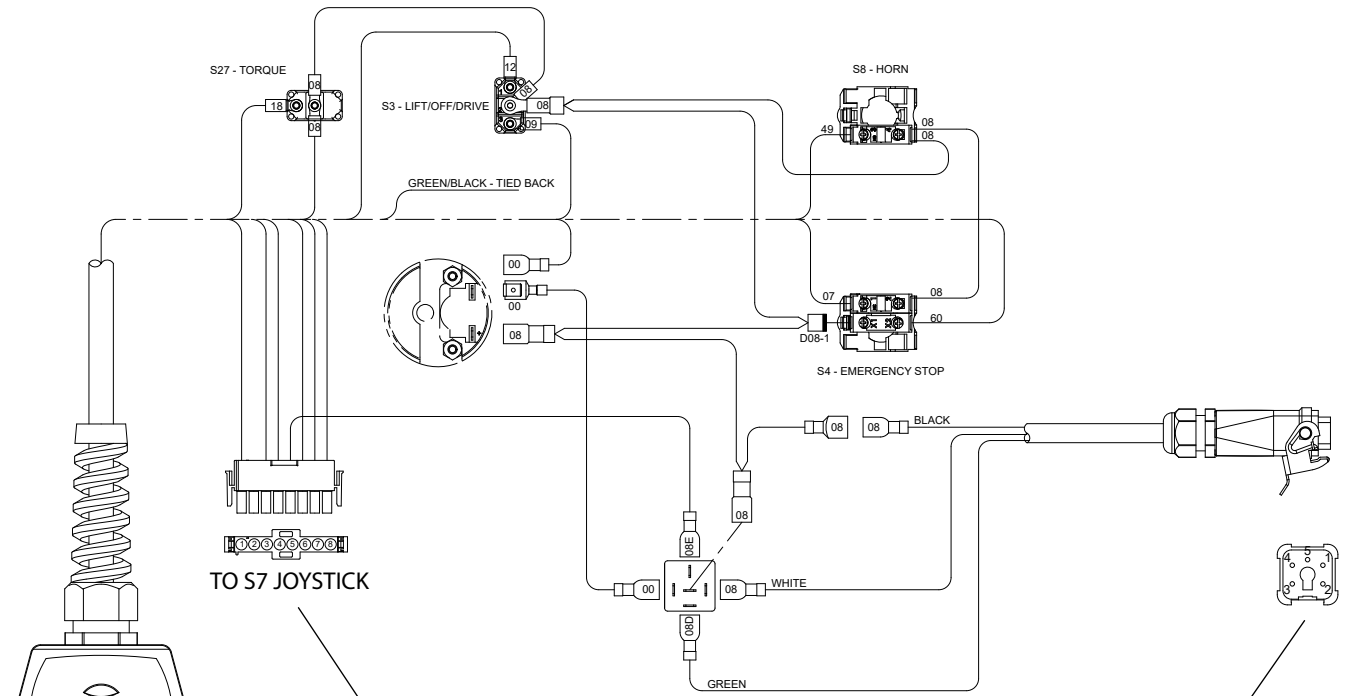


3.7 Platform control box wiring - SGLE



PIN NO.	COLOURED WIRE	BLACK WIRE	CIRCUIT NO.
1	WHITE	GREEN/YELLOW	00
2	BLUE	2	12
3	ORANGE	3	09
4	BLACK	4	08A
5	RED	5	07
6	BLUE/WHITE	6	08
7	GREEN/WHITE	7	49
8	GREEN	8	08B
9	NOT USED	NOT USED	
10	WHITE/BLACK	10	00B
11	RED/BLACK	11	18
12	ORANGE/BLACK	12	59
13	GREEN/BLACK	13	TIED BACK
14	BLUE/BLACK	14	24
15	BLACK/WHITE	1	23
16	RED/WHITE	9	60

3.8 Platform control box wiring - footswitch



PIN NO.	COLOUR	CIRCUIT NO.
1	BLACK	08
2	WHITE	08
3	GREEN	08B

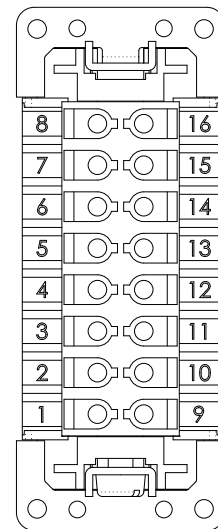
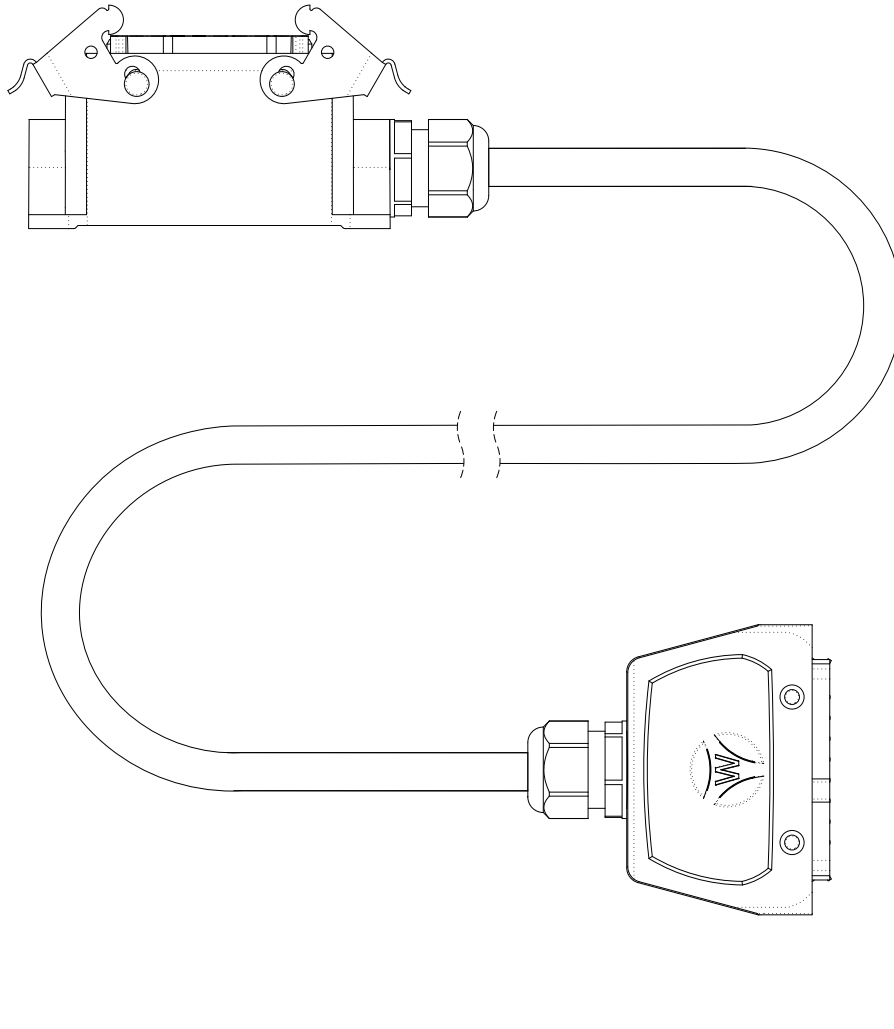
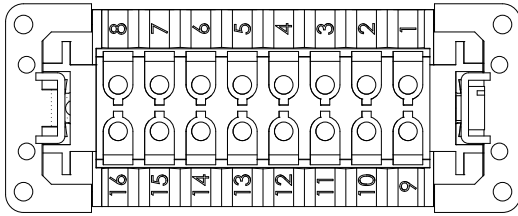
P10

PIN NO.	COLOURED WIRE	BLACK WIRE	CIRCUIT NO.
1	WHITE	GRN/YLW	00
2	BLUE	2	12
3	ORANGE	3	09
4	BLACK	4	08A
5	RED	5	07
6	BLUE/WHITE	6	08
7	GREEN/WHITE	7	49
8	GREEN	8	08B
9	NOT USED	NOT USED	-
10	WHITE/BLACK	10	00B
11	RED/BLACK	11	18
12	ORANGE/BLACK	12	59
13	GREEN/BLACK	13	TIED BACK
14	BLUE/BLACK	14	24
15	BLACK/WHITE	1	23
16	RED/WHITE	9	60

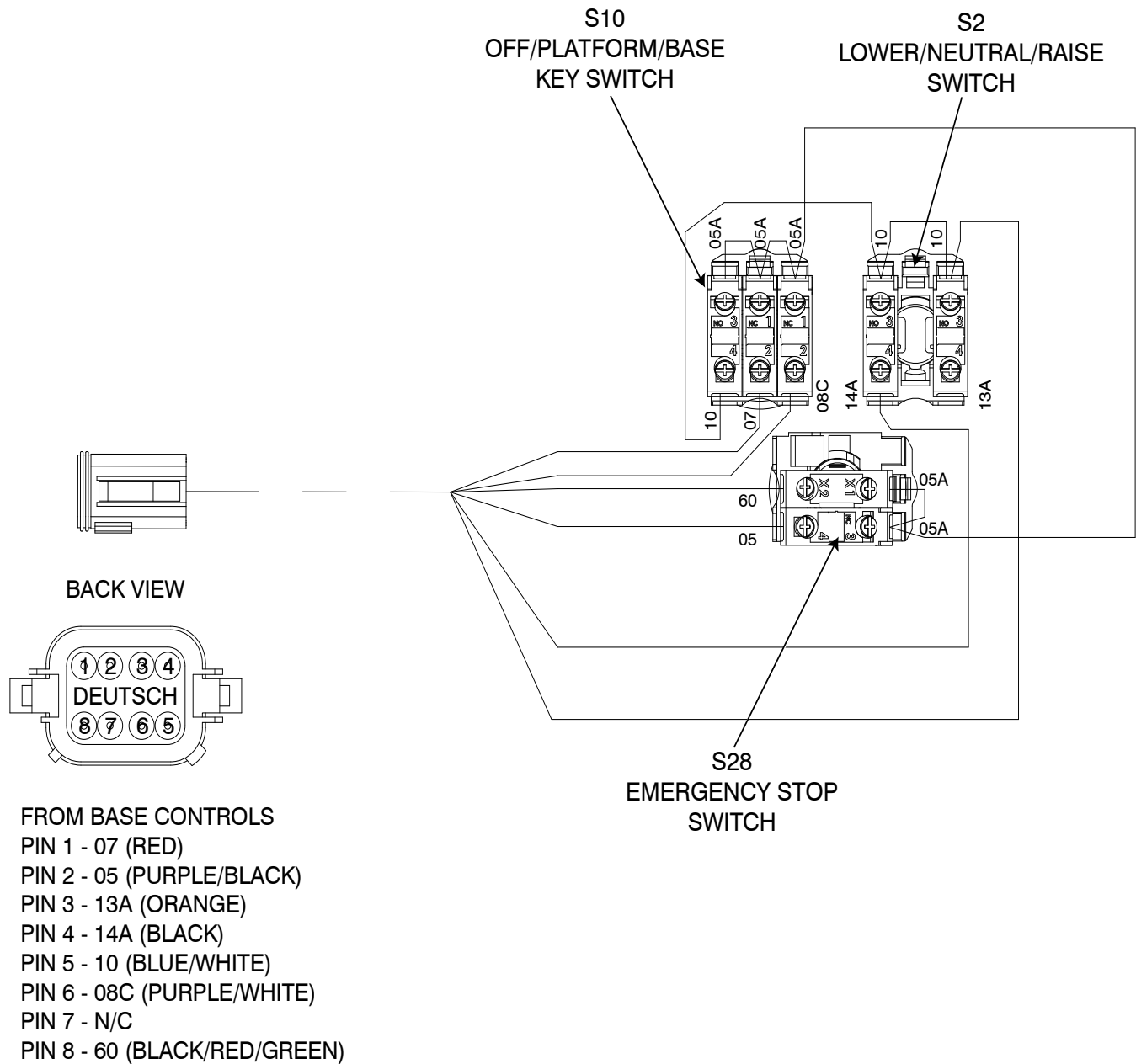
PIN NO.	LABEL	DESCRIPTION	CTRL BOX HARNESS	JOYSTICK HARNESS
1	24	LEFT	BLUE/BLACK	WHITE/RED
2	NONE	N/C	N/C	N/C
3	23	RIGHT	BLACK/WHITE	WHITE
4	08A	ENABLE OUT	BLACK	WHITE/BLUE
5	08E	24V SUPPLY	PURPLE/WHITE	WHITE/BLACK
6	00B	0V SUPPLY	WHITE/BLACK	GREY
7	59	PROP. OUT	ORANGE/BLACK	BLUE
8	08B	5V SUPPLY	GREEN	YELLOW

3.9 Base to platform control cable

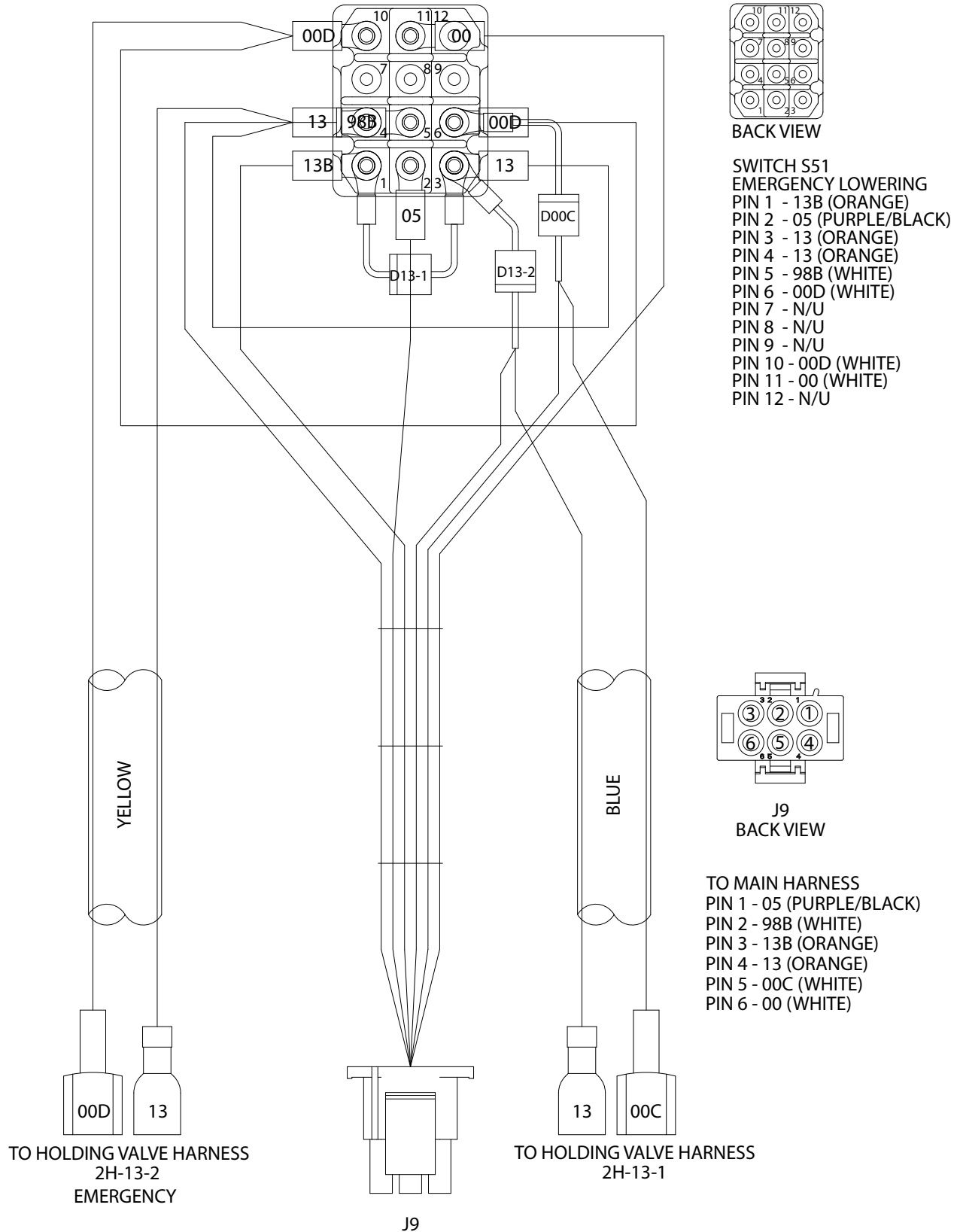
CAVITY NO.	COLOURED WIRE	BLACK WIRE	CIRCUIT NO.
1	WHITE	GREEN/YELLOW	00
2	BLUE	2	12
3	ORANGE	3	09
4	BLACK	4	08A
5	RED	5	07
6	BLUE/WHITE	6	08
7	GREEN/WHITE	7	49
8	GREEN	8	08B
9	NOT USED	NOT USED	
10	WHITE/BLACK	10	00B
11	RED/BLACK	11	18
12	ORANGE/BLACK	12	59
13	GREEN/BLACK	13	-
14	BLUE/BLACK	14	24
15	BLACK/WHITE	1	23
16	RED/WHITE	9	60



3.10 Base control wiring



3.11 Emergency lowering switch wiring



M212536AF

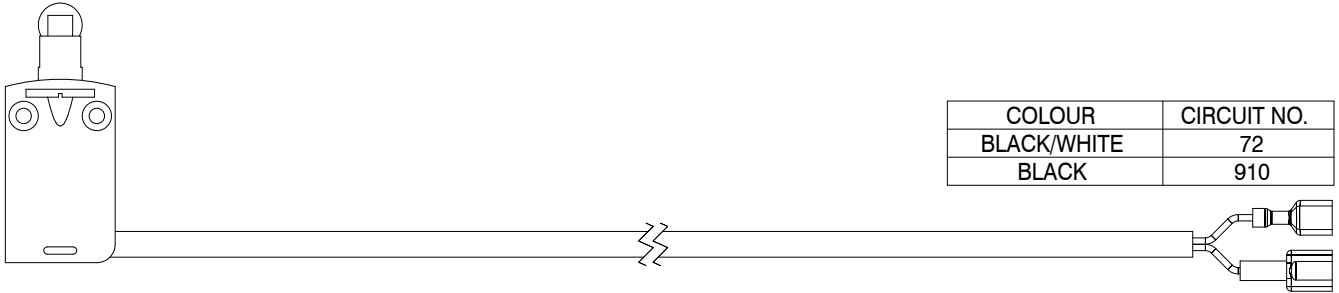
SJ3215, SJ3219

SKYJACK

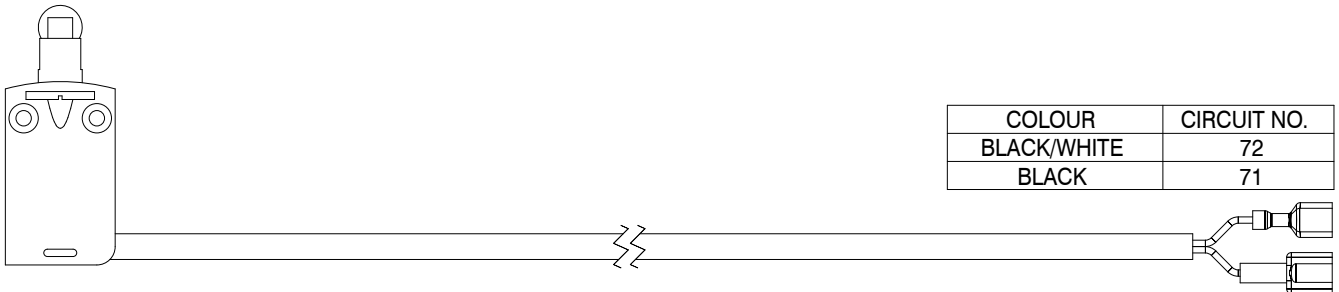
212508AGA

3.12 Pothole limit switch wiring

Hydraulic tray side - LS1



Battery tray side - LS2

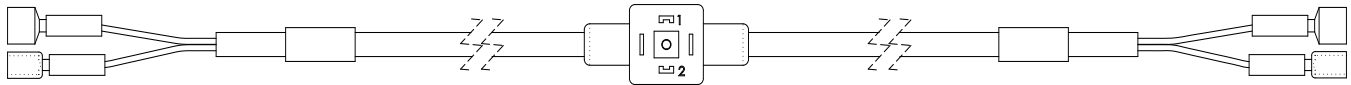


3.13 Holding valve and pressure transducer harnesses

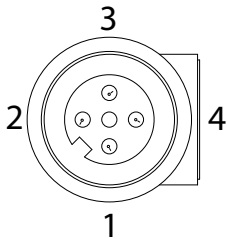
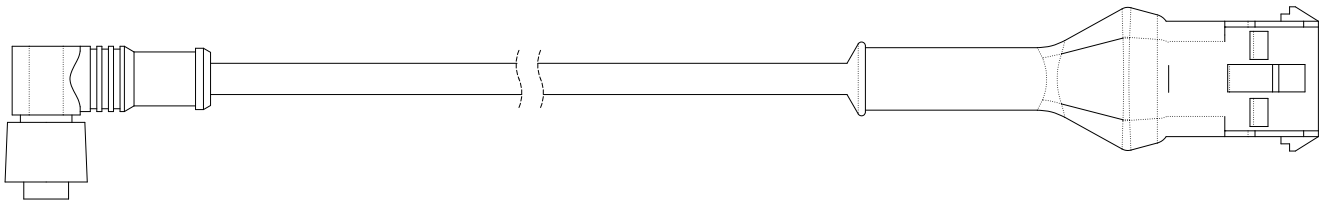
Holding Valve Harness

LABEL	TERMINAL	COLOUR
13	1	BLACK (+12 VDC)
00C	2	WHITE (GND)

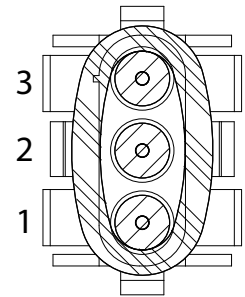
LABEL	TERMINAL	COLOUR
13	1	BLACK (+12 VDC)
00D	2	WHITE (GND)



Pressure Transducer Harness

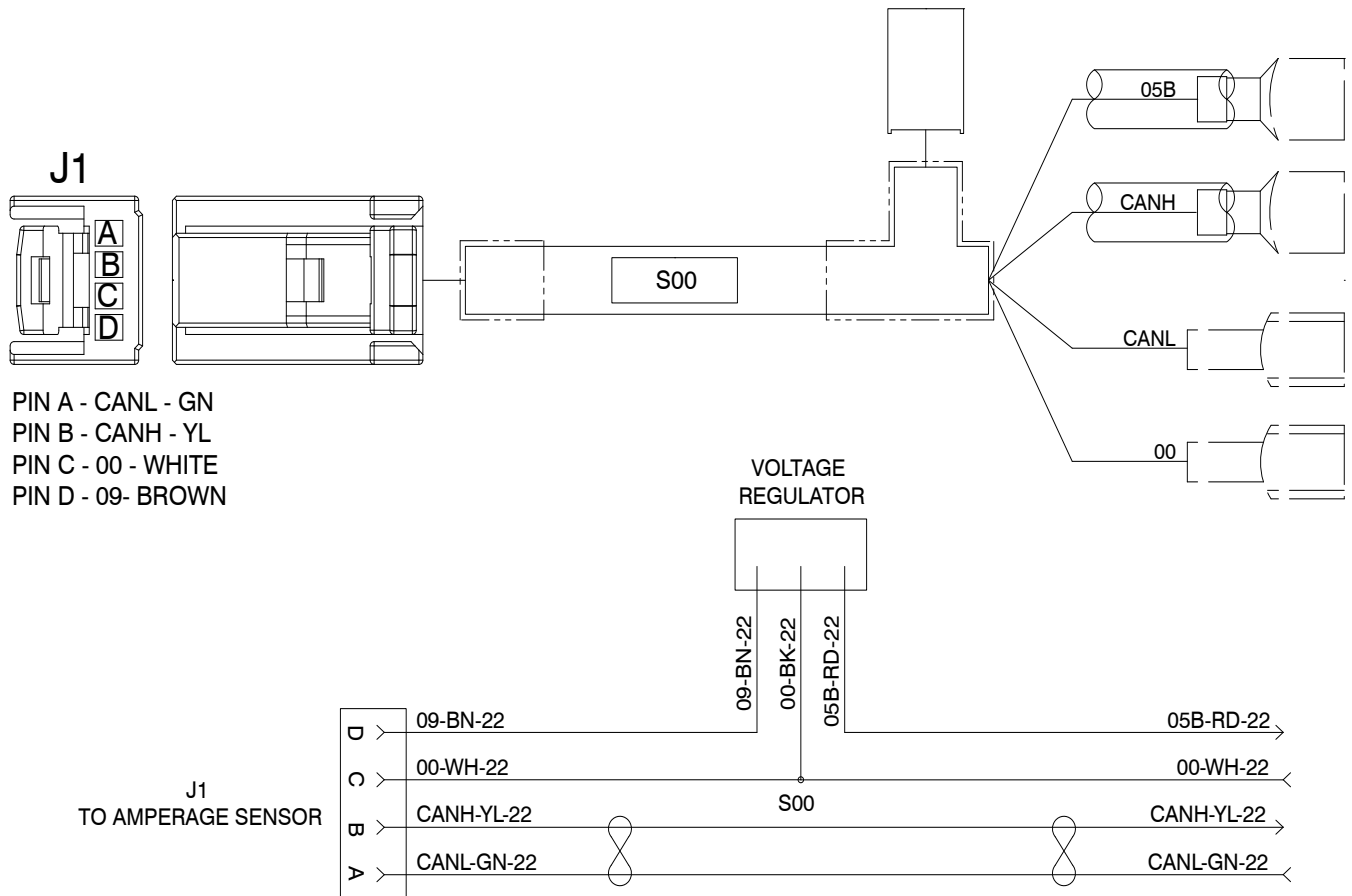


M12 CONNECTOR	MOLEX CONNECTOR	WIRE NUMBER	WIRE COLOUR
PIN 1	PIN 1	910	BROWN
PIN 2	NOT USED	-	-
PIN 3	PIN 3	902	BLUE
PIN 4	PIN 2	60A	BLACK



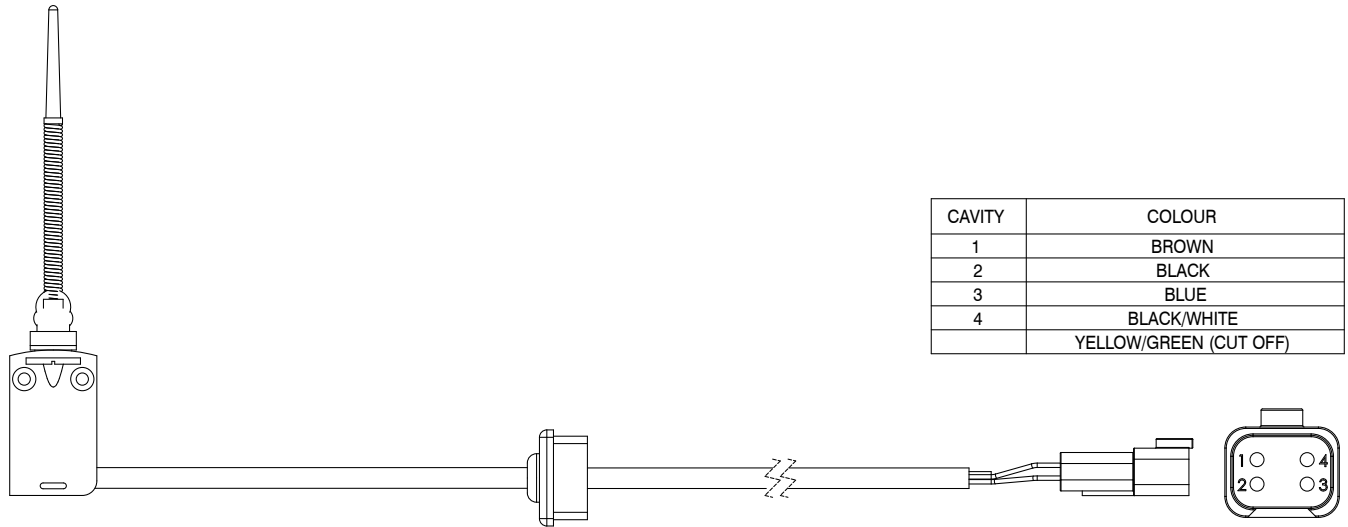
3.14 Battery management system harness

BMS Harness

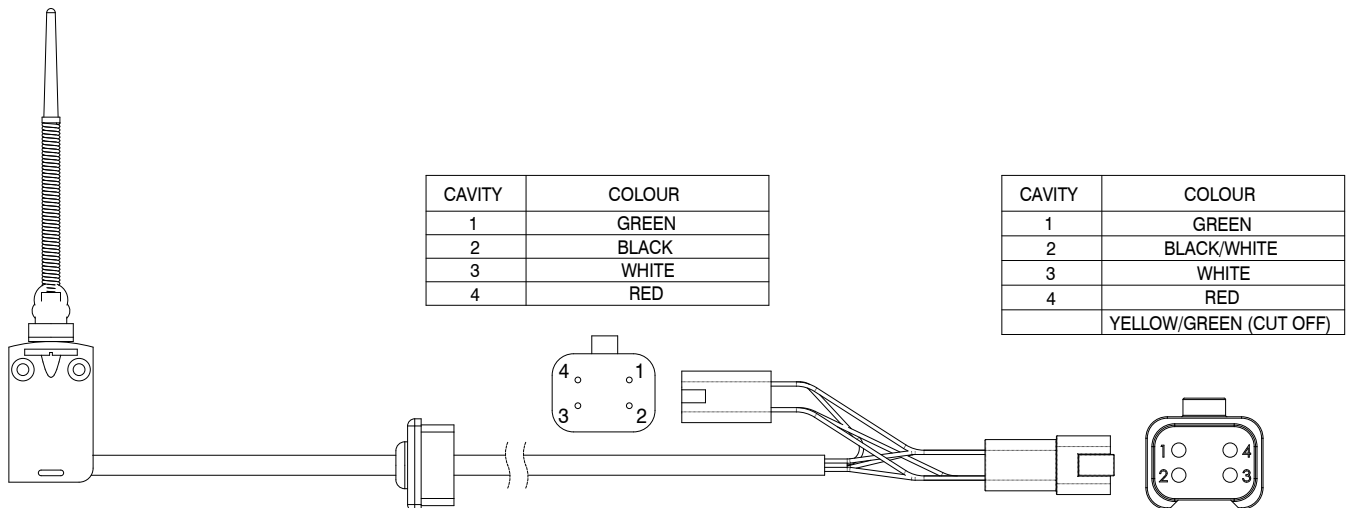


3.15 Anti-oversising limit switch wiring (KC only)

Anti-Oversising Posts Limit Switches

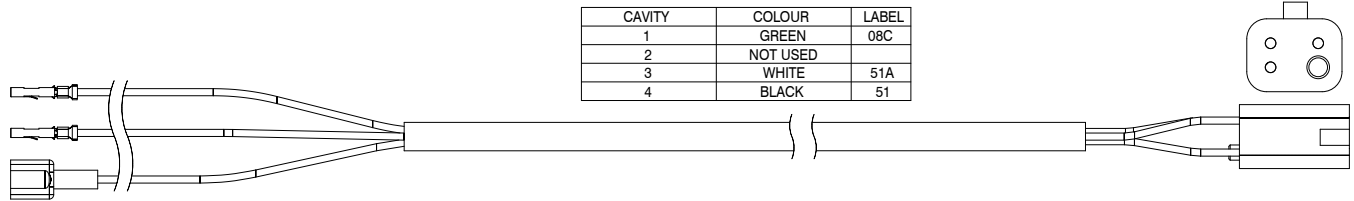


Anti-Oversising Posts Limit Switches - Add 2 Posts

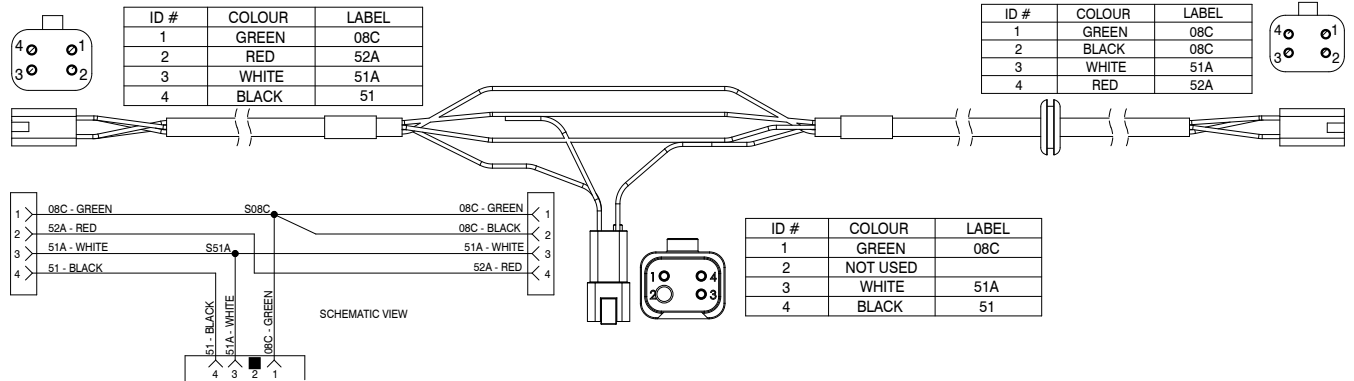


3.16 Anti-overriding limit switch harness (KC only)

Anti-Overriding Posts - Scissor Harness

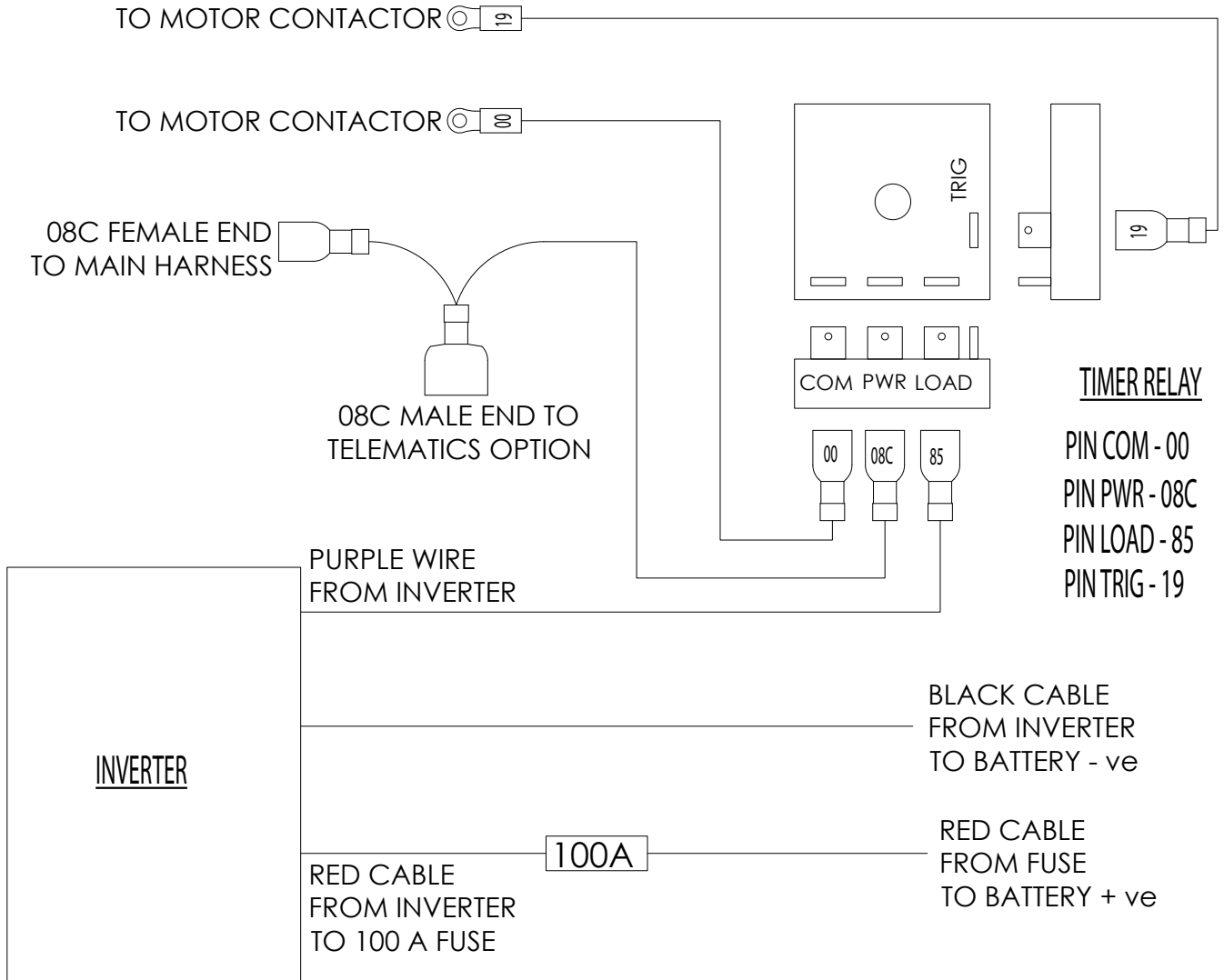


Anti-Overriding Posts - Platform Harness

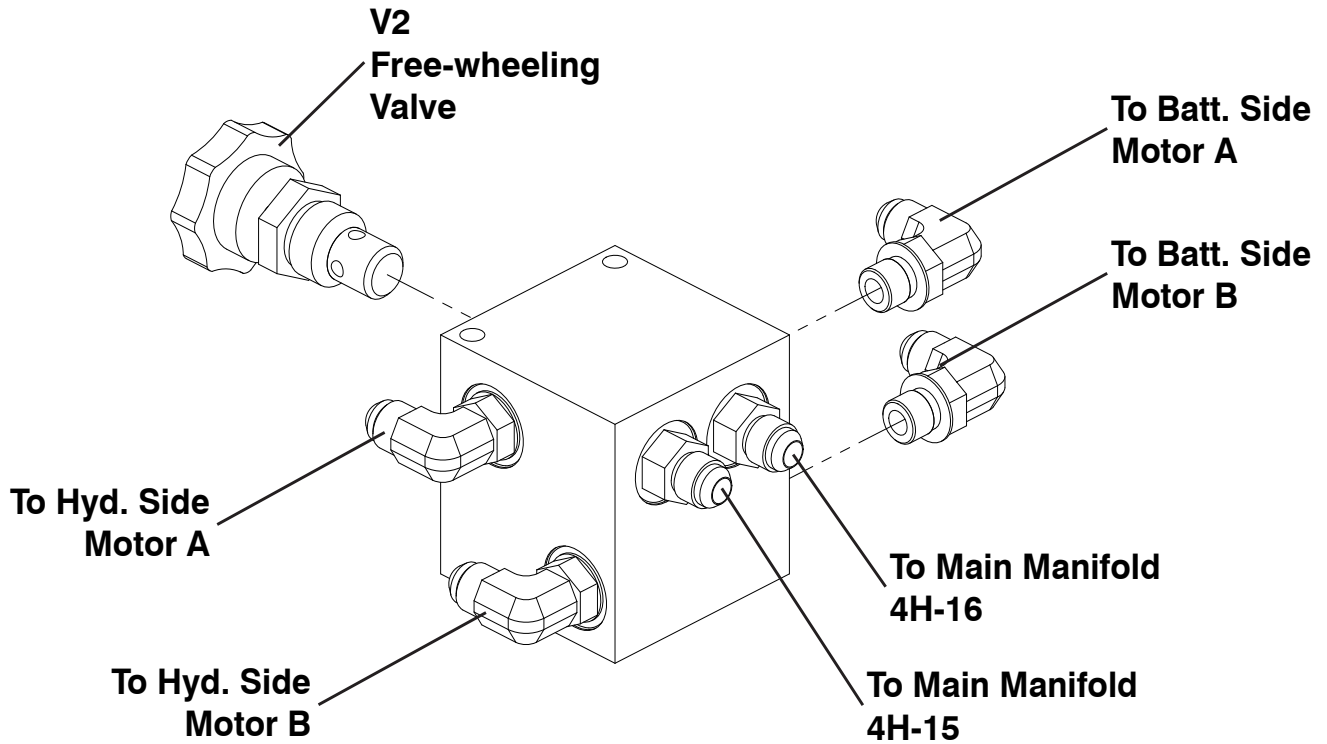


3.17 Inverter wiring

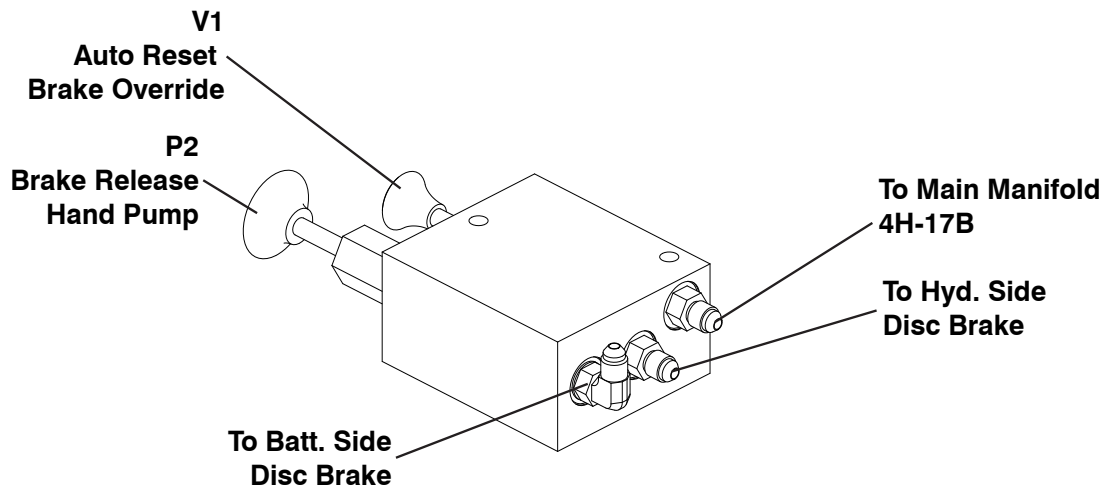
INVERTER OPTION WIRING DIAGRAM



3.18 Free-wheeling manifold MB2

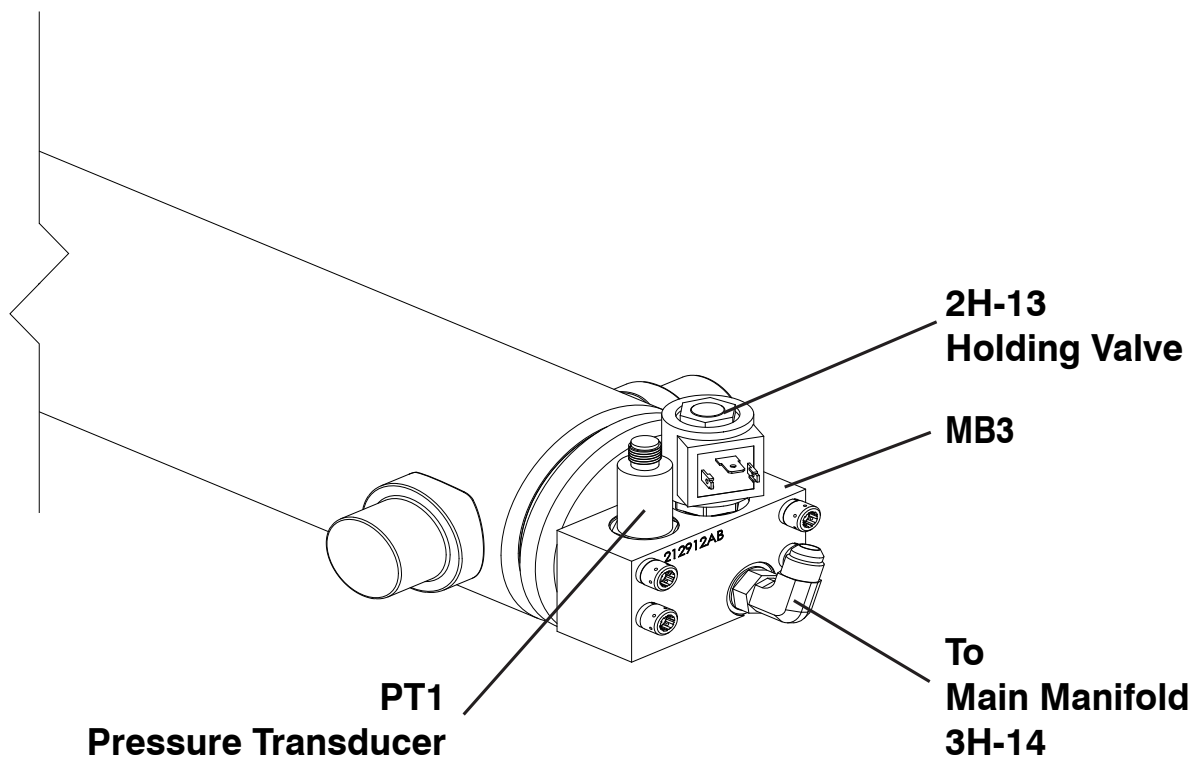


3.19 Brake manifold MB4 (CE, AS & KC)

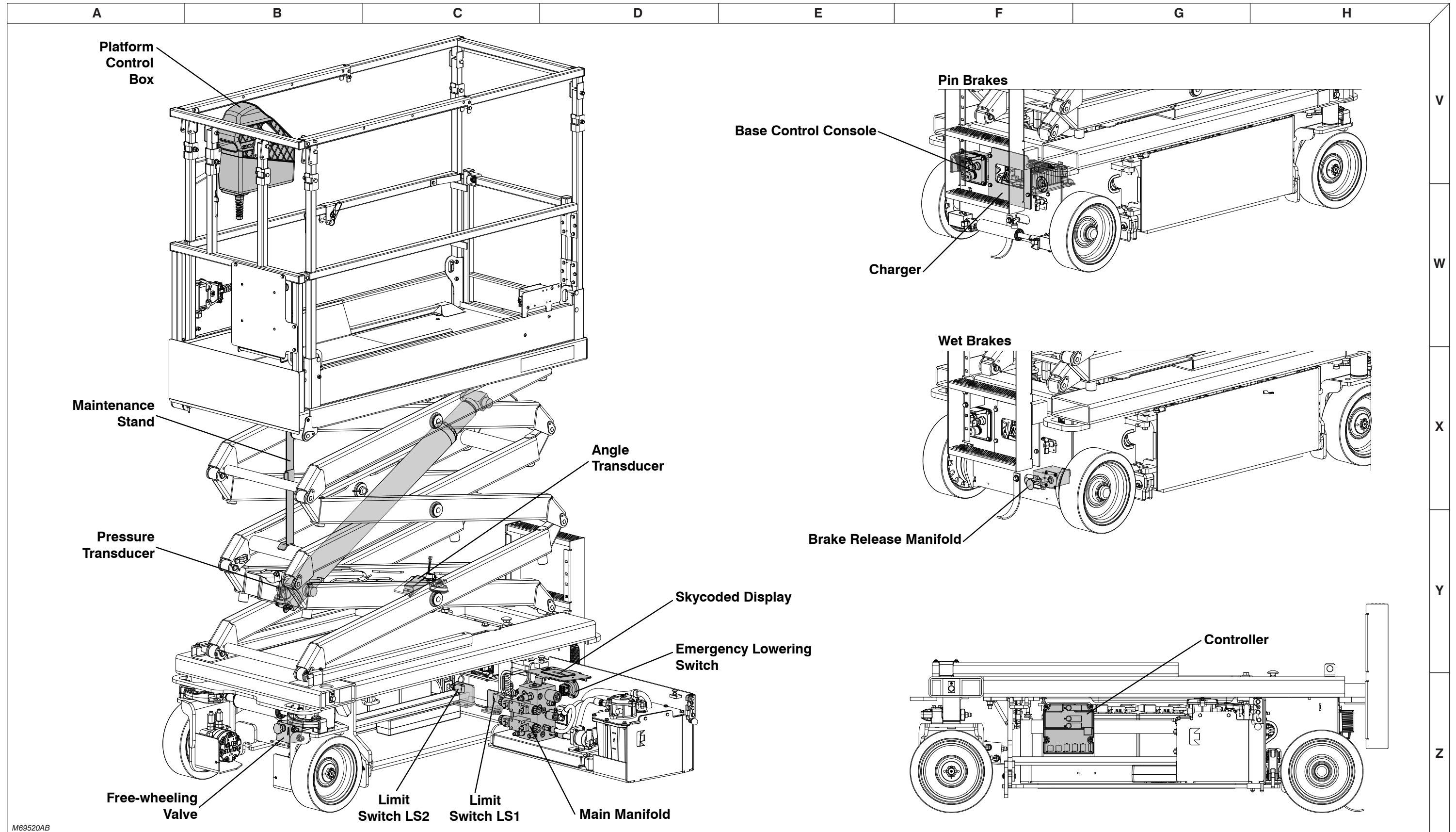


M138021AE_SJ321X_Service, M196578AD_BrakeMan

3.20 Lift cylinder manifold MB3

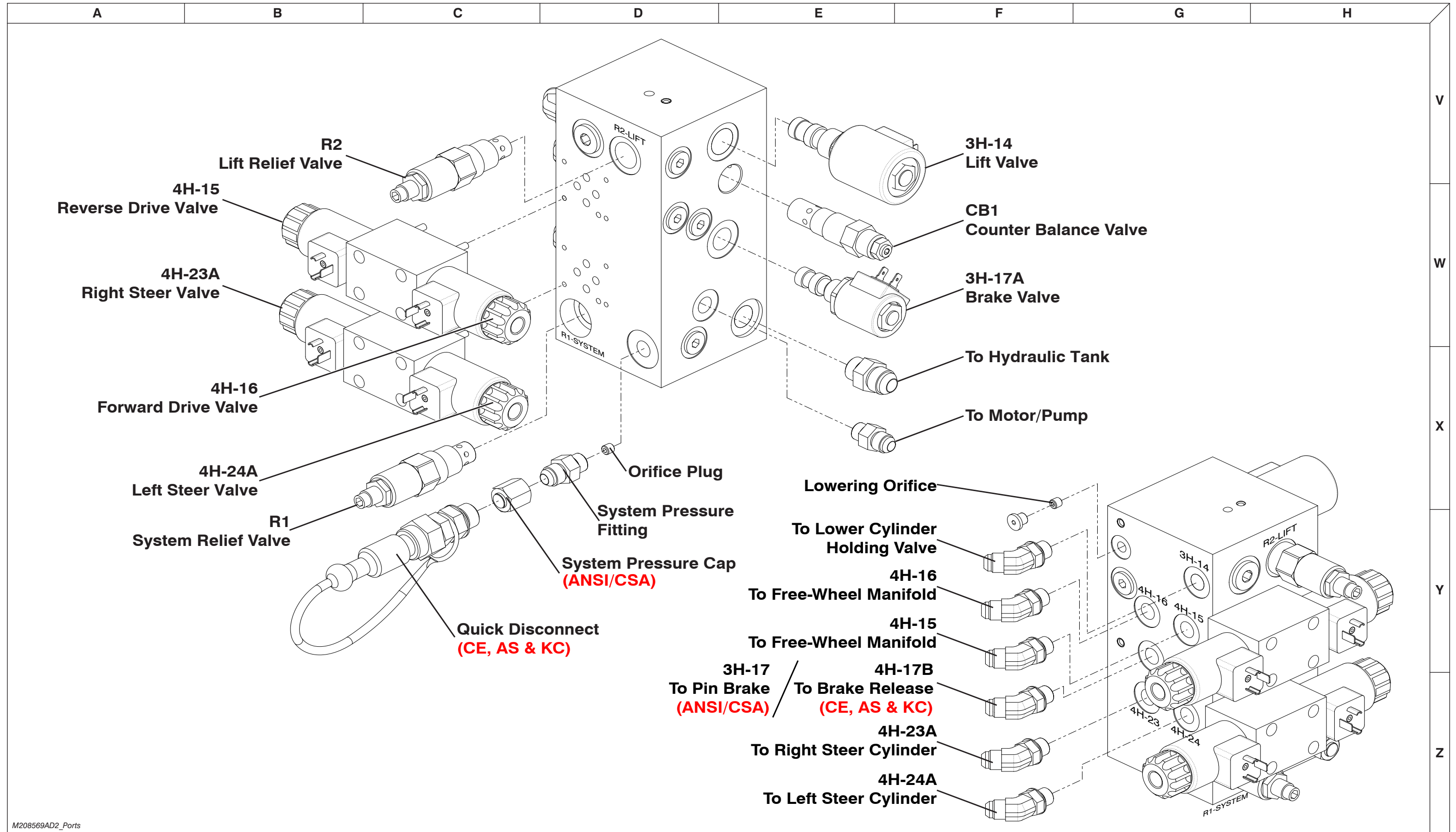


3.21 Major component identification



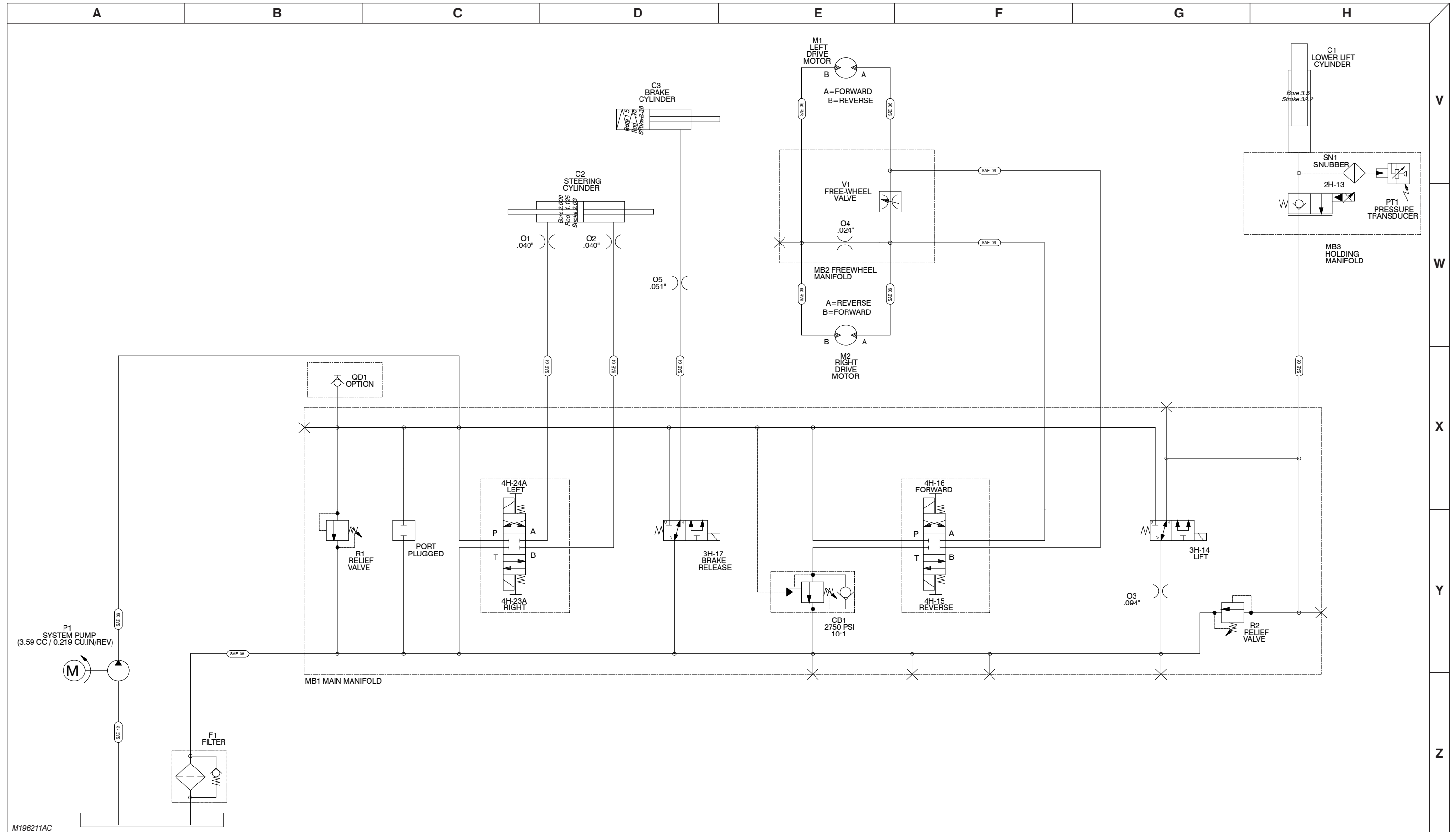
M69520AB

3.22 Main manifold MB1

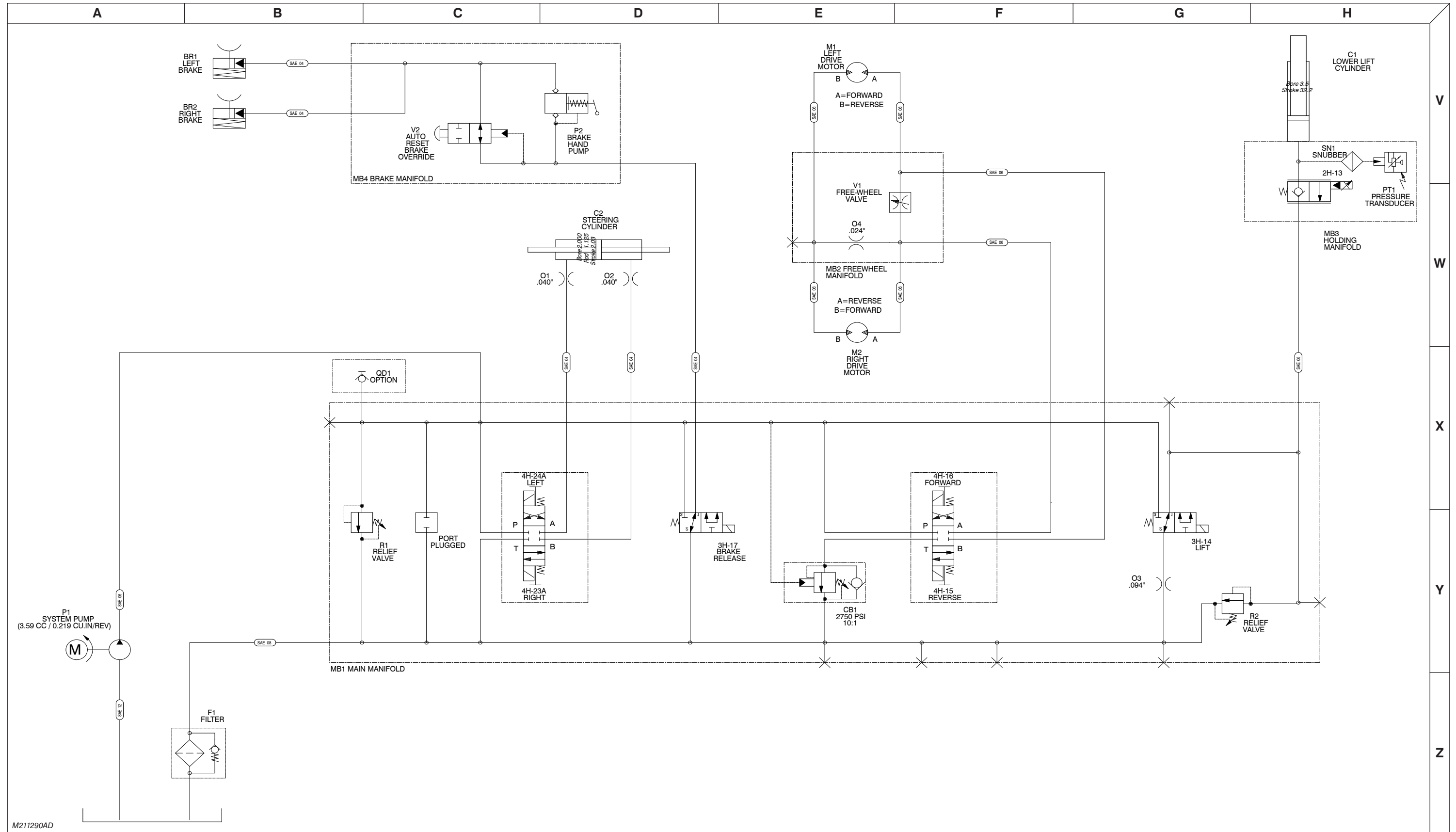


M208569AD2_Ports

3.23 Hydraulic schematic - SJ3215 ANSI/CSA

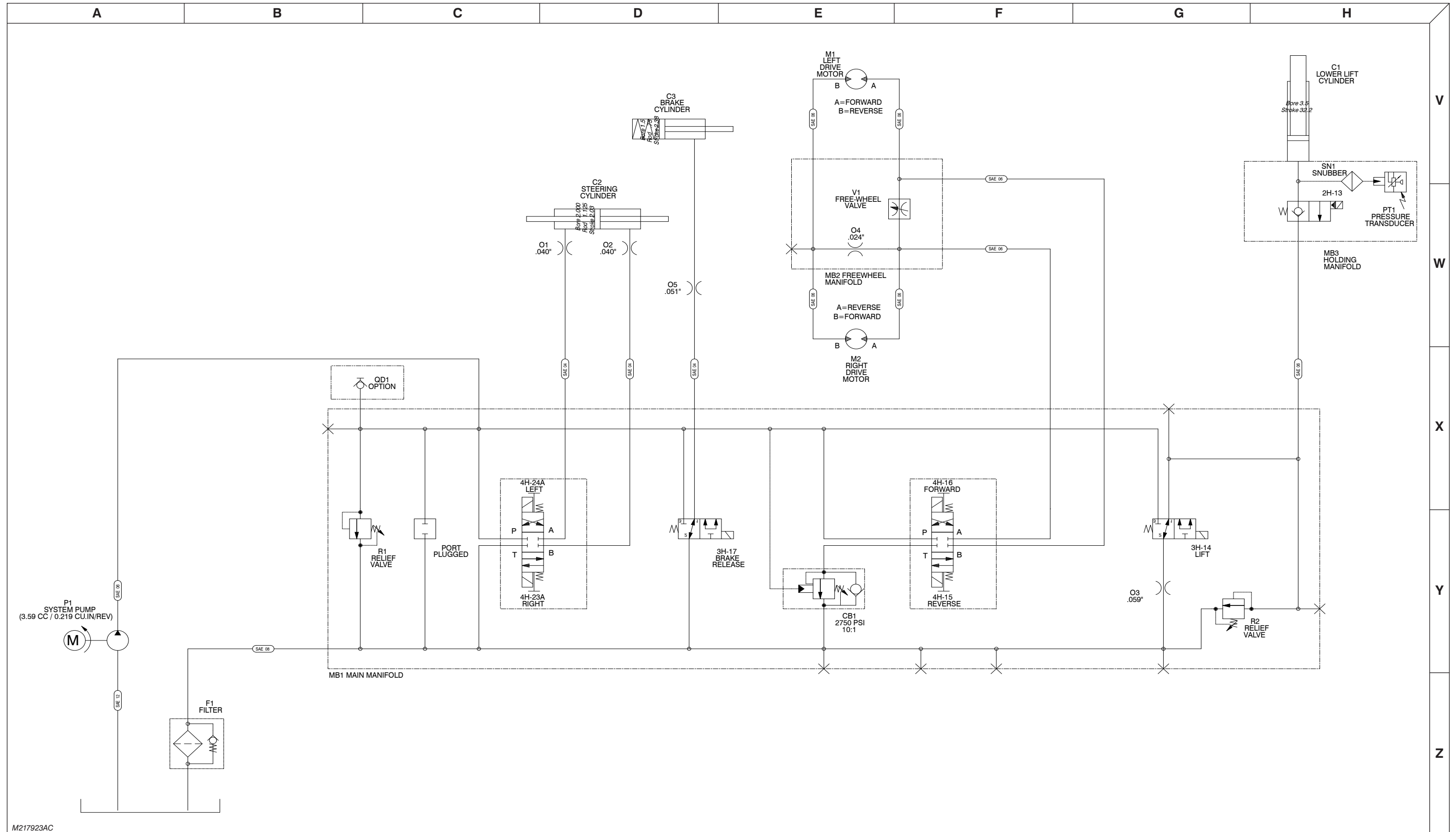


3.24 Hydraulic schematic - SJ3215 CE, AS & KC



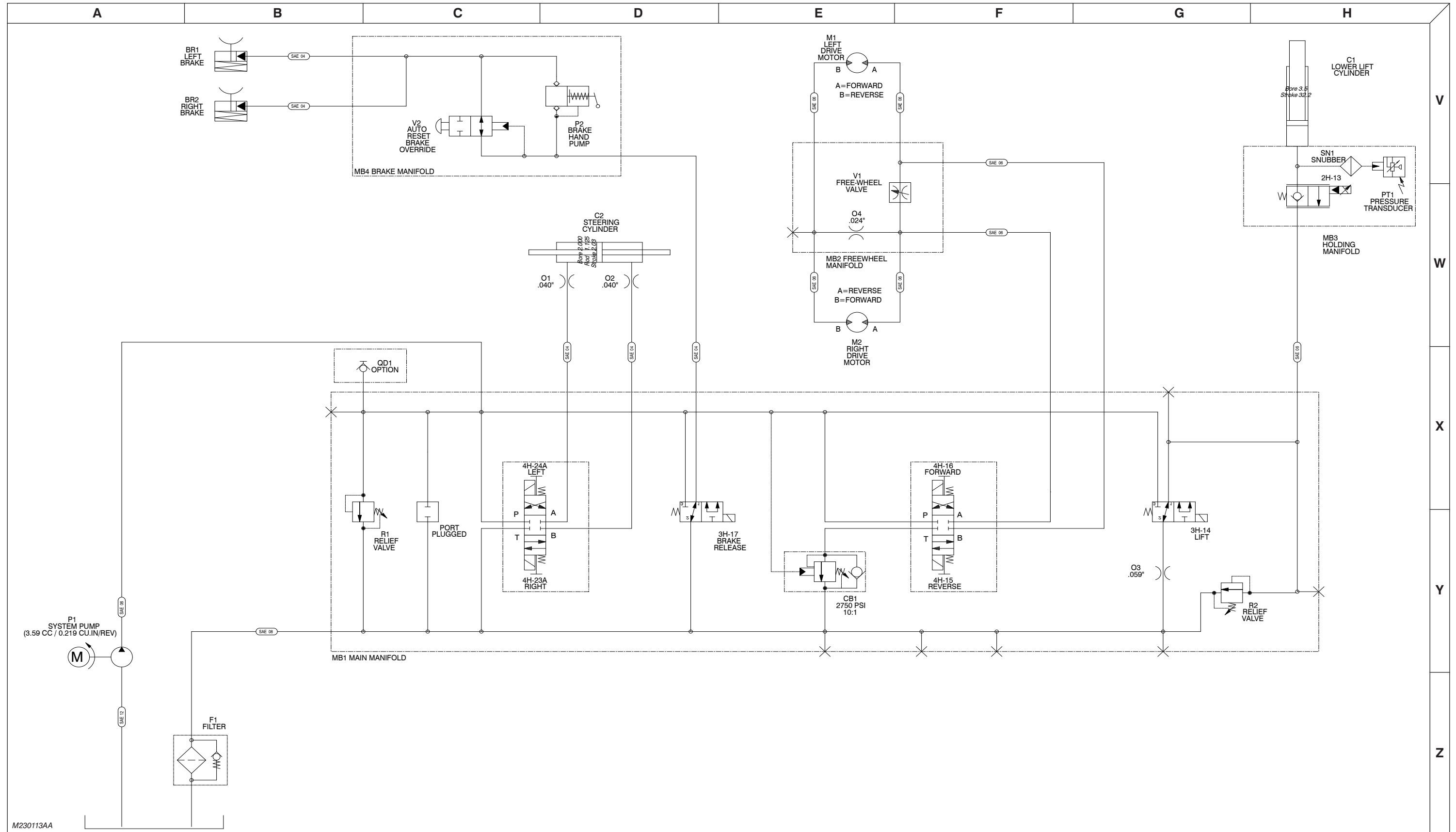
M211290AD

3.25 Hydraulic schematic - SJ3219 ANSI/CSA



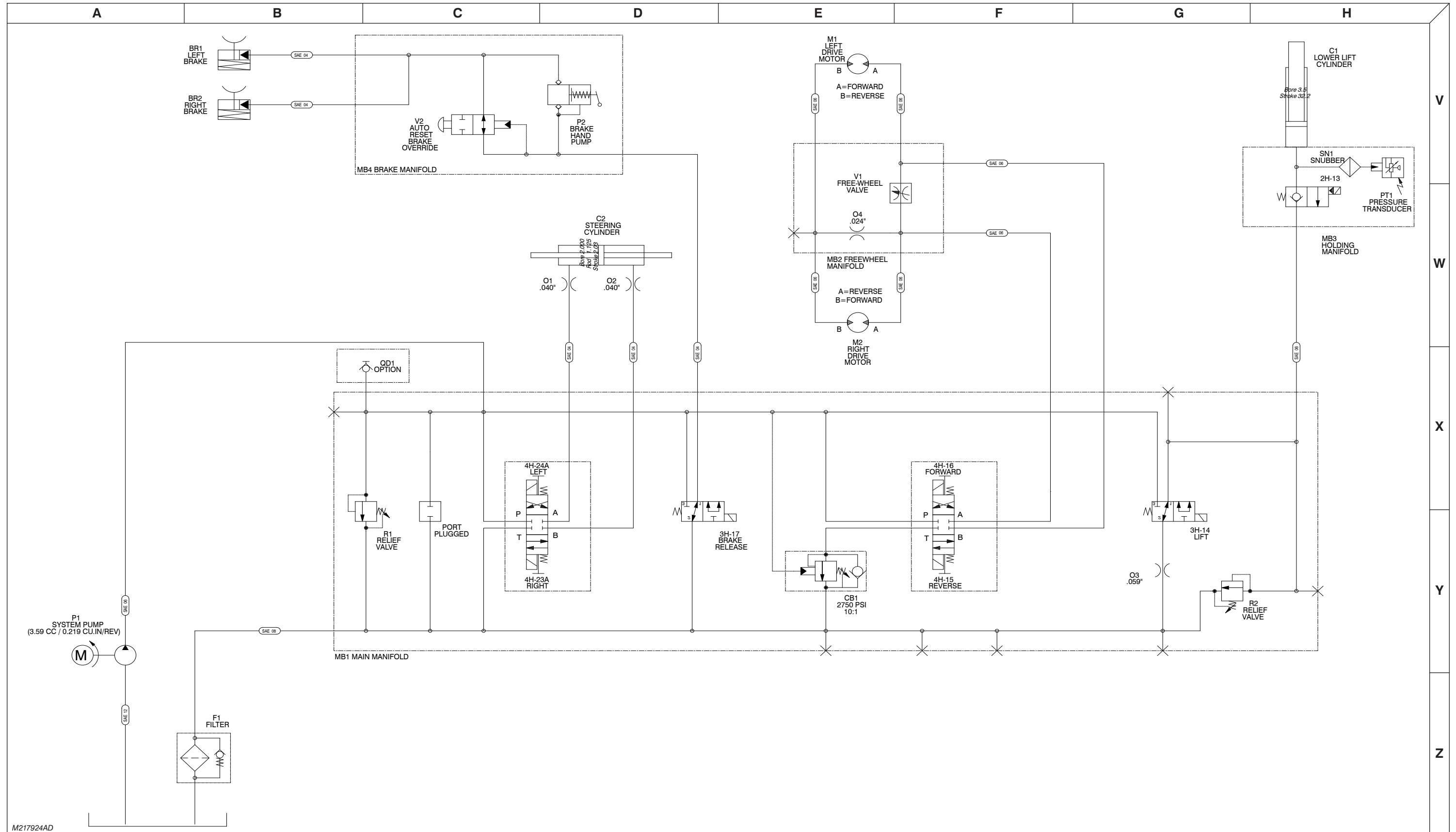
M217923AC

3.26 Hydraulic schematic - SJ3219 CE



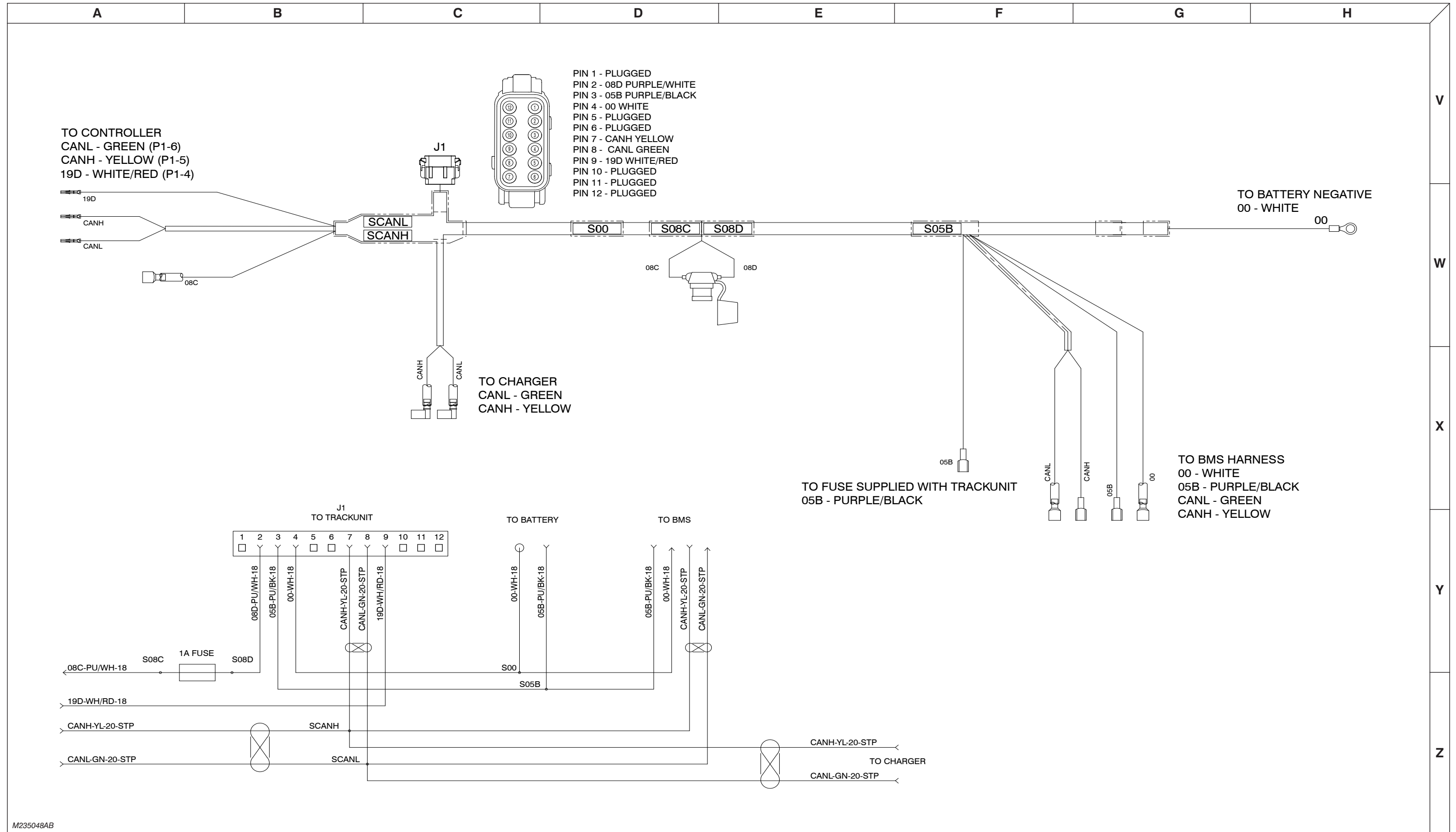
M230113AA

3.27 Hydraulic schematic - SJ3219 AS & KC



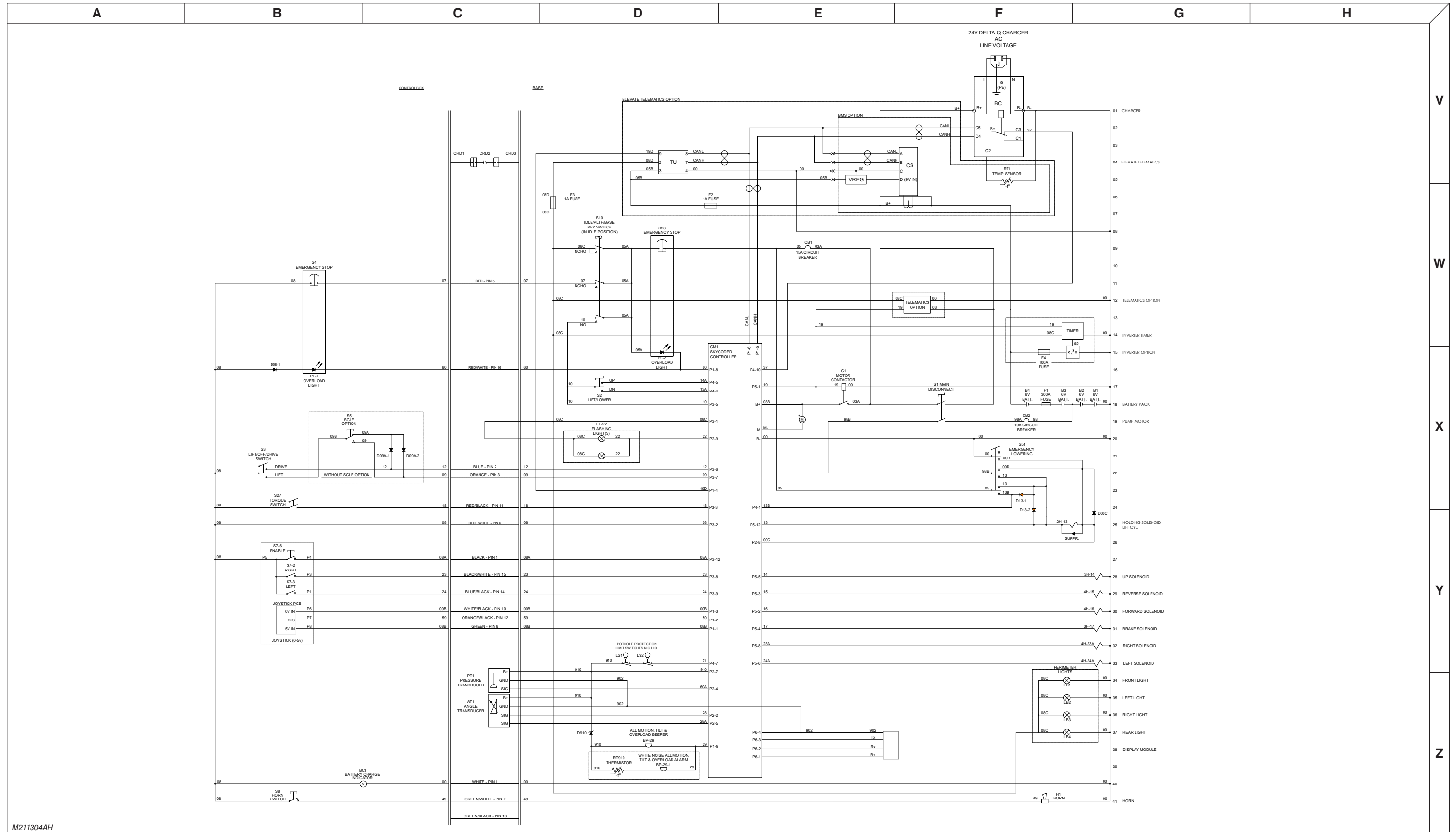
M217924AD

3.28 Elevate Telematics harness



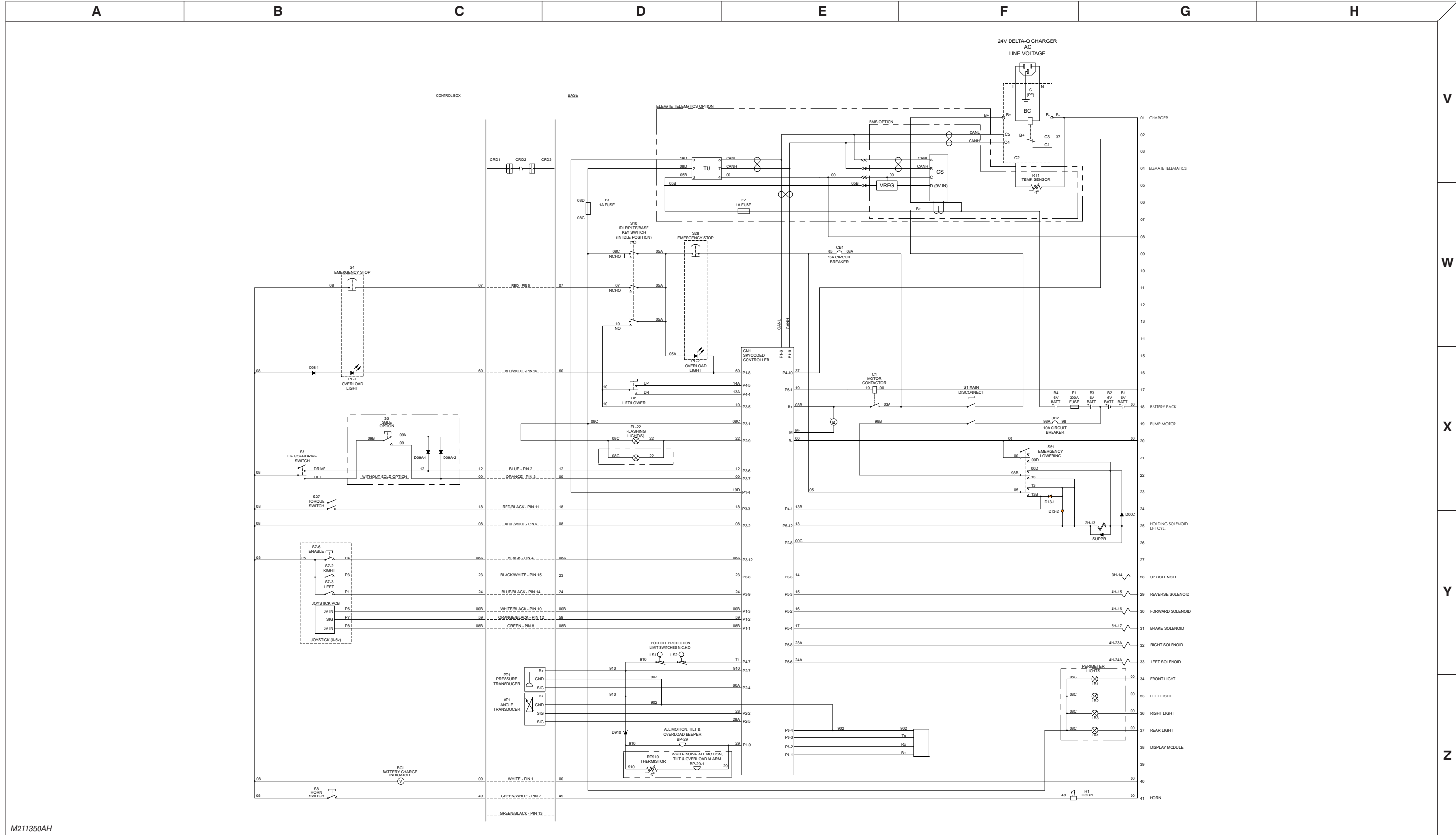
M235048AB

3.29 Electrical schematic - ANSI/CSA



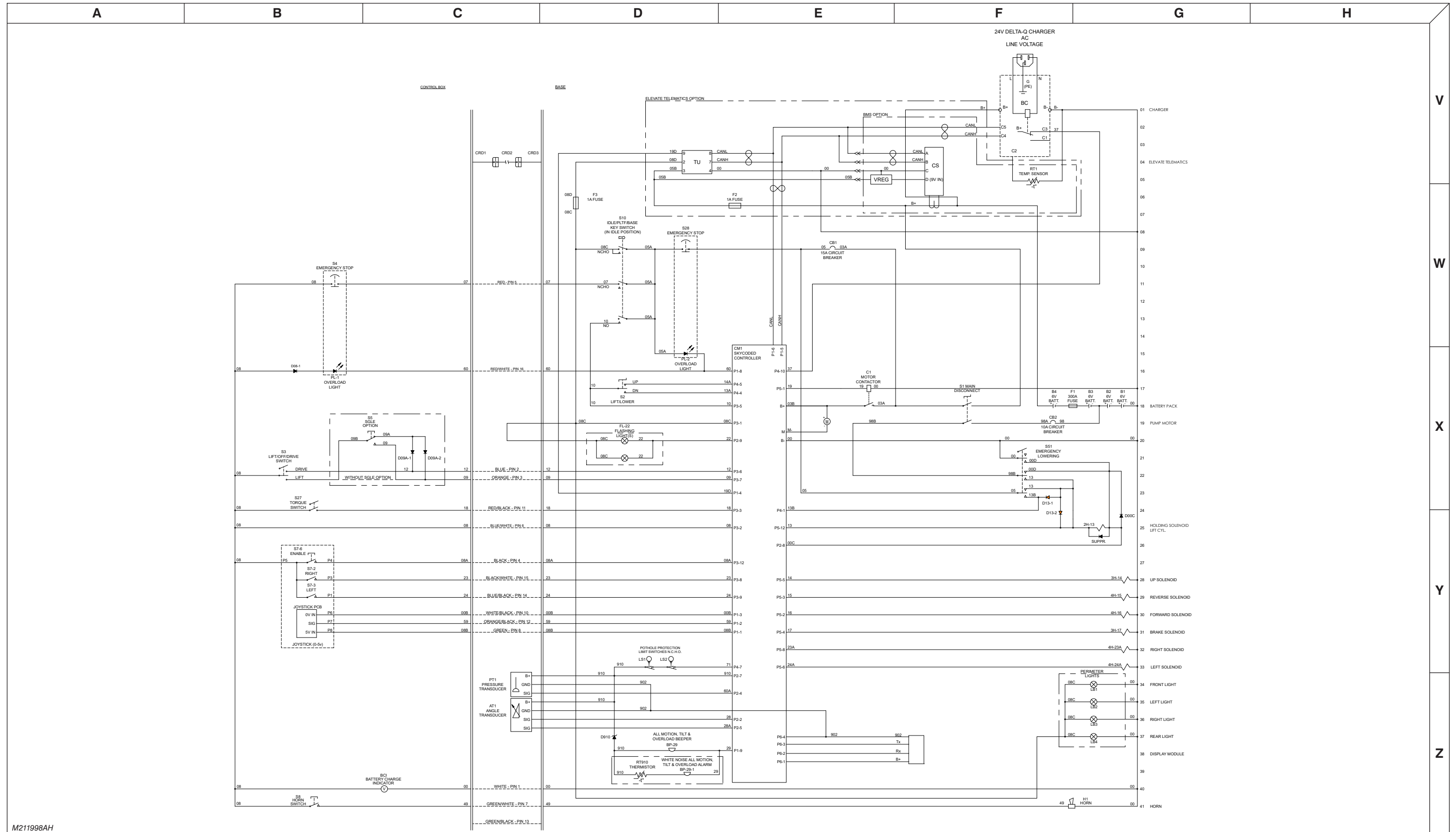
M211304AH

3.30 Electrical schematic - CE



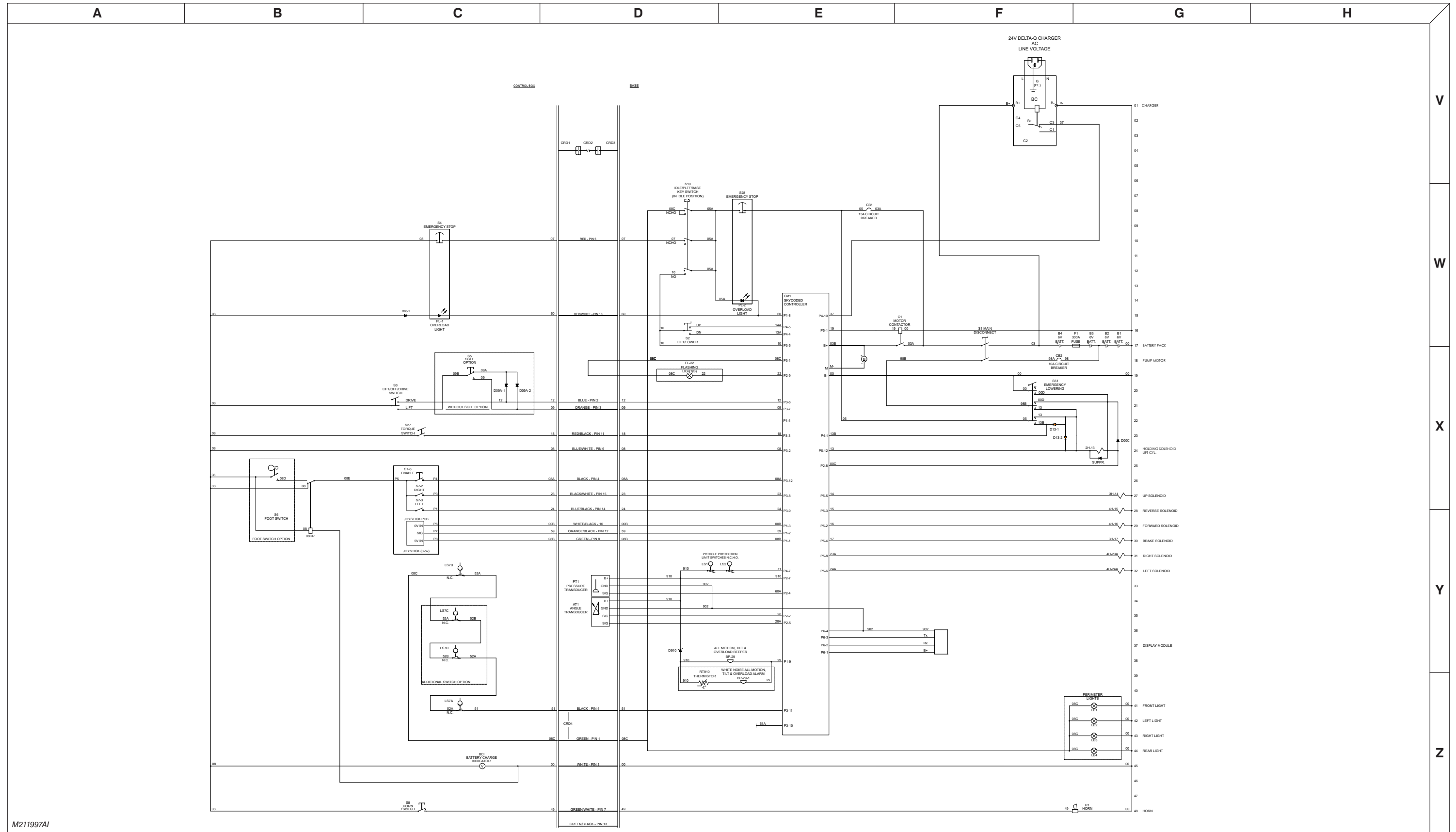
M211350AH

3.31 Electrical schematic - AS



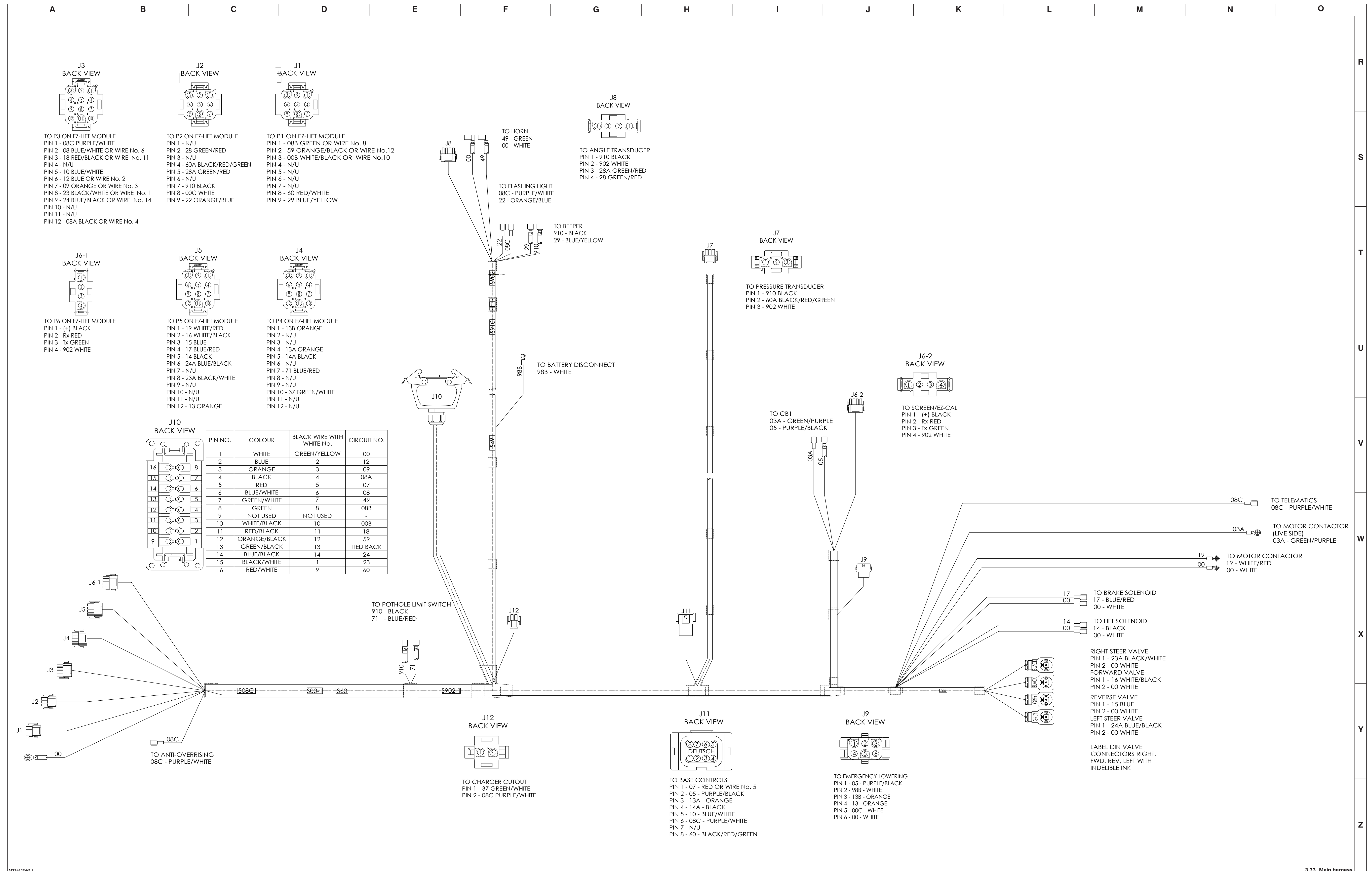
M211998AH

3.32 Electrical schematic - KC



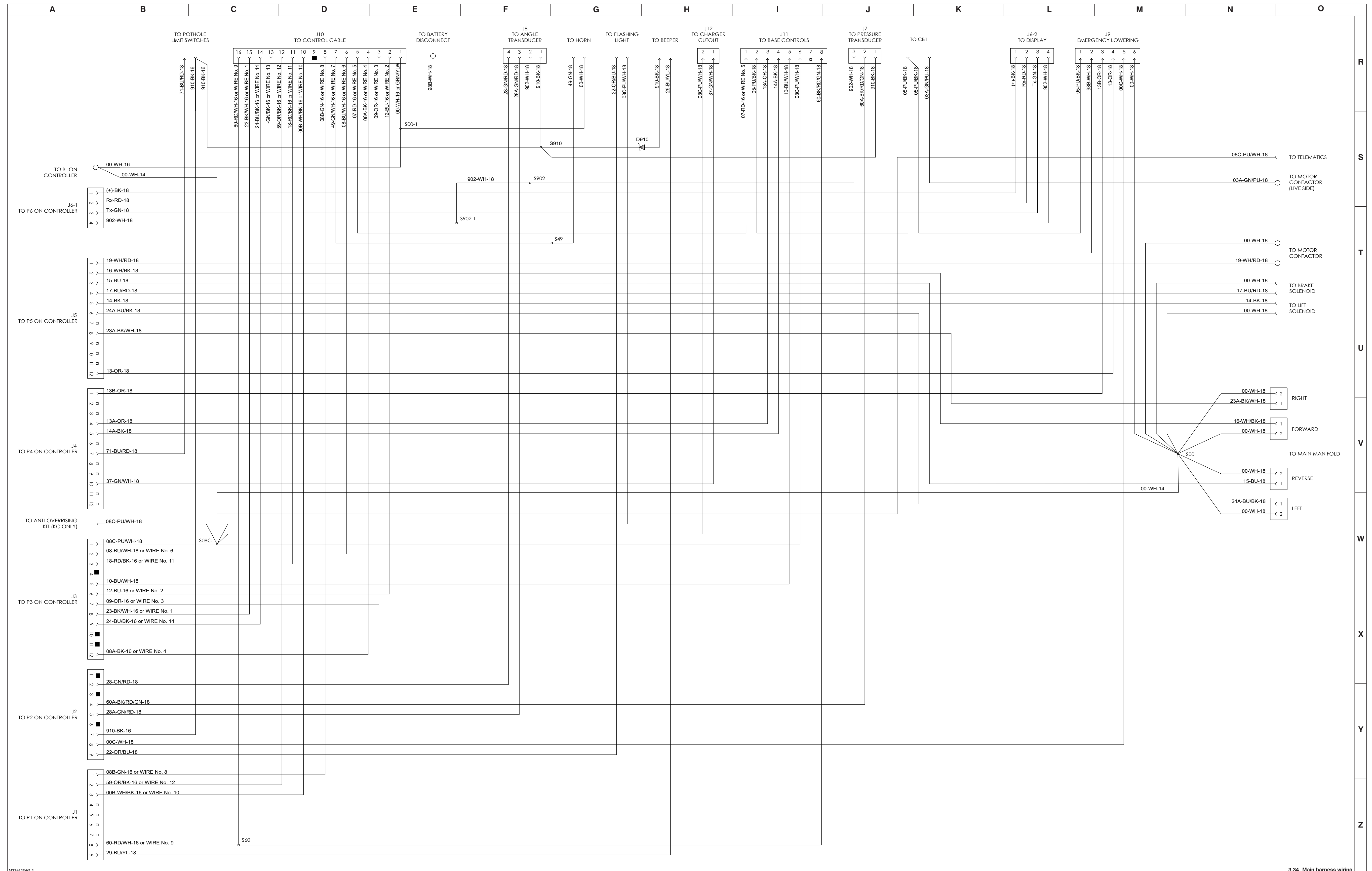
M211997AI

3.33 Main harness



M224525AG-1

3.34 Main harness wiring



M224529AG-2

3.34 Main harness wiring

Section 4 – Troubleshooting Information

4.1 Introduction

The following pages contain a table of Troubleshooting for locating and correcting most service trouble which can develop. Careful and accurate analysis of the systems listed in the table of Troubleshooting will localize the trouble more quickly than any other method. This manual cannot cover all possible troubles and deficiencies that may occur. If a specific trouble is not listed, isolate the major component in which the trouble occurs, isolate whether the problem is electrical or hydraulic, and then isolate and correct the specific problem.

The content of this section is separated into “probable cause” and “remedy.” The information in the left-hand column, preceded by a number, represents the “probable cause.” The information in the right-hand column, in bold text, represents the “remedy” to the “probable cause” directly beside it. See the example below for clarification.

1. Probable cause

Remedy

4.2 Electrical system

4.2-1 All controls inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Battery charger plugged into external power source.	<p>Disconnect charger cord.</p> <p>If equipped with a Delta Q charger, check continuity between wire #B+ and wire #37 on the Delta Q Charger to test the N.C. contact in battery charger cutoff relay L1CR.</p> <p>If equipped with another charger, check continuity between wire #08C and wire #37 on the other charger to test the N.C. contact in the battery charger cutoff relay L1CR.</p> <p>Replace the charger if the contact is not closed when unplugged from an external power source.</p> <p>Check continuity of wire #37 from the battery charger cutoff relay L1CR to control module CM1 pin #P4-10.</p> <p>Use the HMI diagnostic menu to make sure the input P4-10 signal is present.</p>
3. Batteries disconnected or faulty.	Connect batteries and test each battery for the correct supply voltage.
4. Dirty or loose battery terminals.	Clean and tighten the connections.
5. Battery charge low.	<p>Check each cell with a hydrometer. The reading should be 1.275 (fully charged).</p> <p>Recharge if low reading.</p> <p>Replace if the reading difference between cells is 0.050.</p>
6. Main battery cables open or defective.	Check continuity. Replace if defective.
7. Fuse F1 defective or open.	Replace fuse.
8. Main battery disconnect switch S1 open or defective.	<p>Close switch.</p> <p>Check continuity between wire #03 and wire #03A on switch.</p> <p>Check continuity between wire #98A and wire #98B on switch.</p> <p>Replace the switch if there is no continuity between either one of the switch poles.</p>
9. Loose or broken wires from fuse F1 to Battery to main disconnect S1	Check continuity to #03A. Replace if defective.

10. Loose or broken wire #03A to circuit breaker CB1 or circuit breaker is open.	Check continuity to circuit breaker. Test circuit breaker CB1. Replace if defective.
11. Loose or broken wire #05 to base emergency stop switch S28.	Check continuity. Replace if defective.
12. Open or defective base emergency stop switch S28.	Close switch. Check continuity between wire #05 and wire #05A on switch. Replace if defective.
13. Loose or broken wire #05A from base emergency stop switch S28 to base key switch S10.	Check continuity. Replace if defective.
14. Open or defective base key switch S10.	Select function with switch. Check continuity between wire #05A and wire #08C on switch with base or platform selected. Check continuity between wire #05A and wire #07 on switch with platform selected. Check continuity between wire #05A and wire #10 on switch with base selected. Replace switch if no continuity during correct switch function.
15. Loose or broken wire #08C from base key switch S10 to control module CM1 pin #P3-1.	Check continuity. Test for 24V supply voltage between wire #08C and wire #00. Use HMI diagnostic menu to make sure input P3-1 signal is present. Replace if defective.
16. Loose or broken wire #07 from base key switch S10 to platform emergency stop switch S4.	Check continuity. Replace if defective.
17. Open or defective platform emergency stop switch S4.	Close switch. Check continuity between wire #07 and wire #08 on switch. Replace if defective.
18. Loose or broken wire #08 from platform emergency stop switch s4 to control module CM1 pin #P3-2.	Check continuity. Test for 24V supply voltage between wire #08 and wire #00. Use HMI diagnostic menu to make sure Input P3-2 signal is present. Replace if defective.
19. Loose or broken B- cable wire #00 from batteries to B- lug on control module CM1.	Check continuity. Replace if defective.
20. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-2 All controls except for down function inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #19 from control module CM1 pin P5-1 to motor contactor C1.	Check continuity. Test for 24V output voltage between wire #19 and wire #00. Use HMI diagnostic menu to make sure output P5-1 signal is present. Replace if defective.
3. Loose or broken wire #00 from motor contactor C1 to battery (-).	Check continuity. Replace if defective.
4. Loose or broken wire #03A from main disconnect switch S1 to motor contactor C1 N.O. contact.	Check continuity. Replace if defective.
5. Motor contactor C1 not functioning	Check that motor contactor C1 coil is energized when signal on wire #19 from control module CM1 pin #P5-1 to motor contactor C1 is enabled. Check continuity between wire #03A and #03B on the N.O. contact when motor contactor C1 coil is energized (or operating a function that provides B+ to control module CM1 pin #P5-1 from motor contactor C1 on wire #03B). Replace contactor if defective
6. Loose or broken B- cable wire #00 from batteries to B- lug on control module CM1.	Check continuity. Replace if defective.
7. Loose or broken wire #M- from M lug on control module CM1 to motor DCM1.	Check continuity. Replace if defective.
8. Loose or broken wire #03B from B+ lug on control module CM1 to motor DCM1.	Check continuity. Replace if defective.
9. Defective motor DCM1.	Supply the motor DCM1 with 24 volt supply and a B- across motor to check operation of motor DCM1. Replace if defective.
10. External or internal fault detected by control module CM1	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-3 All controls inoperative from base control console

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #03A to circuit breaker CB1 or circuit breaker is open	Check continuity to circuit breaker. Test circuit breaker CB1. Replace if defective.
3. Loose or broken wire #05 to base emergency stop switch S28.	Check continuity. Replace if defective.
4. Open or defective base emergency stop switch S28.	Close switch by pulling knob out and check switch. Replace if defective.
5. Loose or broken wire #05A from base emergency stop switch S28 to base key switch S10	Check continuity. Replace if defective.
6. Open or defective base key switch S10.	Check switch. Check continuity between wire #05A and wire #08C on switch (when selected on base or platform). Check continuity between wire #05A and wire #07 on switch (when selected on platform only). Check continuity between wire #05A and wire #10 on switch (when selected on base only) Replace switch if no continuity when operating switch.
7. Loose or broken wire #08C from base key switch S10 to control module CM1 pin #P3-1 (enable signal).	Check continuity. Test for 24V input voltage between wire #08C and wire #00. Use HMI diagnostic menu to make sure input P3-1 signal is present. Replace if defective.
8. Loose or broken wire #10 from base key switch S10 to Base lift/lower switch S2.	Check continuity. Replace if defective.
9. Loose or broken #10 wire from base key switch S10 to control module CM1 pin #P3-5 (Base signal)	Check continuity. Test for 24V input voltage between wire #10 and wire #00. Use HMI diagnostic menu to make sure input P3-5 signal is present. Replace if defective.
10. Open or defective lift/lower switch S2.	Check switch. Check continuity between wire #10 and wire #14A on switch (when selected on Up). Check continuity between wire #10 and wire #13A on switch (when selected to Dn). Replace switch if no continuity when operating switch.

11. Loose or broken #14A wire from lift/lower switch S2 to control module CM1 pin #P4-5 (Up signal)	<p>Check continuity. Test for 24V input voltage between wire #14A and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P4-5 signal is present</p> <p>Replace if defective.</p>
12. Loose or broken #13A wire from lift/lower switch S2 to control module CM1 pin #P4-4 (Dn signal)	<p>Check continuity. Test for 24V input voltage between wire #13A and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P4-4 signal is present.</p> <p>Replace if defective.</p>
13. External or internal fault detected by control module CM1	<p>Check control module display screen. Use diagnostic menu to see switch and sensor status.</p> <p>Correct trouble code as displayed. Replace module if defective.</p>

4.2-4 No up function from base control console

1. Control module CM1 display is broadcasting an error message.	<p>Check control module display screen and follow instructions to clear error.</p>
2. Open or defective lift/lower switch S2.	<p>Check switch.</p> <p>Check continuity between wire #10 and wire #14A on switch. (Up mode)</p> <p>Replace switch if no continuity when operating switch.</p>
3. Loose or broken wire #14A from lift/lower switch S2 to control module CM1 pin #P4-5 (Up signal).	<p>Check continuity. Test for 24V input voltage between wire #14A and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P4-5 signal is present.</p> <p>Replace if defective.</p>
4. Loose or broken wire #14 from control module CM1 pin #P5-5 to Up valve coil 3H-14.	<p>Check continuity. Test for 24V output voltage between wire #14 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P5-5 signal is present.</p> <p>Replace if defective.</p>
5. Loose or broken wire #00 from battery (-) to Up valve coil 3H-14.	<p>Check continuity. Replace if defective.</p>
6. Defective up valve coil 3H-14.	<p>Check continuity through coil. Replace if defective.</p>

7. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	<p>Check machine limits and reduce weight as required.</p> <p>Check pressure transducer PT1 and angle transducer AT1 functionality.</p> <p>Check wire #60 from control module CM1 pin #P1-8 (overloaded signal).</p> <p>Test for 24V output voltage between wire #60 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P1-8 signal is present (pulsed).</p>
8. Machine not level.	<p>Move machine and ONLY use on level surface.</p> <p>Check control module CM1 display.</p>
9. Check machine tilt procedure .	<p>Check control module CM1 display screen and perform tilt calibration procedure ONLY if level has been checked and needs adjustment.</p>
10. External or internal fault detected by control module CM1	<p>Check control module display screen. Use diagnostic menu to see switch and sensor status.</p> <p>Correct trouble code as displayed. Replace module if defective.</p>

4.2-5 No down function from base control console

1. Control module CM1 display is broadcasting an error message.	<p>Check control module display screen and follow instructions to clear error.</p>
2. Open or defective lift/lower switch S2.	<p>Check switch.</p> <p>Check continuity between wire #10 and 13A on switch (Dn mode)</p> <p>Replace switch if no continuity when operating switch.</p>
3. Loose or broken wire #13A from lift/lower switch S2 to control module CM1 pin #P4-4 (Dn signal).	<p>Check continuity. Test for 24V input voltage between wire #13A and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P4-4 signal is present.</p> <p>Replace if defective.</p>
4. Loose or broken wire #13 from control module CM1 pin #P5-12 to holding valve coil 2H-13	<p>Check continuity. Test for 12V output voltage between wire #13 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P5-12 signal is present.</p> <p>Replace if defective.</p>
5. Loose or broken wire #00C from holding valve coil 2H-13 to control module CM1 pin #P2-8	<p>Check continuity. Replace if defective.</p>
6. Defective lift cylinder holding valve coil 2H-13	<p>Check continuity through coil. Replace if defective.</p>

- | | |
|--|--|
| 7. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing | <p>Check machine limits and reduce weight as required.</p> <p>Check pressure transducer PT1 and angle transducer AT1 functionality</p> <p>Check wire #60 from control module CM1 pin #P1-8 (overloaded signal)</p> <p>Test for 24V output voltage between wire #60 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P1-8 signal is present (pulsed).</p> |
| 8. External or internal fault detected by control module CM1 | <p>Check control module display screen. Use diagnostic menu to see switch and sensor status.</p> <p>Correct trouble code as displayed. Replace module if defective.</p> |

4.2-6 No emergency down function from base control console*



NOTE

*The circuit has redundant wiring and a multiple position (left - spring neutral center - right) emergency lowering toggle switch S51, which will allow function of lowering in either position from neutral center (see below scenarios).

- | | |
|---|--|
| 1. Loose or broken wire #98 from battery to circuit breaker CB2 or the circuit breaker is open. | Check continuity to circuit breaker. Test circuit breaker CB2. Replace if defective. |
| 2. Loose or broken wire #98A from circuit breaker CB2 to main disconnect S1. | Check continuity. Replace if defective. |
| 3. Main battery disconnect switch S1 open or defective. | Close switch. Check continuity. Replace if defective. |

Scenario A:

- *Emergency lowering toggle switch S51 held in “up” position (as per electrical schematic)

- | | |
|---|---|
| ▪ Loose or broken wire #98B from main disconnect S1 to emergency lowering switch S51. | Check continuity. Replace if defective. |
|---|---|

- | | |
|---|---|
| ▪ Loose or broken wire #05 from circuit breaker CB1 to emergency lowering switch S51. | Check continuity. Replace if defective. |
|---|---|

- | | |
|--|---|
| ▪ Open or defective emergency lowering switch S51. | <p>Check continuity between wire #98B and wire #00D on switch, and</p> <p>Check continuity between wire #05 and wire #13 on switch.</p> <p>Replace switch if no continuity on both of these two (2) contacts of switch.</p> |
|--|---|

Scenario B:

- *Emergency Lowering toggle switch S51 held in “down” position (as per electrical schematic)

▪ Loose or broken wire #00 from B- lug on control module CM1 to emergency lowering switch S51.	Check continuity. Replace if defective.
▪ Loose or broken wire #98B from main disconnect S1 to emergency lowering switch S51.	Check continuity. Replace if defective.
▪ Open or defective emergency lowering switch S51.	Check continuity between wire #00 and wire #00D on switch, and Check continuity between wire #98B and wire #13 on switch. Replace switch if no continuity on both of these two (2) contacts of switch
4. Loose or broken 2x wires #00D from emergency lowering switch S51 to Holding valve coil 2H-13.	Check continuity. Replace if defective.
5. Loose or broken 2x wires #13 from emergency lowering switch S51 to Holding valve coil 2H-13.	Check continuity. Replace if defective.
6. Loose or broken wire #00C from control module CM1 pin #P2-8 to Holding valve coil 2H-13.	Check continuity. Replace if defective.
7. Defective isolation diodes D00C, D13-1 and/ or D13-2 for redundant circuits for emergency lowering.	Check diodes and make sure connected securely. Replace if defective.
8. Defective lift cylinder holding valve coil 2H-13.	Check continuity through coil. Replace if defective.

4.2-7 All controls inoperative from platform control console

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #03A to circuit breaker CB1 or circuit breaker is open.	Check continuity to circuit breaker. Test circuit breaker CB1. Replace if defective.
3. Loose or broken wire #05 to base emergency stop switch S28.	Check continuity. Replace if defective.
4. Open or defective base emergency stop switch S28.	Close switch by pulling knob out and check switch. Check continuity between wire #05 and wire #05A. Replace switch if defective.
5. Incorrect selection of base key switch S10.	Check switch is on platform selection Operate and check switch.
6. Open or defective base key switch S10.	Check continuity between wire #05A and wire #07 on switch (platform mode selected). Replace if defective when operating switch.

7. Loose or broken wire #08C from base key switch S10 to control module CM1 pin #3-1 (enable signal).	<p>Check continuity. Test for 24V input voltage between wire #08C and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-1 signal is present.</p> <p>Replace if defective.</p>
8. Loose or broken wire #07 from base key switch S10 to platform emergency stop switch S4.	<p>Check continuity. Replace if defective.</p>
9. Open or defective platform emergency stop switch S4.	<p>Close switch by pulling knob out and check switch.</p> <p>Check continuity between wire #07 and wire #08.</p> <p>Replace switch if defective.</p>
10. Loose or broken wire #08 from platform emergency stop switch S4 to control module CM1 pin #P3-2. (platform signal)	<p>Check continuity. Test for 24V input voltage between wire #08 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-2 signal is present.</p> <p>Replace if defective.</p>
11. Loose or broken wire #08 from platform emergency stop switch S4 to lift/off/drive switch S3	<p>Check continuity. Replace if defective.</p>
12. Open or defective lift/off/drive switch S3.	<p>Check switch.</p> <p>Check continuity between wire #08 and wire #12 (drive mode selected).</p> <p>Check continuity between wire #08 and wire #09 (lift mode selected).</p> <p>Replace if no continuity when operating switch.</p>
13. Loose or broken wire #12 from lift/off/drive switch S3 to control module CM1 pin #P3-6 (drive signal).	<p>Check continuity. Test for 24V input voltage between wire #12 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-6 signal is present.</p> <p>Replace if defective.</p>
14. Loose or broken wire #09 from lift/off/drive switch S3 to control module CM1 pin #P3-7 (lift signal).	<p>Check continuity. Test for 24V input voltage between wire #09 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-7 signal is present.</p> <p>Replace if defective.</p>
15. Loose or broken wire #08 from platform emergency stop switch S4 to joystick S7.	<p>Check continuity. Replace if defective.</p>

16. Defective joystick switches S7-6 enable, S7-2 steer right and S7-3 steer left.	<p>Check switches.</p> <p>Check continuity between wire #08 and wire #08A (enable signal).</p> <p>Check continuity between wire #08 and wire #23 (steer right signal).</p> <p>Check continuity between wire #08 and wire #24 (steer left signal).</p> <p>Replace Joystick if no continuity when operating individual switches.</p>
17. Loose or broken wire #08A from joystick enable switch S7-6 to control module CM1 pin #P3-12 (enable signal).	<p>Check continuity. Test for 24V input voltage between wire #08A and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-12 signal is present.</p> <p>Replace if defective.</p>
18. Loose or broken wire #23 from joystick S7-2 to control module CM1 pin #P3-8 (steer right signal).	<p>Check continuity. Test for 24V input voltage between wire #23 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-8 signal is present.</p> <p>Replace if defective.</p>
19. Loose or broken wire #24 from joystick S7-3 to control module CM1 pin #P3-9 (steer left signal).	<p>Check continuity. Test for 24V input voltage between wire #24 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-9 signal is present.</p> <p>Replace if defective.</p>
20. Defective joystick S7 PCB.	<p>Check joystick.</p> <p>Replace joystick if defective.</p>
21. Loose or broken wire #00B from control module CM1 pin #P1-3 to joystick S7 (0V reference signal).	<p>Check continuity. Replace if defective.</p>
22. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2 (analog output signal).	<p>Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present.</p> <p>Replace if defective.</p>
23. Loose or broken wire #08B from joystick S7 to control module CM1 pin #P1-1 (5V input signal).	<p>Check continuity. Replace if defective.</p>
24. External or internal fault detected by control module CM1.	<p>Check control module display screen. Use diagnostic menu to see switch and sensor status.</p> <p>Correct trouble code as displayed. Replace module if defective.</p>

4.2-8 No up function from platform controls (ANSI/CSA, CE, and AS)

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #09 from lift/off/drive switch S3 to control module CM1 pin #P3-7.	Check continuity. Test for 24V input voltage between wire #09 and wire #00. Use HMI diagnostic menu to make sure input P3-7 signal is present. Replace if defective.
3. Lift//Off/Drive switch S3 is set to an incorrect mode.	Select Lift. Check switch. Replace if defective.
4. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2.	Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present. Replace if defective.
5. Loose or broken wire #14 from control module CM1 pin #P5-5 to Up valve coil 3H-14.	Check continuity. Test for 24V output voltage between wire #14 and wire #00. Use HMI diagnostic menu to make sure output P5-5 signal is present. Replace if defective.
6. Loose or broken wire #00 from battery (-) to Up valve coil 3H-14.	Check continuity. Replace if defective.
7. Defective up valve coil 3H-14.	Check continuity through coil. Replace if defective.
8. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	Check machine limits and reduce weight as required. Check pressure transducer PT1 and angle transducer AT1 functionality. Check wire #60 from control module CM1 pin #P1-8 (overloaded signal). Test for 24V output voltage between wire #60 and wire #00. Use HMI diagnostic menu to make sure Output P1-8 signal is present (pulsed).
9. Machine not level.	Move machine and ONLY use on level surface. Check control module CM1 display.
10. Check machine tilt procedure .	Check control module CM1 display screen and perform Tilt Calibration Procedure ONLY if level has been checked and needs adjustment.
11. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-9 No up function from platform controls (KC)

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #09 from lift/off/drive switch S3 to control module CM1 pin #P3-7.	Check continuity. Test for 24V input voltage between wire #09 and wire #00. Use HMI diagnostic menu to make sure input P3-7 signal is present. Replace if defective.
3. Lift//Off/Drive switch S3 is set to an incorrect mode.	Select Lift. Check switch. Replace if defective.
4. Loose or broken wire #08C from base key switch S10 to anti-overriding limit switch LS7B N.C contact.	Check continuity. Replace if defective.
5. Open or defective anti-overriding limit switch LS7B.	Check switch. Check continuity between wire #08C and wire #52A. N.C. contact on anti-overriding limit switch LS7B. Replace Limit switch if defective.
6. Loose or broken wire #52A from anti-overriding limit switch LS7B to anti-overriding limit switch LS7C (if equipped).	Check continuity. Replace if defective.
7. Open or defective anti-overriding limit switch LS7C (if equipped).	Check switch. Check continuity between wire #52A and wire #52B N.C. contact on anti-overriding limit switch LS7C. Replace limit switch if defective.
8. Loose or broken wire #52B from anti-overriding limit switch LS7C to anti-overriding limit switch LS7D (if equipped).	Check continuity. Replace if defective.
9. Open or defective anti-overriding limit switch LS7D (if equipped).	Check switch. Check continuity between wire #52B and wire #52A. N.C. contact on anti-overriding limit switch LS7D. Replace Limit switch if defective.
10. Loose or broken wire #52A from anti-overriding limit switch LS7D to anti-overriding limit switch LS7A.	Check continuity. Replace if defective.
11. Open or defective anti-overriding limit switch LS7A.	Check switch. Check continuity between wire #52A and wire #51. N.C. contact on anti-overriding limit switch LS7A Replace limit switch if defective.

12. Loose or broken wire #51 from anti-overriding limit switch LS7A to control module CM1 pin #P3-11.	<p>Check continuity to make sure input is high to signal limit switches are not jammed open.</p> <p>Test for 24V output voltage between wire #51 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P3-11 signal is present.</p> <p>Replace if defective.</p>
13. Closed or defective anti-overriding limit switches LS7A, LS7C, LS7D, and/or LS7B N.O contacts.	<p>Check switches.</p> <p>Check continuity between wire #08C and wire #51A. N.O. contacts on all limit switches for input to control module CM1 pin #P3-10 signaling one or more of the limit switches are jammed closed.</p> <p>Test for 24V output voltage between wire #51A and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P3-11 signal is NOT present.</p> <p>Replace limit switch or switches that are defective.</p>
14. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2.	<p>Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present.</p> <p>Replace if defective.</p>
15. Loose or broken wire #14 from control module CM1 pin #P5-5 to Up valve coil 3H-14.	<p>Check continuity. Test for 24V output voltage between wire #14 and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P5-5 signal is present.</p> <p>Replace if defective.</p>
16. Loose or broken wire #00 from battery (-) to Up valve coil 3H-14.	<p>Check continuity. Replace if defective.</p>
17. Defective up valve coil 3H-14.	<p>Check continuity through coil. Replace if defective.</p>
18. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	<p>Check machine limits and reduce weight as required.</p> <p>Check pressure transducer PT1 and angle transducer AT1 functionality.</p> <p>Check wire #60 from control module CM1 pin #P1-8 (overloaded signal).</p> <p>Test for 24V output voltage between wire #60 and wire #00.</p> <p>Use HMI diagnostic menu to make sure Output P1-8 signal is present (pulsed).</p>
19. Machine not level.	<p>Move machine and ONLY use on level surface.</p> <p>Check control module CM1 display.</p>

20. Check machine tilt procedure .	Check control module CM1 display screen and perform Tilt Calibration Procedure ONLY if level has been checked and needs adjustment.
21. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.
4.2-10 No down function from platform controls	
1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #09 from lift/off/drive switch S3 to control module CM1 pin #P3-7.	Check continuity. Test for 24V input voltage between wire #09 and wire #00. Use HMI diagnostic menu to make sure input P3-7 signal is present. Replace if defective.
3. Lift//Off/Drive switch S3 is set in an incorrect mode or is defective.	Select Lift. Check switch. Replace if defective.
4. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2.	Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present. Replace if defective.
5. Loose or broken wire #13 from control module CM1 pin #P5-12 to Holding valve coil 2H-13.	Check continuity. Test for 24V output voltage between wire #13 and wire #00. Use HMI diagnostic menu to make sure output P5-12 signal is present. Replace if defective.
6. Loose or broken wire #00C from Holding valve coil 2H-13 to control module CM1 pin #P2-8.	Check continuity. Replace if defective.
7. Defective Holding valve coil 2H-13.	Check continuity through coil. Replace if defective.
8. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	Check machine limits and reduce weight as required. Check pressure transducer PT1 and angle transducer AT1 functionality. Check wire #60 from control module CM1 pin #P1-8 (overloaded signal). Test for 24V output voltage between wire #60 and wire #00. Use HMI diagnostic menu to make sure Output P1-8 signal is present (pulsed).
9. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-11 Right steer inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Lift//Off/Drive switch S3 is set to an incorrect mode.	Select Drive. Check switch. Replace if defective.
3. Defective Right Steer switch S7-2.	Check switch. Check continuity between wire #08 and wire #23 on switch (right Steer signal). Replace switch if no continuity when operating switch.
4. Loose or broken wire #23 from right steer switch S7-2 to control module CM1 pin #P3-8.	Check continuity. Test for 24V input voltage between wire #23 and wire #00. Use HMI diagnostic menu to make sure input P3-8 signal is present. Replace if defective.
5. Loose or broken wire #23A from control module CM1 pin #P5-8 to Right Steer valve coil 4H-23A.	Check continuity. Test for 24V output voltage between wire #23A and wire #00. Use HMI diagnostic menu to make sure output P5-8 signal is present. Replace if defective.
6. Loose or broken wire #00 from battery (-) to right steer valve coil 4H-23A.	Check continuity. Replace if defective.
7. Defective right steer valve coil 4H-23A.	Check continuity through coil. Replace if defective.
8. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-12 Left steer inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Lift//off/drive switch S3 is set to an incorrect mode.	Select Drive. Check switch. Replace if defective.
3. Defective left steer switch S7-3.	Check switch. Check continuity between wire #08 and wire #24 on switch (left steer signal). Replace switch if no continuity when operating switch.

4. Loose or broken wire #24 from left steer switch S7-3 pin to control module CM1 pin #P3-9.	<p>Check continuity. Test for 24V input voltage between wire #24 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-9 signal is present.</p> <p>Replace if defective.</p>
5. Loose or broken wire #24A from control module CM1 pin #P5-6 to Left Steer valve coil 4H-24A.	<p>Check continuity. Test for 24V output voltage between wire #24A and wire #00.</p> <p>Use HMI diagnostic menu to make sure output P5-6 signal is present.</p> <p>Replace if defective.</p>
6. Loose or broken wire #00 from battery (-) to left steer valve coil 4H-24A.	<p>Check continuity. Replace if defective.</p>
7. Defective left steer valve coil 4H-24A.	<p>Check continuity through coil. Replace if defective.</p>
8. External or internal fault detected by control module CM1	<p>Check control module display screen. Use diagnostic menu to see switch and sensor status.</p> <p>Correct trouble code as displayed. Replace module if defective.</p>
4.2-13 Forward drive function inoperative	
1. Control module CM1 display is broadcasting an error message.	<p>Check control module display screen and follow instructions to clear error.</p>
2. Loose or broken wire #12 from lift/off/drive switch S3 to control module CM1 pin #P3-6.	<p>Check continuity. Test for 24V input voltage between wire #12 and wire #00.</p> <p>Use HMI diagnostic menu to make sure input P3-6 signal is present.</p> <p>Replace if defective.</p>
3. Lift//off/drive switch S3 is set in an incorrect mode or is defective.	<p>Select Drive. Check switch. Replace if defective.</p>
4. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2.	<p>Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present.</p> <p>Replace if defective.</p>
5. Defective joystick enable switch S7-6.	<p>Check switch.</p> <p>Check continuity between wire #08 and wire #08A on switch.</p> <p>Replace joystick if no continuity when operating switch.</p>
6. Defective joystick S7.	<p>Check joystick. Replace if defective.</p>
7. Loose or broken wire #00B from control module CM1 pin #P1-3 to joystick S7 (0V reference).	<p>Check continuity. Replace if defective.</p>

8. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2 (analog output signal).	Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present. Replace if defective.
9. Loose or broken wire #08B from control module CM1 pin #P1-1 to joystick S7 (5V supply).	Check continuity. Replace if defective.
10. Loose or broken wire #16 from control module CM1 pin #P5-2 to forward drive valve coil 4H-16.	Check continuity. Test for 24V output voltage between wire #16 and wire #00. Use HMI diagnostic menu to make sure output P5-2 signal is present. Replace if defective.
11. Loose or broken wire #00 from battery (-) to forward drive valve coil 4H-16	Check continuity. Replace if defective.
12. Loose or broken wire #17 from control module CM1 pin #P5-4 to Brake valve coil 3H-17.	Check continuity. Test for 24V output voltage between wire #17 and wire #00. Use HMI diagnostic menu to make sure output P5-4 signal is present. Replace if defective.
13. Loose or broken wire #00 from battery (-) to brake valve coil 3H-17	Check continuity. Replace if defective.
14. Defective forward drive valve coil 4H-16.	Check continuity through coil. Replace if defective.
15. Defective brake valve coil 3H-17.	Check continuity through coil. Replace if defective.
16. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-14 Reverse drive function inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #12 from lift/off/drive switch S3 to control module CM1 pin #P3-6.	Check continuity. Test for 24V input voltage between wire #12 and wire #00. Use HMI diagnostic menu to make sure input P3-6 signal is present. Replace if defective.
3. Lift/off/drive switch S3 is set in an incorrect mode or is defective.	Select drive. Check switch. Replace if defective.

4. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2.	Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present. Replace if defective.
5. Defective joystick enable switch S7-6.	Check switch. Check continuity between wire #08 and wire #08A on switch. Replace Joystick if no continuity when operating switch.
6. Defective joystick S7.	Check joystick. Replace if defective.
7. Loose or broken wire #00B from control module CM1 pin #P1-3 to joystick S7 (0V reference).	Check continuity. Replace if defective.
8. Loose or broken wire #59 from joystick S7 to control module CM1 pin #P1-2 (analog output signal).	Check continuity. Use HMI diagnostic menu to make sure proportional input P1-2 signal is present. Replace if defective.
9. Loose or broken wire #08B from control module CM1 pin #P1-1 to joystick S7 (5V supply).	Check continuity. Replace if defective.
10. Loose or broken wire #15 from control module CM1 pin #P5-3 to reverse drive valve coil 4H-15.	Check continuity. Test for 24V output voltage between wire #15 and wire #00. Use HMI diagnostic menu to make sure output P5-3 signal is present. Replace if defective.
11. Loose or broken wire #00 from battery (-) to reverse drive valve coil 4H-15	Check continuity. Replace if defective.
12. Loose or broken wire #17 from control module CM1 pin #P5-4 to brake valve coil 3H-17.	Check continuity. Test for 24V output voltage between wire #17 and wire #00. Use HMI diagnostic menu to make sure output P5-4 signal is present. Replace if defective.
13. Loose or broken wire #00 from battery (-) to brake valve coil 3H-17	Check continuity. Replace if defective.
14. Defective reverse drive valve coil 4H-15.	Check continuity through coil. Replace if defective.
15. Defective brake valve coil 3H-17.	Check continuity through coil. Replace if defective.
16. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-15 No drive or steer when platform elevated

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Pothole protection bars not fully lowered.	Clear obstructions. Repair as needed.
3. Loose or broken wire #910 from control module CM1 pin #P2-7 to pothole protection limit switch LS1.	Check continuity. Test for 24V output voltage between wire #910 and wire #902 at P6-4. Use HMI diagnostic menu to make sure output P2-7 supply is present. Replace if defective.
4. Defective pothole protection limit switch LS1.	Check switch. Check continuity between wire #910 and wire #72 at switch. Replace if no continuity when operating switch.
5. Loose or broken wire #72 from pothole protection limit switch LS1 to pothole protection limit switch LS2.	Check continuity. Replace if defective.
6. Defective pothole protection limit switch LS2.	Check switch. Check continuity between wire #72 and wire #71. Replace if no continuity when operating switch.
7. Loose or broken wire #71 from pothole protection limit switch LS2 to control module CM1 pin #P4-7.	Check continuity. Test for 24V input voltage between wire #71 and wire #00. Use HMI diagnostic menu to make sure input P4-7 signal is present. Replace if defective.
8. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.2-16 Pressure transducer PT1 inoperative

1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #910 from control module pin #P2-7 to B+ (pin 1) on pressure transducer PT1.	Check continuity. Test for 24V output voltage between wire #910 and wire #902 at P6-4. Use HMI diagnostic menu to make sure output P2-7 supply is present. Replace if defective.
3. Loose or broken wire #902 from control module pin #P2-3 to GND (pin 3) on pressure transducer PT1.	Check continuity. Replace if defective.

4. Loose or broken wire #60A from control module pin #P2-4 to SIG (pin2) on pressure transducer PT1	Check continuity. Use HMI diagnostic menu to make sure proportional input P2-4 signal is present. Replace if defective.
5. Defective pressure transducer PT1.	Check operation. Replace if defective.
6. External or internal fault detected by control module CM1	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.
4.2-17 Angle transducer AT1 inoperative	
1. Control module CM1 display is broadcasting an error message.	Check control module display screen and follow instructions to clear error.
2. Loose or broken wire #910 from control module CM1 pin #2-7 to B+ (pin 1) on angle transducer AT1.	Check continuity. Test for 24V output voltage between wire #910 and wire #902 at P6-4. Use HMI diagnostic menu to make sure output P2-7 supply is present. Replace if defective.
3. Loose or broken wire #902 from control module pin #P2-3 to GND (pin 2) on angle transducer AT1 .	Check continuity. Replace if defective.
4. Loose or broken wire #28 from control module pin #P2-2 to SIG (pin 3) on angle transducer AT1.	Check continuity. Use HMI diagnostic menu to make sure proportional input P2-2 signal is present. Replace if defective.
5. Loose or broken wire #28A from control module pin #P2-5 to SIG (pin 4) on angle transducer AT1.	Check continuity. Use HMI diagnostic menu to make sure proportional input P2-5 signal is present. Replace if defective.
6. Defective angle transducer AT1.	Check operation. Replace if defective.
7. External or internal fault detected by control module CM1.	Check control module display screen. Use diagnostic menu to see switch and sensor status. Correct trouble code as displayed. Replace module if defective.

4.3 Hydraulic system

4.3-1 All functions inoperative

1. Electric Motor DCM1 not engaged.	Refer to electrical troubleshooting.
2. Pump P1 defective.	Check system pressures and pump P1 functionality. Replace if defective.
3. Loose or missing orifice.	Check for missing orifice in main manifold. See main manifold diagram in Section 3 for location.

4.3-2 All system sluggish

1. System relief valve R1 defective or not adjusted properly.	Adjust valve. Replace if defective.
2. Hydraulic pump P1 worn.	Check system pressure and flow from pump P1. Replace if defective.

4.3-3 Platform drifts down

1. Defective or leaking lift cylinder(s) seals at the gland.	Replace if damaged. Note: There are no piston seals, just wear rings.
2. Combination of stuck or defective Holding valve 2H-13.	Check valves. Replace if defective.

4.3-4 Platform lifts slowly

1. Defective lift valve 3H-14.	Check valve. Replace if defective.
2. Lift relief valve R2 is set incorrectly.	Check pressures. Replace if defective.
3. Defective holding valve 2H-13.	Check holding valve 2H-13. Replace if defective.
4. Defective or plugged lift orifice O3.	Clean orifice. Replace if defective.

4.3-5 Platform does not lift

1. Defective Lift valve 3H-14.	Check valve. Replace if defective.
2. Hydraulic oil level too low.	Fully lower the platform. Fill hydraulic tank until fluid is at or slightly above the top mark on the sight glass.
3. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	Check machine limits and reduce weight as required. Refer to electrical troubleshooting.
4. Defective or plugged lift orifice O3.	Clean orifice. Replace if defective.
5. Leaking or defective lift cylinder C1.	Check cylinder(s). Replace if defective.

4.3-6 Platform will not lower

1. Defective lift valve 3H-14.	Check valve. Replace if defective.
2. Defective holding valve 2H-13.	Clean valve. Replace if defective.
3. Defective or plugged lift orifice O3.	Clean orifice. Replace if defective.
4. Machine overloaded and overload lights PL-1 and PL-2 on emergency stop buttons flashing.	Check machine limits and reduce weight as required. Refer to Electrical troubleshooting.

4.3-7 Platform drives slow

1. Free-wheeling valve V2 open or defective.	Close valve. Replace if defective.
2. Defective or plugged drive orifice O4.	Clean orifice. Replace if defective.
3. Defective counterbalance valve CB1.	Check valve. Replace if defective.
4. Drive Motors M1 and/or M2 defective.	Check motors. Replace if defective.

4.3-8 Platform will not drive in forward or reverse

1. Free-Wheeling valve V2 is open or defective.	Close valve. Replace if defective.
2. Brakes are not released.	Check brakes. Replace if defective.
3. Forward drive valve 4H-16 or Reverse Drive valve 4H-15 is defective.	Check valves. Replace if defective.
4. Defective or plugged drive orifice O4.	Clean orifice. Replace if defective.
5. Defective counter balance valve CB1	Check valve. Replace if defective.
6. Drive Motors M1 and/or M2 defective.	Check motors. Replace if defective.

4.3-9 Brake(s) will not release (pin brakes)

1. Brake release valve 3H-17 is defective.	Check valve. Replace if defective.
2. Defective or plugged brake orifice O5.	Check orifice. Replace if defective.
3. Leaking or defective brake cylinder.	Check cylinder. Replace or repair if defective.

4.3-10 Brake(s) will not release (wet brakes)

1. Brake release valve 3H-17 is defective.	Check valve. Replace if defective.
2. Brake override valve V1 is defective.	Check valve. Replace if defective.
3. Defective internal brake piston seals.	Check brake pack will maintain pressure. If pressure is not maintained replace seals.
4. Defective brakes BR1 and/or BR2.	Inspect wheel assembly. Repair and replace as necessary.

4.3-11 MEWP will not hold on a grade (wet brakes)

1. Worn or damaged brake(s).	Inspect brake discs for wear. Replace if worn or damaged.
2. Broken or damaged brake compression springs.	Check springs. Replace if defective.
3. Defective brakes BR1and/or BR2.	Inspect wheel assembly. Repair and replace as necessary.

4.3-12 Platform does not steer

1. Right Steer valve 4H-23A and/or Left Steer valve 4H-24A is defective.	Check valves. Replace if defective.
2. Steer cylinder C2 seal leaking.	Rebuild cylinder. Replace if damaged.
3. Steering cylinder orifice O1 and/or O2 is plugged.	Clean orifice. Replace if damaged.
4. Mechanical binding in kingpins.	Check for binding. Repair as needed.

Section 5 – Procedures

NOTE

The illustrations in this manual are for instructional purposes only. The models and components shown may appear somewhat different from those on your actual MEWP.

5.1 Safety and workmanship

Your safety, and that of others, is the first consideration when doing maintenance on equipment. Always be conscious of weight. Never attempt to move heavy parts without the aid of a mechanical device. Do not allow heavy objects to rest in an unstable position. When you raise a part of the equipment, make sure it has sufficient support.

Unless specifically noted otherwise, before beginning any procedure:

1. Park the MEWP on a firm, level surface. Fully lower the machine.
2. Push in the emergency stop buttons on the platform control console and the base control console.
3. Turn the off/platform/base key switch to the off position. Remove the key.
4. Turn the main power disconnect switch to the off position.

After you complete a procedure which involves the modification, adjustment, or replacement of a hydraulic or electrical component, do all of the function tests given in your unit's Operation Manual.

WARNING

Fall hazard. Use the three points of contact principle when you use the MEWP to enter or exit the platform. If you do not obey, there is a risk of death or serious injury.

WARNING

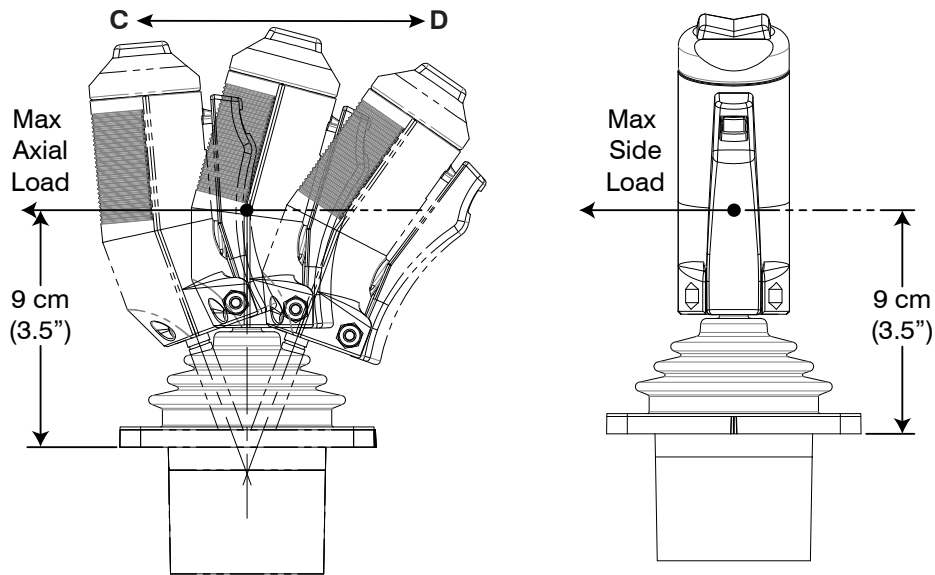
Do not operate the platform controls without the correct fall protection attached to the designated location in the platform. Failure to do so could result in death or serious injury!

WARNING

Make sure there are no people or obstructions in the test area, and there is sufficient space for the scissor and drive functions required for the given procedures.

5.2 Platform

5.2-1 Single axis joystick



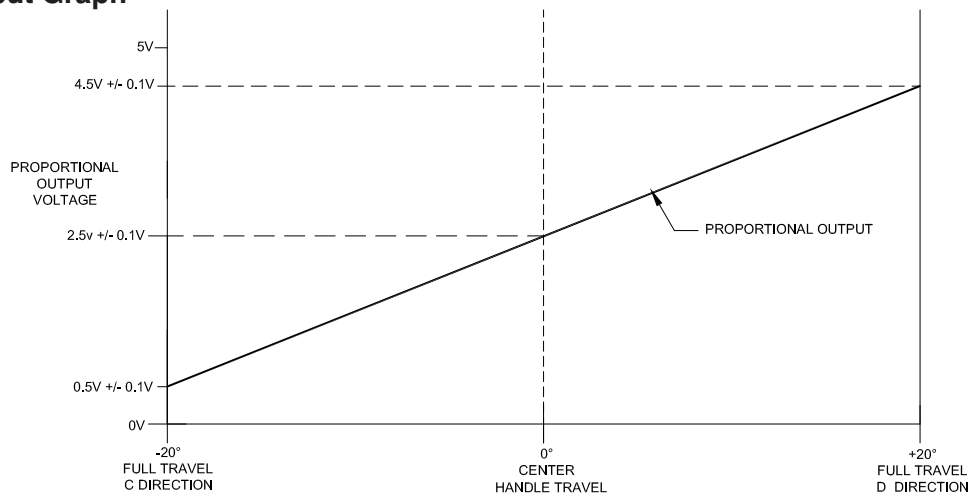
Joystick Switch Wiring

WIRE CHART		
COLOR	FUNCTION	PIN #
WHITE/RED	STEER LEFT	1
NONE	N/A	2
WHITE	STEER RIGHT	3
WHITE/BLUE	ENABLE TRIGGER	4
WHITE/BLACK	HANDLE COM (+24V)	5
GRAY	GROUND	6
BLUE	PROPORTIONAL OUTPUT	7
YELLOW	POWER (+5V)	8

Joystick Specifications

Input Voltages	5 V and 24 V
Center	2.4 V to 2.6 V
C DIR	0.5 V to 2.4 V
D DIR	2.6 V to 4.5 V
Operating Temperature	-40°C to 85°C
Storage Temperature	-40°C to 85°C
IP Rating	IP 57

Joystick Output Graph



5.2-2 Gate spring hinge adjustment

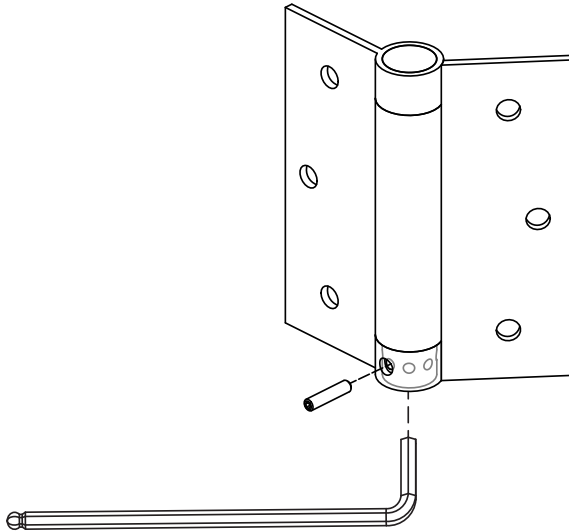
1. The tension of the spring hinges should be such that when you open the gate halfway and release it, it automatically closes and latches.
2. To adjust the tension of the spring hinges, first remove the safety locking screw from each hinge. Keep the screws for installation later.



NOTE

You need two hands to adjust the tension on the spring hinge.

3. To increase the tension, insert a 5/32" hex wrench in the screw socket. Turn the wrench clockwise until you get to the correct tension. Then if needed, turn it a small amount more to align the locking screw holes.
4. Hold the wrench in place and install the locking screw.
5. Release the wrench.

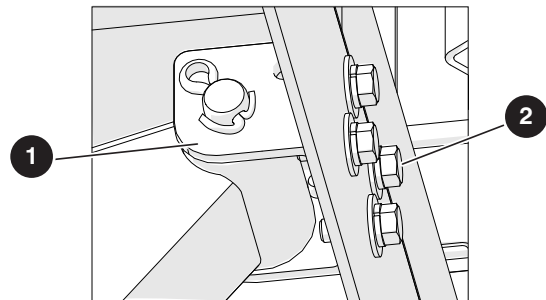
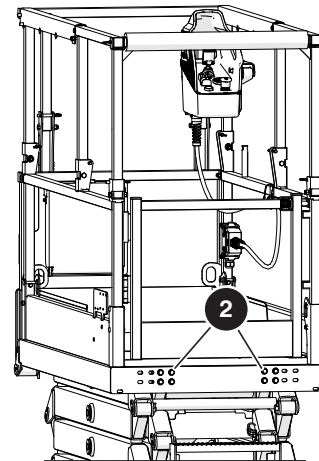


6. Adjust the tension on all of the hinges until the gate releases and latches from a half-open position.

5.2-3 Platform mounting hardware

If damage is found during an inspection of the platform mounting hardware, or following maintenance or repair of the platform mounting hardware and/or removal of the platform, you must:

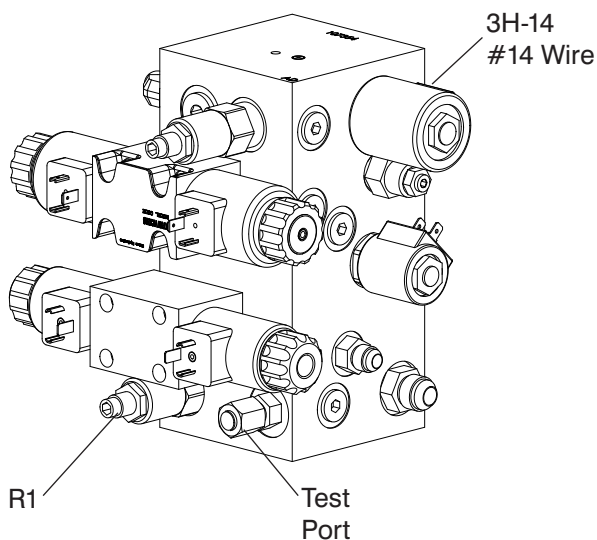
1. Inspect the platform, scissors, and the attachment area. Make sure you also do a check for damage to the threads on the scissor arm bracket **1**. Remove any debris, oils or grease from the threads.
2. Replace all of the platform mounting hardware **2** (bolts, flat washers, and spring washers) with new Skyjack-approved parts. Refer to the parts manual for the part numbers for your specific MEWP.
3. Apply a high-strength threadlocker (Loctite 270 or equivalent) to each bolt. Refer to the threadlocker manufacturer instructions for the specific requirements on its use.
4. Insert all of the bolts evenly. Then use a correctly calibrated torque wrench set to 41 Nm (30 ft-lb) to tighten each bolt. Use a smooth, even motion until an indication (audible click) is heard and felt.
5. When all of the bolts are torqued, repeat the tightening sequence to confirm the torque.



5.3 Base

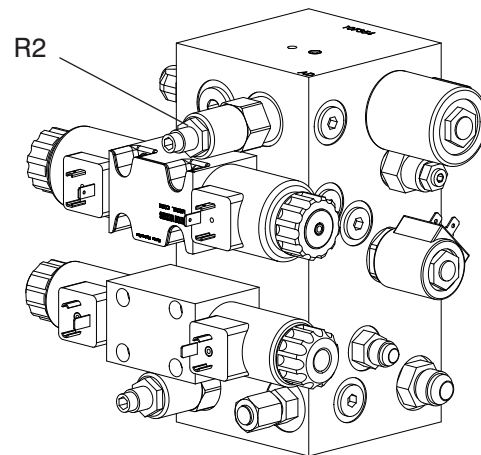
5.3-1 System relief pressure adjustment

1. Locate the system pressure fitting or quick disconnect port on the main manifold.
2. Install a calibrated 5000 psi gauge to the system pressure fitting or quick disconnect port.
3. At the main manifold, loosen the locknut on the system relief valve R1.
4. Remove the black #14 wire from the lift coil 3H-14.
5. Turn the base/off/platform key switch to the platform position.
6. Select lift with the lift/drive select switch on the platform control console.
7. Engage the lift function with the joystick and hold.
8. Observe the reading on the gauge. Adjust the R1 system relief value to the value listed on the serial number plate. Turning the stem on the relief valve clockwise increases the pressure. Turning the stem counterclockwise decreases the pressure.
9. Release the lift function and tighten the locknut.
10. Reconnect the #14 wire to the lift coil 3H-14.
11. Remove the gauge from system pressure test port.



5.3-2 Lift relief pressure adjustment

1. Lower the platform completely.
2. Load the platform with the capacity that is found on the machine's serial plate.
3. At the main manifold loosen the locknut on the lift relief valve R2.
4. Insert an Allen wrench in the stem of R2 and turn the valve stem out one turn.
5. Use the base controls to lift the platform and at the same time slowly turn the stem of R2 in until the scissor stack just starts to lift, then turn the valve in an additional $\frac{1}{2}$ turn. If you need to repeat the adjustment, lower the platform to the stowed position and repeat.
6. Fully lower the platform and make sure that it lifts the 100% capacity.
7. Tighten the locknut on the lift relief valve R2.



5.3-3 Replace the pothole compression rod

New compression rods must be adjusted to the correct height for the pothole protection system to work correctly.

If the compression rod is too long

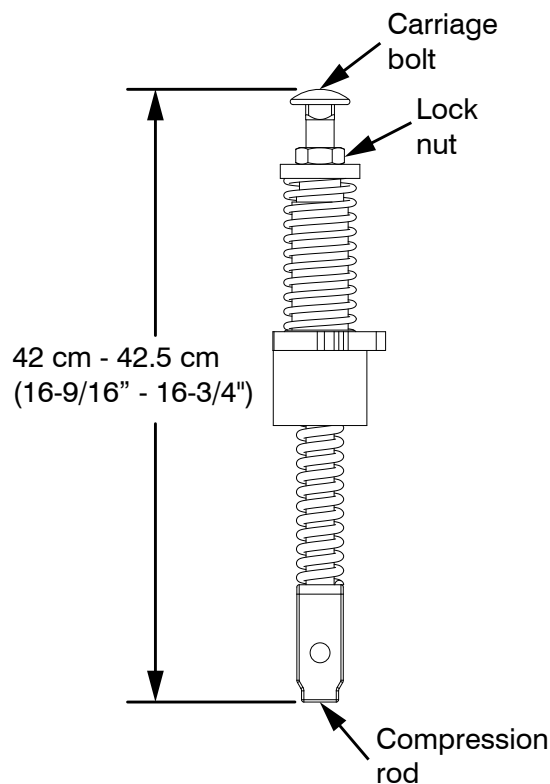
- There is a risk that the compression rod gets bent when the scissor stack lowers.
- The machine may not drive at all at certain heights, and the Skycoded display shows "POTHOLE - DRIVELOCKED!"

If the compression rod is too short

- The pothole bar will not fully retract.

Adjust the compression rod

1. Loosen the lock nut then adjust the carriage bolt until the overall length of the compression rod assembly matches the dimensions shown below.
2. The overall length is measured from the tip of the carriage bolt to the bottom of the compression rod.



3. Hold the carriage bolt in place and tighten the lock nut.
4. Do a final check of the overall length and make sure it is still correct.

Test the compression rod

1. Raise the platform to the approximate height shown below and try to drive the MEWP:
 - SJ3215/19 - 2.2 m to 2.8 m (7' 4" to 9' 2")
2. If the MEWP does not drive and the Skycoded display shows "POTHOLE - DRIVELOCKED!", make sure the overall length of the compression rods is correct, and the pothole limit switches are installed correctly. Refer to [5.3-4 Replace and adjust the pothole limit switches \(LS1 battery tray side & LS2 hydraulic tray side\)](#).

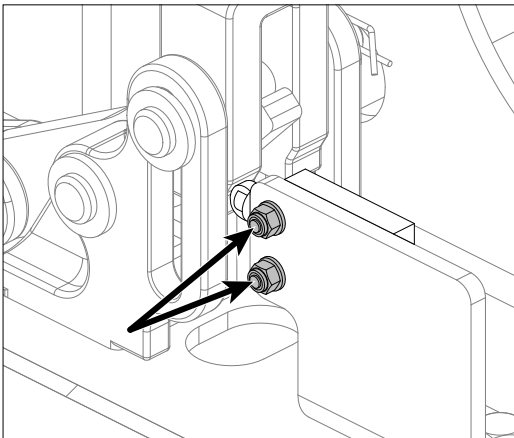
5.3-4 Replace and adjust the pothole limit switches (LS1 battery tray side & LS2 hydraulic tray side)

Machine preparation

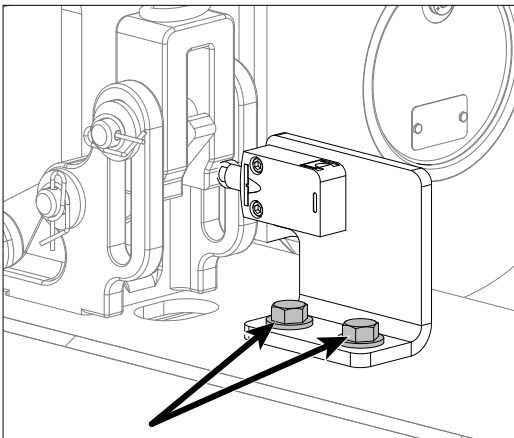
1. Park the MEWP on a firm level surface.
2. Chock or block the wheels so the MEWP does not roll forward or backward.

Remove the limit switches

1. Raise the platform until the pothole bars are deployed.
2. Swing out the hydraulic tray and the battery tray to gain access to the pothole limit switches below the base.
3. Remove the bolts, washers and nuts (x 2) that secure the limit switches to the pothole lock plates. Set the hardware aside.



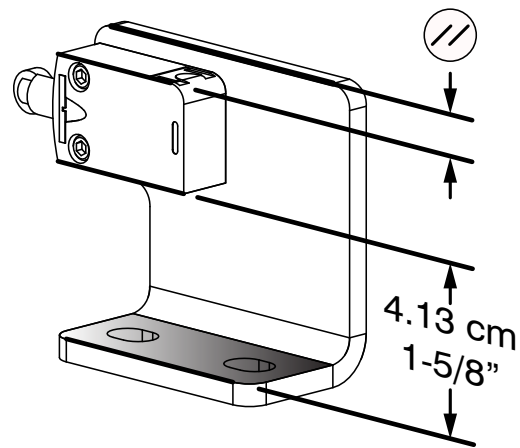
4. Remove the bolts and washers (x 2) that secure the lock plates to the base. Set the hardware aside.



5. Remove the limit switches and free the limit switch cables. Cut tie wraps as necessary.
6. Follow the cable into the main harness.
7. Disconnect the limit switch wires from the main harness. Discard the limit switches.

Replace the limit switches

1. Install the new limit switches (210227 for the battery tray and 210226 for the hydraulic tray) on the lock plates using the hardware removed earlier.
2. Make sure the distance between bottom of the limit switches and the top surface of the lock plates is 4.13 cm (1-5/8").



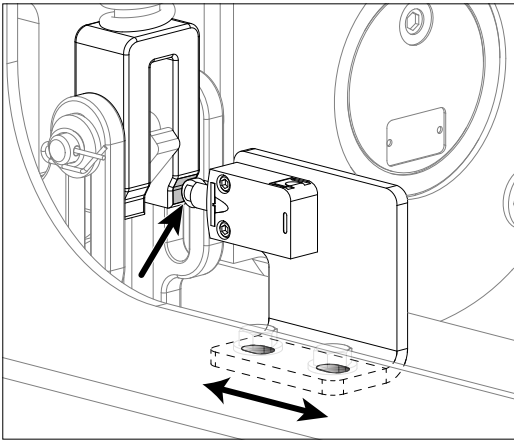
3. Make sure the limit switches are parallel with the edge of the lock plates.
4. Tighten the hardware on the limit switches.
5. Loosely install the lock plates onto the base using the hardware removed earlier.

Connect the limit switch wires

1. Route the new limit switch cables along the same path as the old ones to the main harness. Use tie wraps to secure the cables at regular intervals.
2. Plug the spade connectors into the same wire numbers. The #72 wires from each limit switch connect to each other. The #71 and #901 wires from the limit switches connect to the respective wires on the main harness.

Adjust the limit switches

1. Make sure the platform is still raised. Then use the slotted holes in the lock plates to move the plates back and forth until the limit switch plungers are barely touching the compression rods. Make sure the plungers are not pushed in.



2. Tighten the hardware to secure the lock plates to the base. Make sure the limit switches do not move while you tighten the bolts, and the retaining pins of the plunger roller are fully visible.

Test the limit switches

1. Place a block, approximately 3.75 cm (1-1/2") high, under the hydraulic tray.
2. Raise the platform approximately 2 to 3 m (7' to 10') until the pothole protection limit switches are activated.
3. Select the "Diagnostics" menu on the display module.
4. Scroll to the "Inputs" menu.
5. Scroll to P4-7 to observe the pothole limit switch status. Make sure the I/O is correct.
 - OFF when the pothole protection is on a block
 - ON when the pothole protection is fully lowered.
6. Attempt to drive forward or reverse. The MEWP should not move forward or backward when the pothole protection bar is on a block.

5.3-5 Pothole bar replacement/removal for servicing

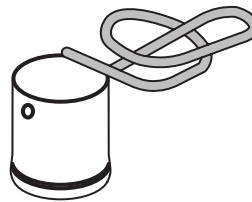
Prepare the machine

1. Make sure the MEWP is on firm, level ground.
2. Chock or block the wheels to keep the MEWP from rolling forward or backward.

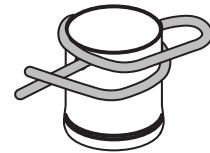
Tools necessary

- Needle nose pliers

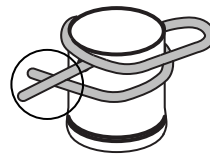
How to install or remove a Rue Ring



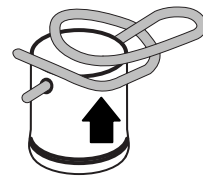
Install into
hole



Automatic
lock



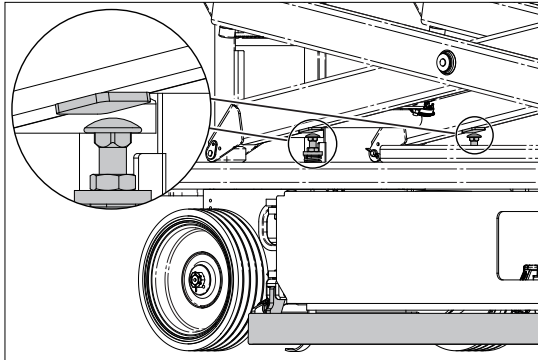
Optional
manual lock



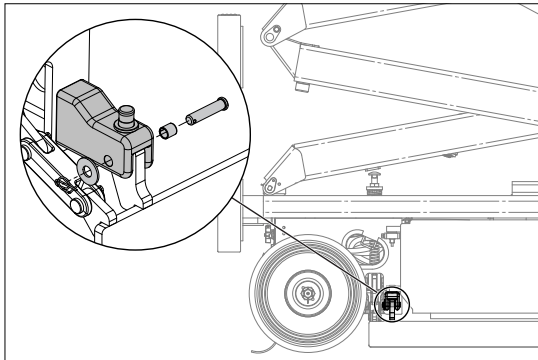
Push up and
back to remove

Installation instructions

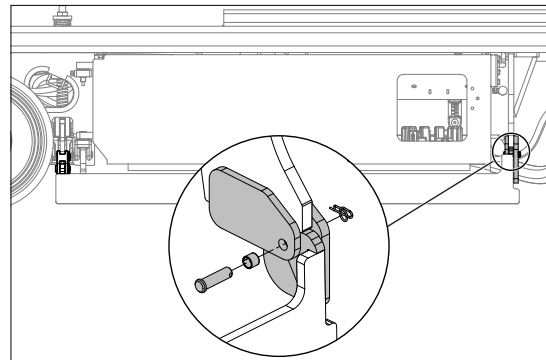
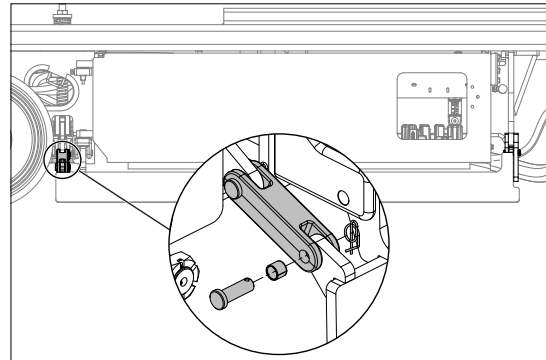
1. Raise the scissor stack until the pothole bars are deployed and there is no tension on either pothole plunger.



2. Remove the rue ring cotter pins and hardware that connect the pothole bar to the hydraulic and battery tray. Keep the pins and hardware.
3. Make sure the bushing is secured. Do an inspection on the bushing for excessive wear. Replace it if necessary.



4. Pull the pothole bar to allow access to the next rue ring cotter pin.
5. Remove the pins and hardware that connect the pothole bar to the pivot point from the pothole protection assembly and base weldment. Keep the pins and hardware.



6. Remove and discard the old pothole bar, if you plan to replace it.
7. Install a new pothole bar.
8. Install the pins and hardware in the pivot points on the pothole assembly and base.

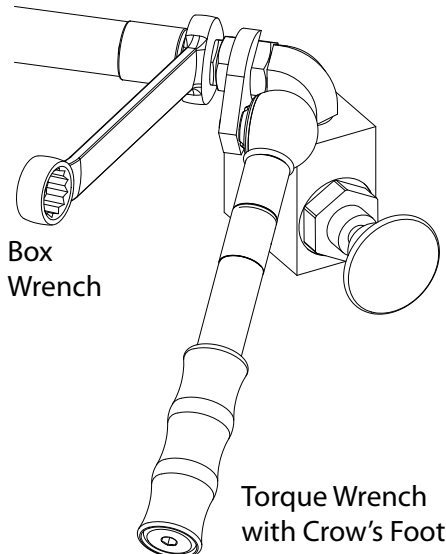
Test the pothole bars

1. Raise and lower the scissor stack a few times to make sure the pothole bars deploy correctly.

5.3-6 Tightening and torque recommendations for hydraulic couplings and hoses

General work practices

1. All components must be free of damage or contamination. O-rings cannot be reused anytime the component has been installed beyond finger tight. Clean or replace components, as required.
2. Over-tightening a coupling may result in overstressing and/or cracking, and may lead to leaking or failure.
3. When tightening hose couplings, make sure the hose does not twist on the adapter. Twisting will shorten the hose life and scar the sealing surfaces of swivel type couplings (JIC, 45°, etc.), which can create leaks.
4. When tightening hose couplings, use a torque wrench (with a crow's foot) on the hose end hex swivel nut, and a standard box wrench on the hose end stem hex to hold the hose from twisting.



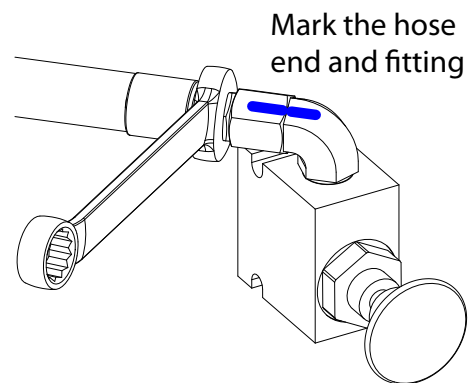
5. Lubricate all o-ring surfaces with suitable hydraulic oil prior to installation in the flange head and o-ring seal grooves. This will minimize the possibility of damage to the o-ring when installed.
6. Install 45° and 90° hydraulic hose ends first, then align the direction and tighten. Adjust the swivel nut on the straight hose end before tightening to create the desired flow.

Torquing using a torque wrench

1. This method applies to JIC (37°) and FFOR (flat face o-ring) hose ends and fittings, when the components are accessible with a torque wrench and crow's foot tools.
2. Align the hose end or fitting to the mating component.
3. Install the nut two or three turns by hand to make sure the alignment is correct. Jiggle the hose while tightening it to make sure the faces contact fully.
4. Using a correctly calibrated torque wrench, tighten the coupling using a smooth, even motion until an indication (audible click) is heard and felt. Do NOT over tighten it. For the recommended torque values, refer to [2.4 Torque specifications for hydraulic couplings & hoses](#).
5. Apply a drop of torque seal to the connection.

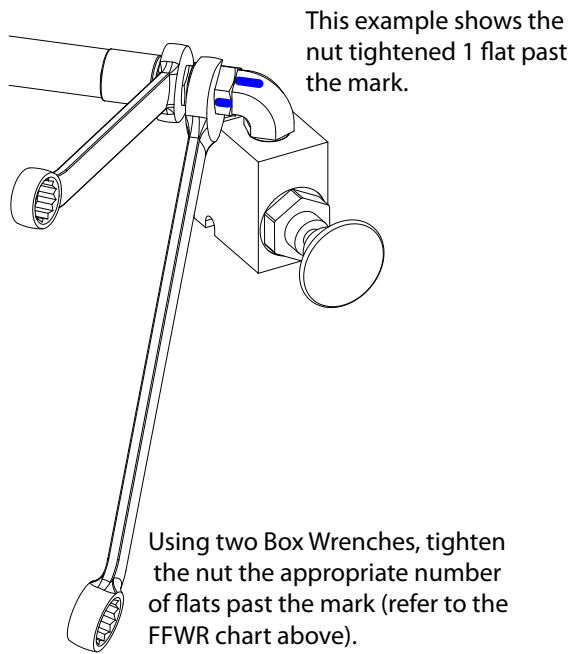
Torquing using the flats from wrench resistance method

1. This method applies to JIC (37°) and FFOR (flat face o-ring) hose ends only, when the components are not accessible with a torque wrench or crow's foot tools, or when a correctly calibrated torque wrench is not available.
2. Align the hose end or fitting to the mating component.
3. Install the swivel hose end nut hand tight to the fitting to make sure the alignment is correct. Jiggle the hose while tightening it to make sure the faces contact fully.
4. Tighten the nut using a box wrench until minor resistance is felt.
5. Note the position of the nut relative to the fitting with a marking device (i.e., paint marker).



- Referencing the chart below, use a second box wrench to tighten the nut the appropriate number of flats past the mark. Do NOT over tighten it.

FLATS FROM WRENCH RESISTANCE CHART for JIC Hose Ends			
Size		FFWR	
Dash	Frac. (in.)	37° Tube Nut	Swivel Nut
-4	1/4"	2	1.5
-5	5/16"	2	2
-6	3/8"	1.5	1.5
-8	1/2"	1.5	1.25
-10	5/8"	1.5	-
-12	3/4"	1.25	-
-16	1"	1	-
-20	1 1/4"	1	-
-24	1 1/2"	1	-
-32	2"	1	-



- Apply a drop of torque seal to the connection.

5.3-7 Integrated hub wheel removal and installation

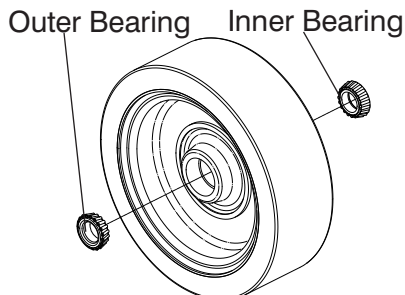
Tools needed

- Adjustable torque wrench capacity 203 Nm (150 ft-lb)
- Hub puller

Grease application - new rear wheels with pin brakes only (if required)

Model	Recommended Grease Type
SJ3215, SJ3219	STARPLEX EP2
	UNIUREX EP2
	SHELL GADUS S2

If the bearings are provided separately, you must coat them in grease before you install them on the front wheels.



Front side shown

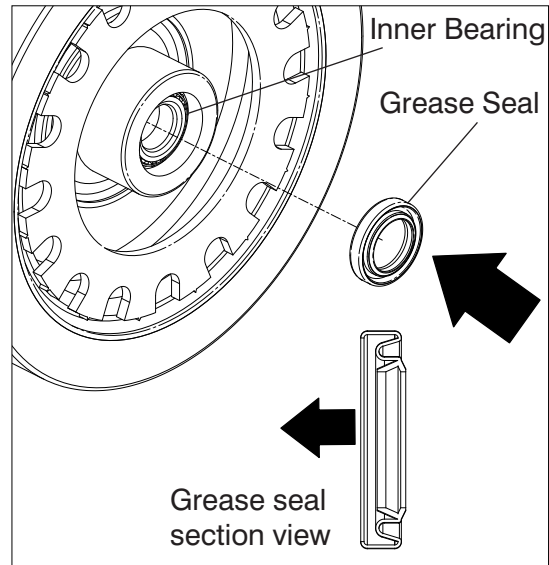
8. Thoroughly clean the bearings using solvent, and allow them to dry.
9. Completely coat the inner and outer bearings with grease. Be careful not to contaminate the grease. This could cause internal damage and shorten the life span of the bearings. Contaminants include dust, dirt, sand, water or other foreign particles.
10. Install the inner and outer bearings. The grease should allow the bearings to stick to the bearing cups inside the wheel assembly.



NOTE

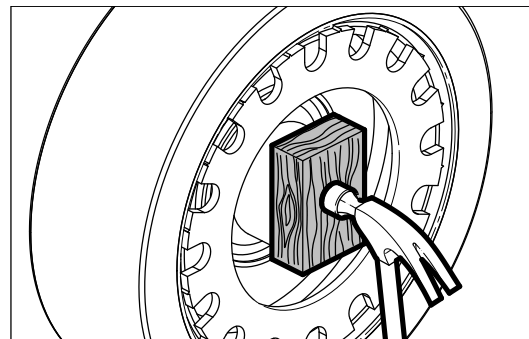
The inner bearing has a larger diameter than the outer bearing. Make sure you install the bearings with the tapered end in first.

11. From the back side of the wheel, place the grease seal on the hub with the tapered end facing inwards.



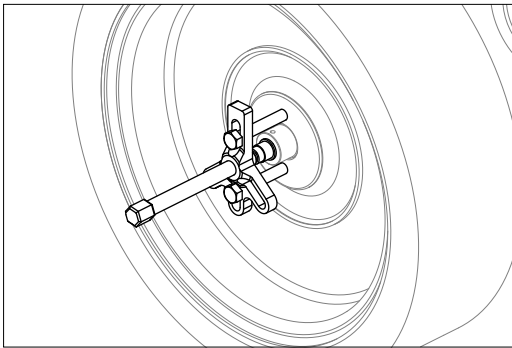
Rear side shown

12. Lightly tap the grease seal into place using a hammer, protecting the grease seal with a flat piece of wood.

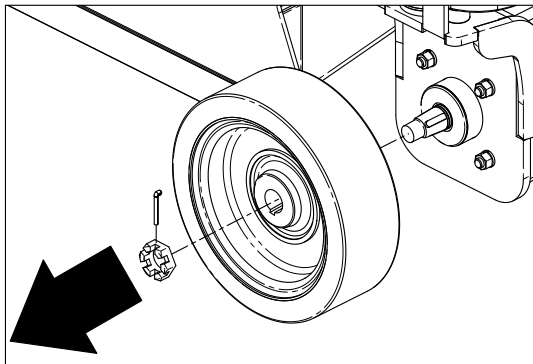


Integrated hub wheel removal

1. Use an appropriately rated lifting device to raise the MEWP until all the wheels are off the ground. Set the MEWP on stands sufficiently rated to support the weight of the machine.
2. Remove and set aside the wheel motor nut or castle nut.
3. Remove and discard the locktooth washer or cotter pin. A new one is required to reinstall the integrated hub wheel.
4. Use two 3/8"-24 bolts with a hub puller to remove the wheel.

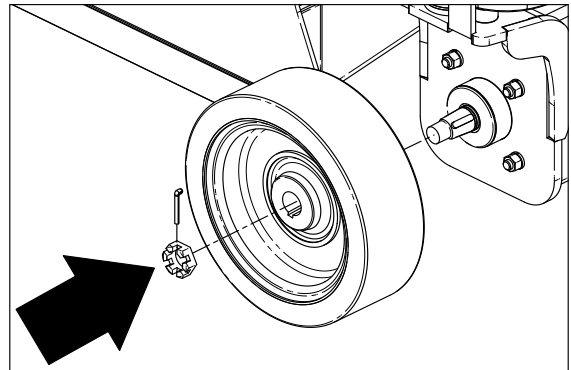


5. Use a hub puller to remove and discard the hub/integrated hub wheel from the wheel motor or brake.

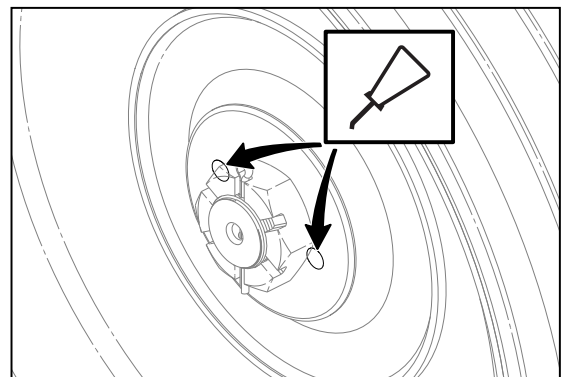


Front integrated hub wheel installation

1. Install the integrated hub wheel onto the spindle.
2. Install the castle nut. Finger tighten the nut.
3. Tighten the castle nut to 203 Nm (150 ft-lb).
4. Insert a 1/8" x 1-1/2" cotter pin.
5. If the holes do not align to install the cotter pin, continue to torque the castle nut clockwise until the next hole is visible.
6. Make sure the cotter pin is pushed in completely.
7. Bend the ends of the cotter pin to secure the castle nut.



8. To limit rust bleed, apply a few drops of grease to the two small tapped holes on the front wheels.



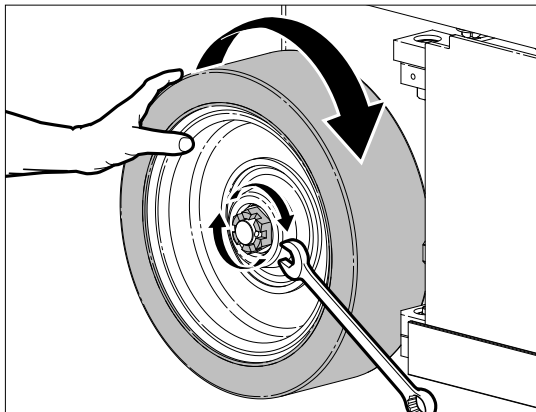
Rear integrated hub wheel installation - pin brakes

1. Install the integrated hub wheel onto the spindle.
2. Install the castle nut and the flat washer. Finger tighten the nut.
3. Use a wrench to manually disengage the pin brakes on both sides. This will allow you to rotate the wheel.
4. Rotate the wheel slowly while tightening the castle nut to approximately 68 Nm (50 ft-lb). This is to seat all the bearings in the wheel assembly.



NOTE

Do not over-torque the castle nut as it reduces the bearing life.



5. Loosen the castle nut to remove the torque. Do not rotate the wheel.
6. Finger tighten the castle nut until it is snug.

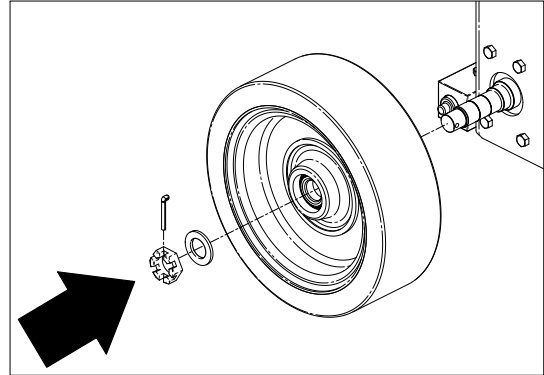


NOTE

The castle nut should be free to rotate, with the only restraint being the cotter pin.

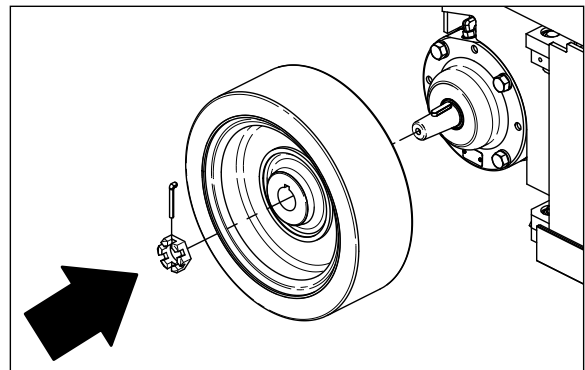
7. Use a wrench to reengage the pin brakes on both sides. Do not lower the machine while the pin brakes are disengaged.
8. Turn the castle nut back slightly until the next cotter pin hole is visible on the spindle.
9. Install a 1/8" x 1-1/2" cotter pin. Make sure the cotter pin is pushed in completely to allow the dust cap to fit.

10. Bend the ends of the cotter pin to secure the castle nut.
11. Install the dust cap over the castle nut. Be sure not to damage the castle nut while installing the dust cap.



Rear integrated hub wheel installation - wet brakes

1. Install the integrated hub wheel onto the spindle.
2. Install a 1" castle nut onto the brake.
3. Tighten the castle nut to 203 Nm (150 ft-lb).
4. Insert a 1/8" x 1-1/2" cotter pin.
5. If the holes do not align to install the cotter pin, continue to torque the castle nut clockwise until the next hole is visible.
6. Make sure the cotter pin is pushed in completely.
7. Bend the ends of the cotter pin to secure the castle nut.



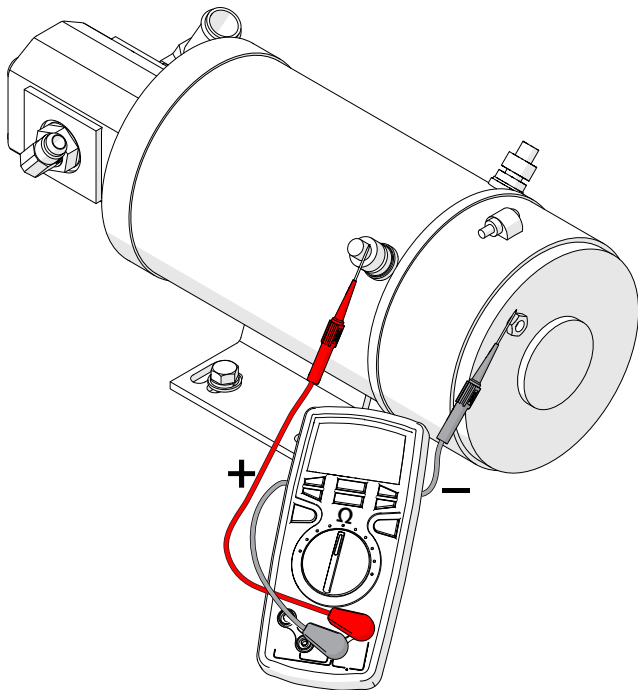
5.3-8 Test the DC motor

1. Turn the main power disconnect switch to the off position.
2. Open the hydraulic tray and locate the motor.
3. Sand the surface of the nut at the end of the motor case to provide a good connection for a multimeter.
4. Set a multimeter to ohms Ω .
5. Place the positive lead on the motor's **negative** input. Place the negative lead on the bolt that was sanded.

Result:

- Good=open line (OL) or any ohms value with "M" or "K", showing a weak connection.
- Bad=any ohms value below 1k, or direct continuity.

Solution: clean, rebuild or replace the DC motor.

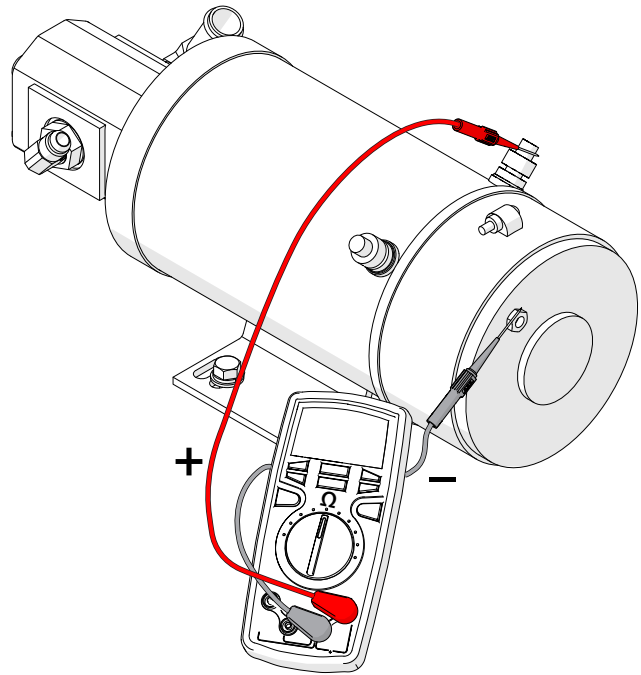


6. Repeat step 5 with the positive lead on the motor's **positive** input. Place the negative lead on the nut that was sanded.

Result:

- Good=open line (OL) or any ohms value with "M" or "K", showing a weak connection.
- Bad=any ohms value below 1k, or direct continuity.

Solution: clean, rebuild or replace the DC motor.

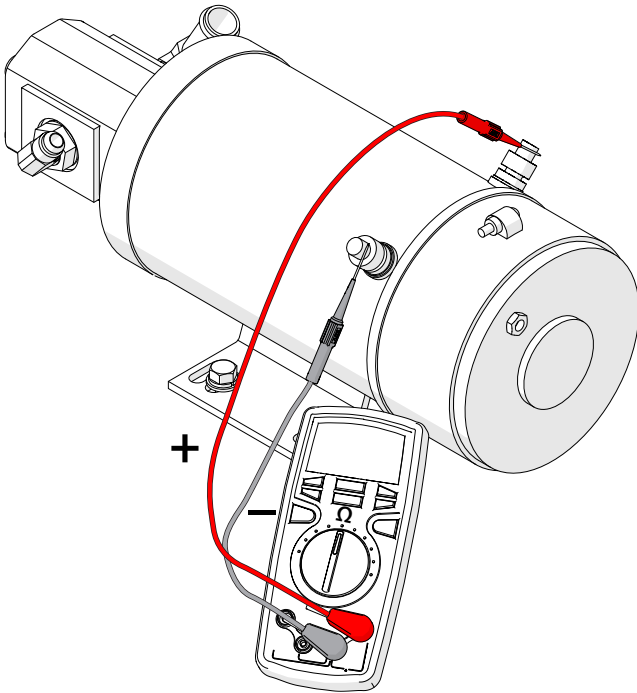


- Place the positive lead on the motor's positive input. Place the negative lead on the motor's negative input.

Result:

- Good=good connection or any ohms value below 10 ohms.
- Bad=open line (OL) or any ohms value with "M" or "K", showing a weak connection.

Solution: clean, rebuild or replace the DC motor.



5.4 Battery Charger

5.4-1 Battery service

⚠ WARNING

Explosion hazard. Keep flames and sparks away. Do not smoke near the batteries. Battery acid releases explosive gas while charging. Charge the batteries in a well-ventilated area.

⚠ WARNING

Battery acid is extremely corrosive – wear proper eye and facial protection as well as appropriate protective clothing. If contact occurs, immediately flush with cold water and seek medical attention.

1. Turn the main power disconnect switch to the off position.
2. Check the battery case for damage.
3. Check the battery fluid level in each battery. If the plates are not covered by at least 13 mm (1/2") of solution, add distilled or demineralized water.
4. Make sure all the battery connections are tight.

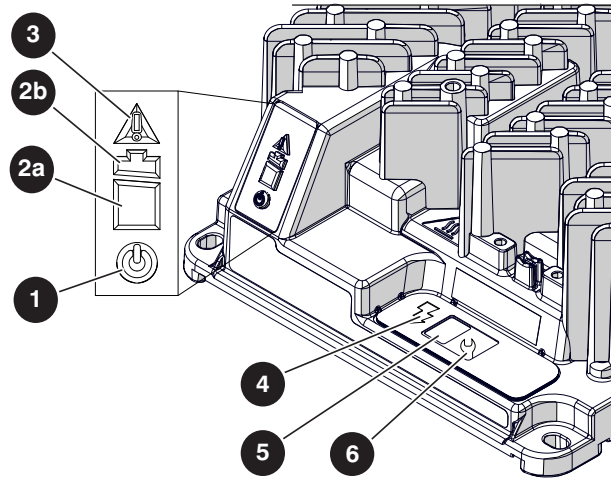
NOTE

Do not use any batteries other than the flooded lead-acid batteries of the proper Ah rating.

⚠ WARNING

Use the original or equivalent to the original parts and components for the MEWP.

5.4-2 Charger maintenance



No.	Indicator type	Condition	Description
1	AC power	Blue	Battery charger is connected to the AC power.
2a	Battery charge <80%	Green flash	Low charge — continue to charge.
		Solid green	High charge — continue to charge.
2b	Battery charge >80%	Green flash	High charge — continue to charge or stop the charge.
		Solid green	Charge complete — stop the charge.
3	Fault/error	Solid red	Charger fault — refer to the service manual.
		Amber flash	Error found — refer to the service manual.
4	Charge output	Solid yellow	Charger output is on.
5	Charge profile/error display	Algorithm or fault/error code	N/A.
6	Select charge profile	Charge algorithm	N/A.

5.4-3 Charger profiles

IMPORTANT

Charger profiles differ depending on the battery type and manufacturer. Only use charger profiles with the batteries they were designed for. The use of other incompatible batteries may cause poor charging performance and decreased battery health.

1. Place the charger near a power outlet, but leave it unplugged.
2. Find your battery type in the following chart, and make a note of the profile number (starting with P).
3. Press and hold the Select Charger Profile button (wrench icon) on the Delta-Q charger. You will hear a small click when you press the button.
4. Continue to hold the Select Charger Profile button, and connect the charger to a power outlet.

5. Continue to hold the button for approximately 10 seconds or until the Error Indicator turns orange and the Battery Charging Indicator starts flashing green.
6. The current charger profile displays up to three times.



NOTE

The process times out and the profile remains unchanged if there are 15 seconds of inactivity, or if the charging profile is allowed to display three times.

7. Press and release the button to scroll through the charging profiles.
8. Select a profile, and press and hold the button for 10 seconds or until the Error Indicator and Battery Charging Indicator lights turn off.
9. Press the button again to confirm the selected profile.
10. Disconnect the charger from the power outlet.

Battery Brand	Compatible with	Profiles
U.S. Battery - US 2200 XC/XC2 Flooded, 6V, 232 Ah	200 - 255 Ah flooded	#11 (P-0-1-1)
Discover Energy - EVGC6A-A AGM, 6V, 220 Ah	220 - 400 Ah AGM	#43 (P-0-4-3)
Discover Energy - EV12A-A AGM, 12V, 140 Ah*		
U.S. Battery - US 12V XC2 Flooded, 12V, 155 Ah*	330 - 425 Ah flooded	#73 (P-0-7-3)
U.S. Battery - US 250 XC/XC2 Flooded-lead, 6V, 255 Ah		
Trojan - T105 ELPT Flooded, 6V, 225 Ah	150 - 250 Ah 6V, 8V, 12V flooded	#3 (P-0-0-3)

*The batteries used for these charger profiles are connected in a series-parallel circuit.

5.4-4 Charger troubleshooting

The IC Series charger is continuously monitoring itself and its environment for unusual conditions. There are a few indications that may require the attention of the user.

Symptom	Recommended Action
No Indicator Lights	Check AC voltage and connection to wall power.
Only Blue AC Light On	Charger is connected to AC and is waiting for a battery to be connected, or for CAN remote control commands. Battery voltage must rise over 0.1V/cell before charging will begin. Some charging algorithms require a higher battery voltage to begin.
Solid Red Fault/Error Indicator	Read fault code (e.g., F-0-0-1) number on the Charge Algorithm/Error Display and refer to the fault code table.
Flashing Amber Fault/Error Indicator	Read error code (e.g., E-0-0-1) number on the Charge Algorithm/Error Display and refer to the error code table.

5.4-5 Charger fault codes

Fault Code	Description	Troubleshooting/Customer Actions
F-0-0-1	DC-DC Failure: LLC excessive leakage fault.	Internal charger fault. Disconnect AC and battery from charger for a minimum of 30 seconds. If it fails again, contact Skyjack service.
F-0-0-2	Power Factor Correction (PFC) Failure: PFC excessive leakage fault.	
F-0-0-3	PFC has taken too long to boost.	
F-0-0-4	The charger has been unable to calibrate the current offset.	
F-0-0-5	The voltage drop across the DC relay is too high while the relay is closed.	
F-0-0-6	Large difference between internal DC-DC and battery sense currents.	

5.4-6 Charger error codes

Fault Code	Description	Troubleshooting/Customer Actions
E-0-0-1	Battery voltage over limit in software. Typically 2.5V/cell. At the start of a charger cycle only and only for lead acid batteries. It is acceptable for the voltage to go above this during charging and when charging Lithium batteries.	<ul style="list-style-type: none"> ▪ Check the battery voltage and cable connections. ▪ Check charger voltage model is appropriate for batteries. ▪ This error automatically clears once the condition has been corrected.
E-0-0-2	Battery voltage too low to start a charge cycle. Algorithm dependent. Typically 0.1V/cell.	<ul style="list-style-type: none"> ▪ Check the battery voltage and cable connections. ▪ Check the charger is the correct voltage for the batteries it is connected to. ▪ Check battery size and condition. Batteries may be overdischarged. Use another charger to bring the batteries above the minimum voltage. ▪ This error automatically clears once the condition has been corrected.
E-0-0-3	Charge time limit reached. Algorithm dependent.	<ul style="list-style-type: none"> ▪ Charger output reduced due to high temperatures. Operate at lower ambient temperature. ▪ Charger output reduced due to low AC voltages. Check AC voltages. ▪ Check for shorted or damaged cells. ▪ Poor battery health. Replace the battery. ▪ Batteries too large for the charger. Replace batteries. ▪ Very deeply discharged battery. Retry charge. ▪ Battery connections are loose or corroded. Check connections. ▪ Extra loads. Turn off other devices running on the battery ▪ This error automatically clears once the charger is reset by cycling DC or by loss of AC for over 10 minutes.
E-0-0-4	Battery could not be trickle charged up to the minimum voltage. May also be used for other battery-related errors depending on the algorithm.	<ul style="list-style-type: none"> ▪ Check for shorted or damaged cells. ▪ Poor battery health. Replace the battery. ▪ Check DC connections. ▪ May be caused because of output reduced due to high temperature. ▪ Some new batteries may trigger these alarms as there voltage dips ▪ when charging starts before it goes onto rise.
E-0-0-7	Charge amp-hour Limit reached. Algorithm dependent.	<ul style="list-style-type: none"> ▪ Charger output reduced due to high temperatures. Operate at lower ambient temperature ▪ Charger output reduced due to low AC voltages. Check AC voltage. ▪ Check for shorted or damaged cells. ▪ Poor battery health. Replace the battery. ▪ Very deeply discharged battery. Retry charge. ▪ Battery connections are loose or corroded. Check connections. ▪ Extra loads. Turn off other devices running on the battery ▪ This error automatically clears once the charger is reset by cycling ▪ DC or by loss of AC for over 10 minutes.

E-0-0-8	Battery temperature out of range. Algorithm dependent.	<ul style="list-style-type: none"> ▪ Cool or warm batteries as needed. ▪ Check temperature sensor and connections. ▪ This error automatically clears once the condition has been corrected.
E-0-1-1	Charge disabled by external command	<ul style="list-style-type: none"> ▪ Charger has been disabled by an external controller over the CANbus network. ▪ This error automatically clears once the command has been removed.
E-0-1-2	Reverse polarity	<ul style="list-style-type: none"> ▪ Battery is connected the wrong way around. Check the battery connections. ▪ This error automatically clears once the condition has been corrected.
E-0-1-3	Battery does not take current	<ul style="list-style-type: none"> ▪ Check for an electrical component or loose connection between the charger and the battery. ▪ When charging lithium batteries, make sure the charger is properly connected to the battery and battery management system. ▪ This error automatically clears once the charger is disconnecting DC or AC.
E-0-1-9	Hardware build does not support software version	<ul style="list-style-type: none"> ▪ The charger hardware does not support the new software version. ▪ Existing SW is left running. Contact Delta-Q Technologies.
E-0-2-0	No active algorithm selected	<ul style="list-style-type: none"> ▪ Reprogram the charger with its original software, algorithms, and settings. ▪ Use the wrench button to select the correct algorithm if still available on the charger. ▪ The problem clears automatically when an available algorithm is set on the charger, as default.

E-0-2-1	High battery voltage while charging. Algorithm dependent. Typically 2.8V/cell.	<ul style="list-style-type: none"> ▪ When already charged, some new batteries may exhibit this error. ▪ Disconnect the battery connection and wait for the battery voltage to fall. Reconnect the batteries to see if the condition reoccurs. ▪ Check battery size and condition. Batteries in poor condition, with a high internal resistance, may cause this error. New batteries, if charged when already full, may also cause this error. Disconnect and reconnect the batteries a few times. ▪ Check the battery voltage and cable connections. ▪ This error automatically clears once the condition has been corrected.
E-0-2-2	Low battery voltage while charging. Algorithm dependent. Typically 0.1V/cell.	<ul style="list-style-type: none"> ▪ Another device may be drawing current from the battery. ▪ Check the battery voltage and cable connections. ▪ Check battery size and condition. Batteries may be overdischarged. ▪ Use another charger to bring the batteries above the minimum voltage. ▪ This error automatically clears once the condition has been corrected.
E-0-2-3	High AC voltage error (>270 VAC)	<ul style="list-style-type: none"> ▪ AC voltage is too high. Connect charger to an AC source that has a stable AC voltage between 85 and 270 VAC/45-65 Hz. ▪ In newer software versions this does not prevent charging. ▪ This error will automatically clear once the condition has been corrected.
E-0-2-4	Charger failed to turn on properly	<ul style="list-style-type: none"> ▪ Disconnect AC input and battery for 30 seconds. If the error persists, contact Delta-Q Technologies.
E-0-2-5	AC voltage has dipped below 80 VAC 3 times in 30 seconds	<ul style="list-style-type: none"> ▪ AC source is unstable. This could be caused by an undersized generator and/or input cables that are too long or too small. ▪ Connect the charger to an AC source with a stable AC voltage between 85 and 270 VAC/45-65 Hz. ▪ This error will automatically clear once the condition has been corrected.
E-0-2-8	Attempt to select algorithm incompatible with this software	<ul style="list-style-type: none"> ▪ Update charger software, continue to use existing algorithm* or select a different charging algorithm that is compatible. <p>* Notes</p> <ul style="list-style-type: none"> ▪ If selecting a different algorithm, the existing algorithm will remain in the charger. ▪ If upgrading an existing algorithm, the existing algorithm will be deleted. Contact Delta-Q Technologies for a software upgrade to run the new algorithm.

E-0-2-9	Cannot transmit on CAN bus	<ul style="list-style-type: none"> Check the physical CAN connector, electrical bus conditions, and other CAN modules for correct functioning. For example, check that termination resistance is approximately 60 ohms.
E-0-3-0	CAN heartbeat timeout on Battery module	<ul style="list-style-type: none"> May be caused by a missing heartbeat message. Check the CAN bus battery module for correct function. This error automatically clears once the condition has been corrected.
E-0-3-1	The Vref for the ADC measurements has triggered an alarm	<ul style="list-style-type: none"> Internal charger error. Disconnect AC and the battery for a minimum of 30 seconds and retry. If the problem persists, contact Delta-Q Technologies. This error automatically clears once the condition has been corrected.
E-0-3-2	CAN Heartbeat Lost	<ul style="list-style-type: none"> An error was detected with the CAN heartbeat communications with a registered node being guarded. Check the networked CANbus device(s) for correct functioning. This alarm does not display or get logged on the charger but does appear on the CAN bus via an emergency message.
E-0-3-6	Battery temperature sensor is missing or shorted	<ul style="list-style-type: none"> Check sensor connections. The charger behavior when this fault occurs can be configured. OEMs may contact Delta-Q Technologies for more information. This error automatically clears once the condition has been corrected.
E-0-3-8	Fan will not turn	<p>(Fan-equipped models only)</p> <ul style="list-style-type: none"> Check fan connections. Check to make sure the fan turns freely and is not obstructed. This error automatically clears once the condition has been corrected.
E-0-3-9	The button is stuck down	<ul style="list-style-type: none"> Inspect for damage or objects on or near the button.
E-0-4-0	Fan voltage pulled low	<p>(Fan-equipped models only)</p> <ul style="list-style-type: none"> Check to make sure the fan turns freely.
E-0-4-5	Battery disconnected	<ul style="list-style-type: none"> Battery disconnected Reconnect the battery or check the wiring
E-0-4-6	Invalid PDO Length	<ul style="list-style-type: none"> Check to make sure all PDOs are valid length. This error automatically clears once the condition has been corrected
E-0-4-7	Platform overvoltage alarm	<ul style="list-style-type: none"> A battery or some other source has been connected to the charger that exceeds the hardware's design limits.

5.5 Skycoded control module

5.5-1 Calibration and diagnostic tool key functions

WARNING

Only trained and authorized personnel are permitted to service a MEWP.

WARNING

Read all instructions closely before attempting each phase of the calibration procedure.

The Skycoded controller is the Skyjack-configured flexible control system. It supplies high-side switched outputs for the valves and contactor, proportional outputs, pulse width modulated (PWM) outputs, and low-side outputs for indicator lamps, etc. It also provides active-high inputs from operator controls, and analog inputs from joysticks and sensors. The Skycoded controller has specific Skyjack software and flashed memory for use with load sensing and overload prevention.

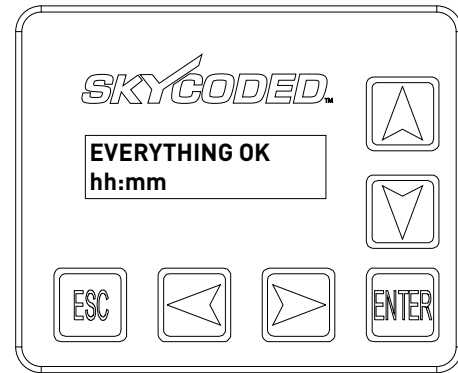
Because the Skycoded controller has an integrated tilt sensor, it is mounted securely to the lateral bracket, which is behind a panel behind the ladder on the control side of the machine.

Factory calibrations for height, load, and level are completed at Skyjack. They only need to be adjusted if a major component (for example, the Skycoded controller) is replaced. See [5.5-9 Calibrate level procedure](#) and [5.5-10 Calibrate load procedure](#) for instructions on how to do these steps if necessary. See the [5.5-7 Initial setup and change defaults procedure](#) when replacing the Skycoded controller.

The display module in the hydraulic tray connects to the control module CM1 P6 connector by a rear plug with a four-pin RS232 connection. See [5.5-2 Skycoded control module pin chart](#) for Skyjack-specific wiring specifications on the Skycoded controller.

The module uses a two-line display and shows various menus and settings. The top line of the display describes the currently selected menu, and the bottom line shows the currently selected item in that menu.

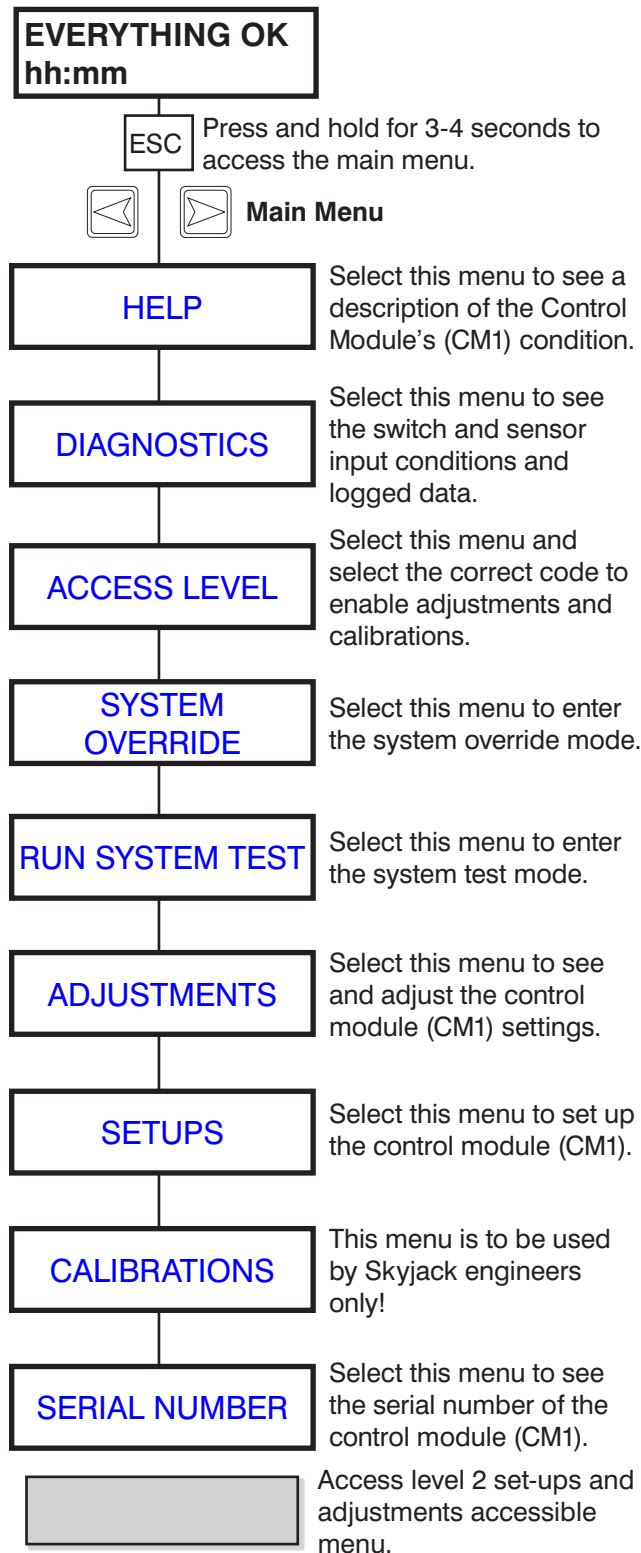
Skycoded display controls



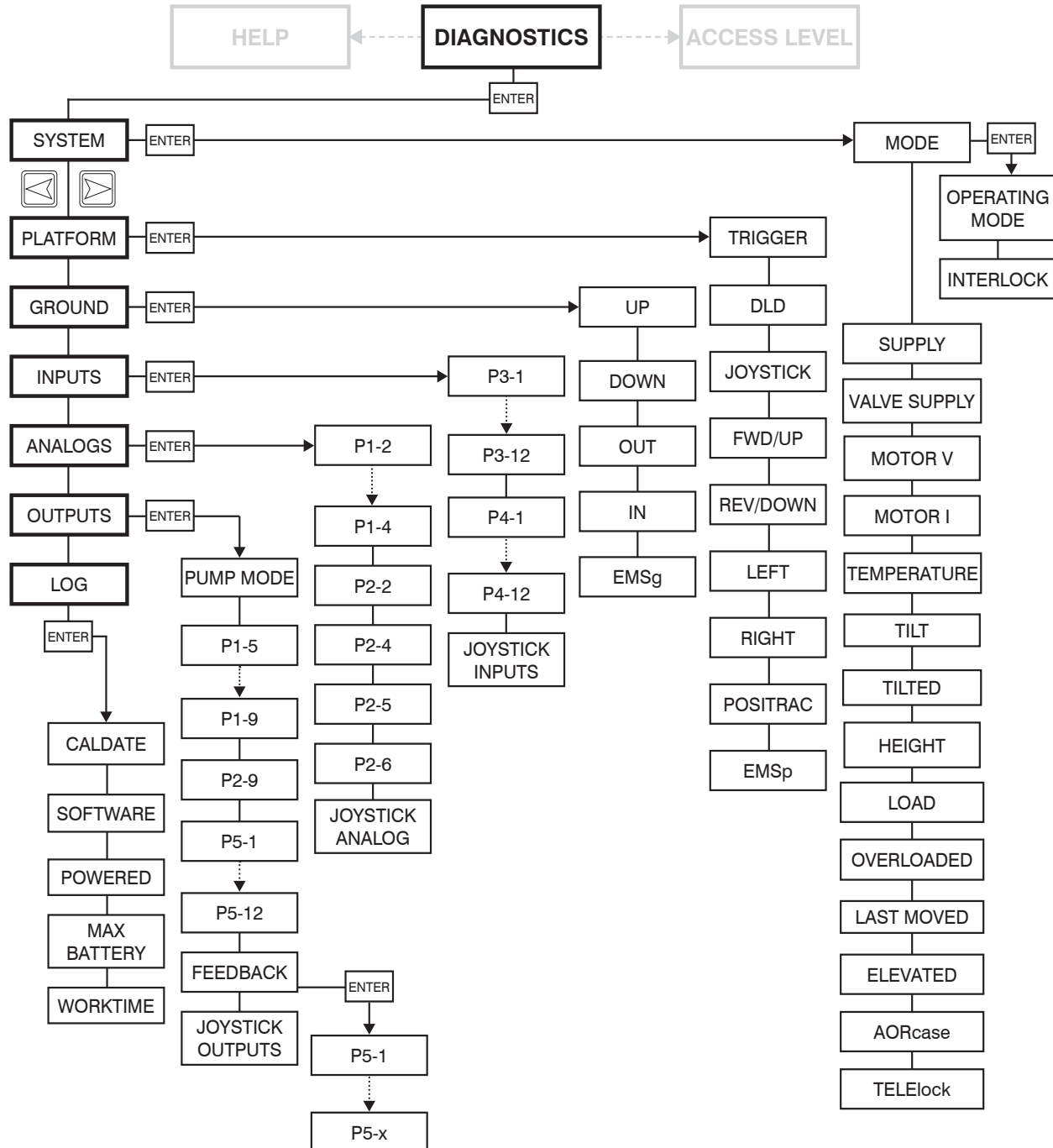
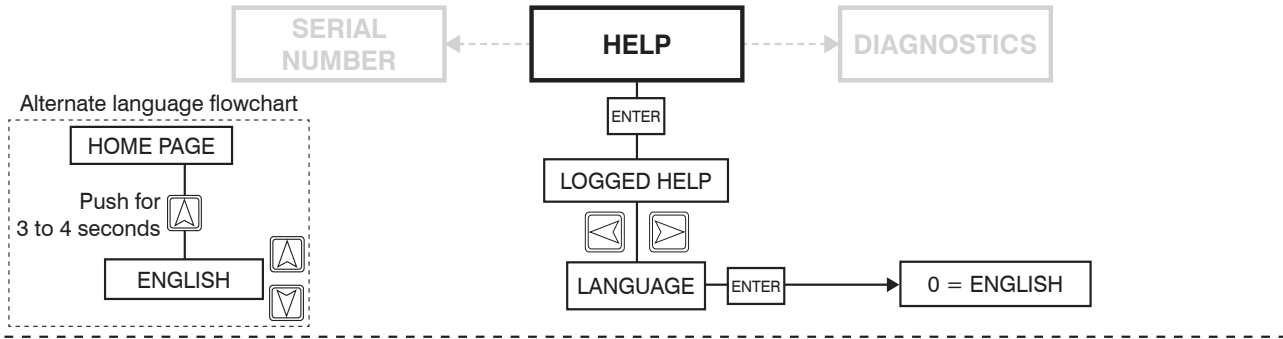
Symbol	Key Function
	ESC/ENTER buttons To move back and forth between menu and sub-menu
	LEFT/RIGHT buttons Select menus and setting to be adjusted
	UP/DOWN buttons Adjust setting values

Use the left and right arrows to scroll through the top level menu selections and press ENTER.

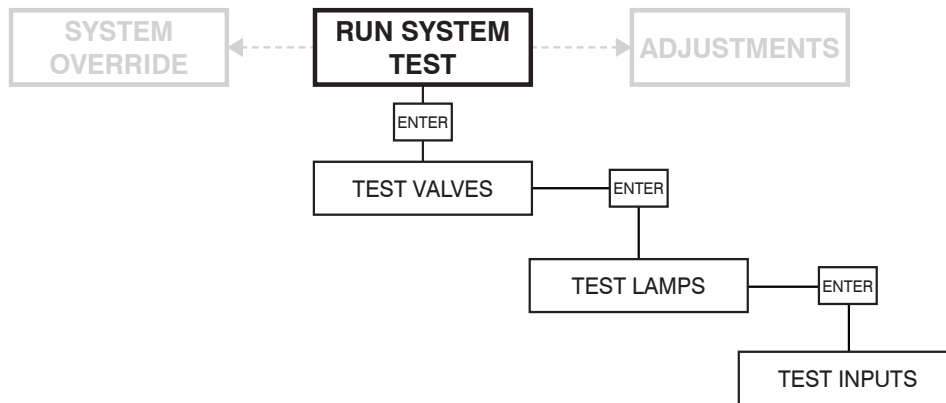
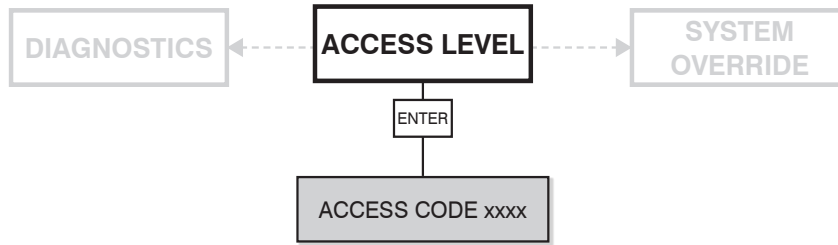
Skycoded controls - Initial state



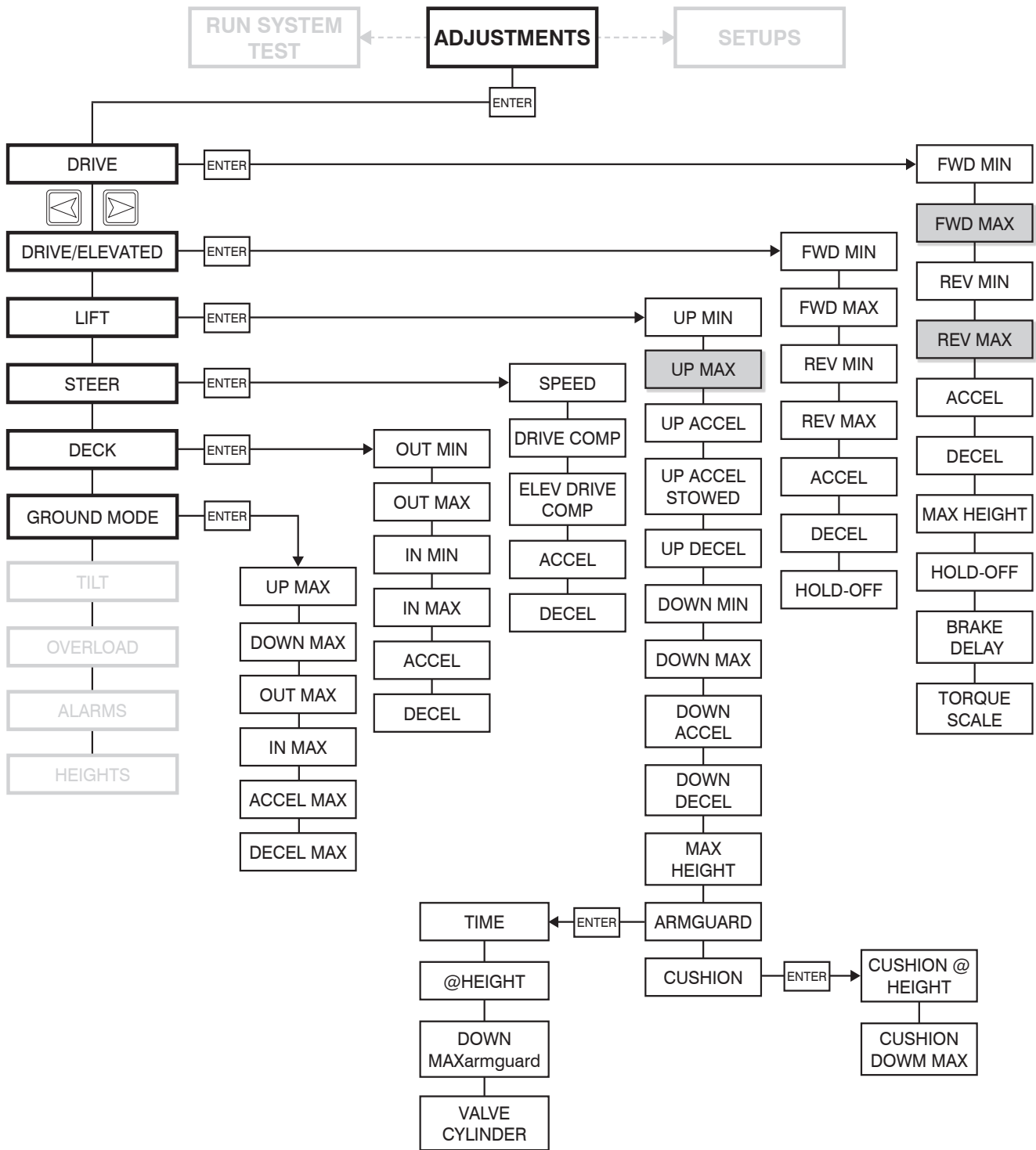
Skycoded controls - HELP/DIAGNOSTICS



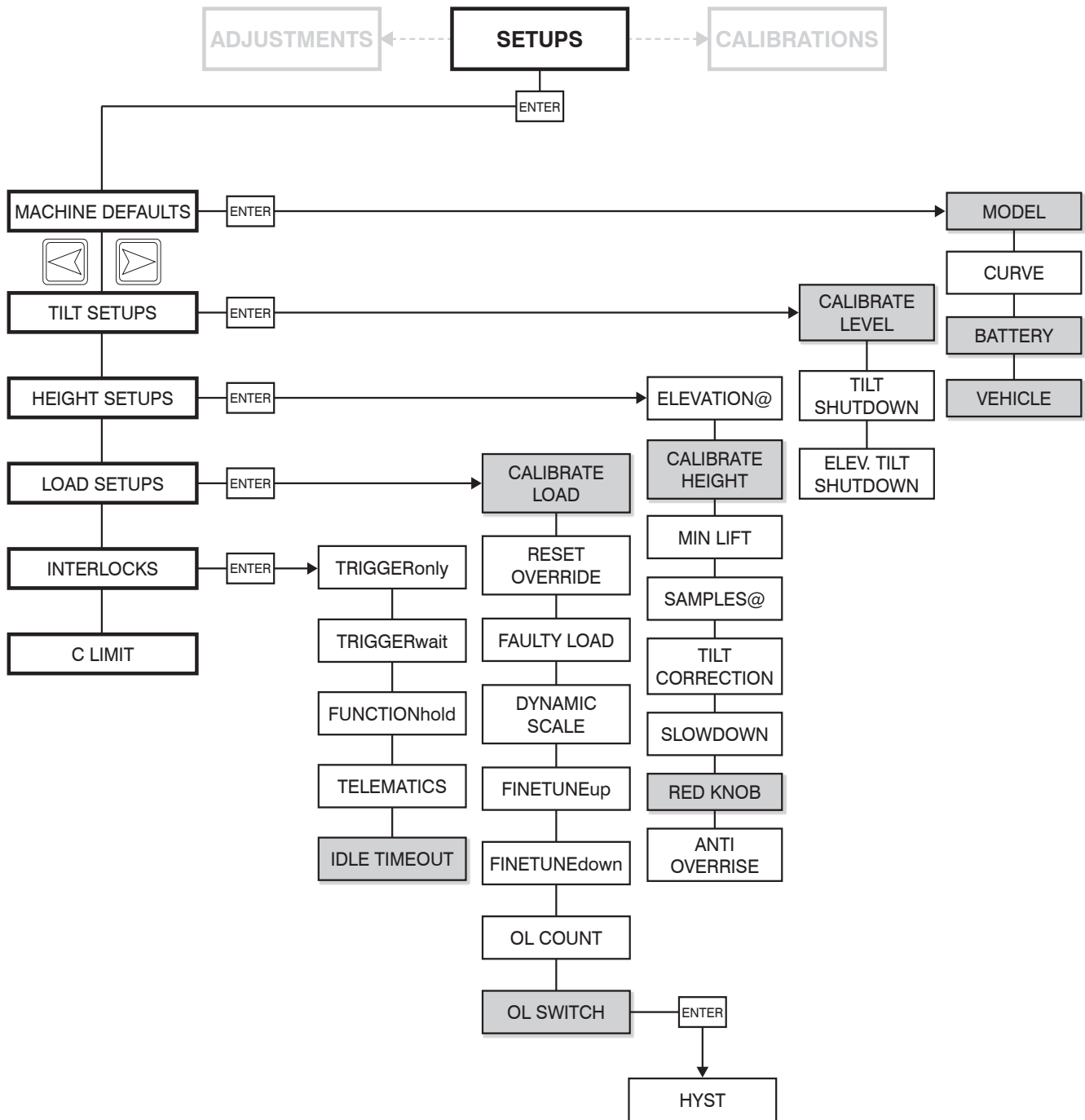
Skycoded controls - ACCESS LEVEL/SYSTEM OVERRIDE/RUN SYSTEM TEST



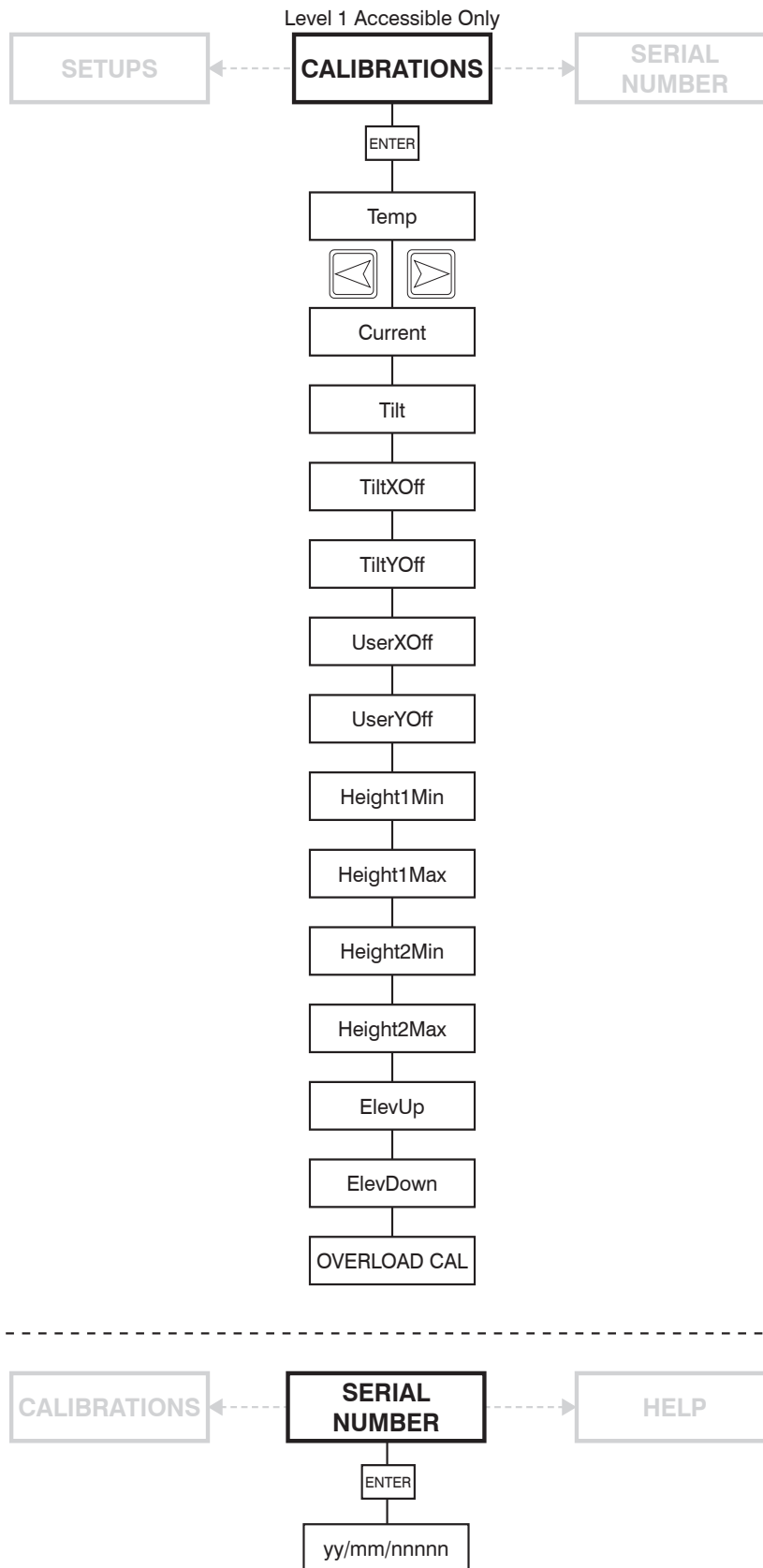
Skycoded controls - ADJUSTMENTS



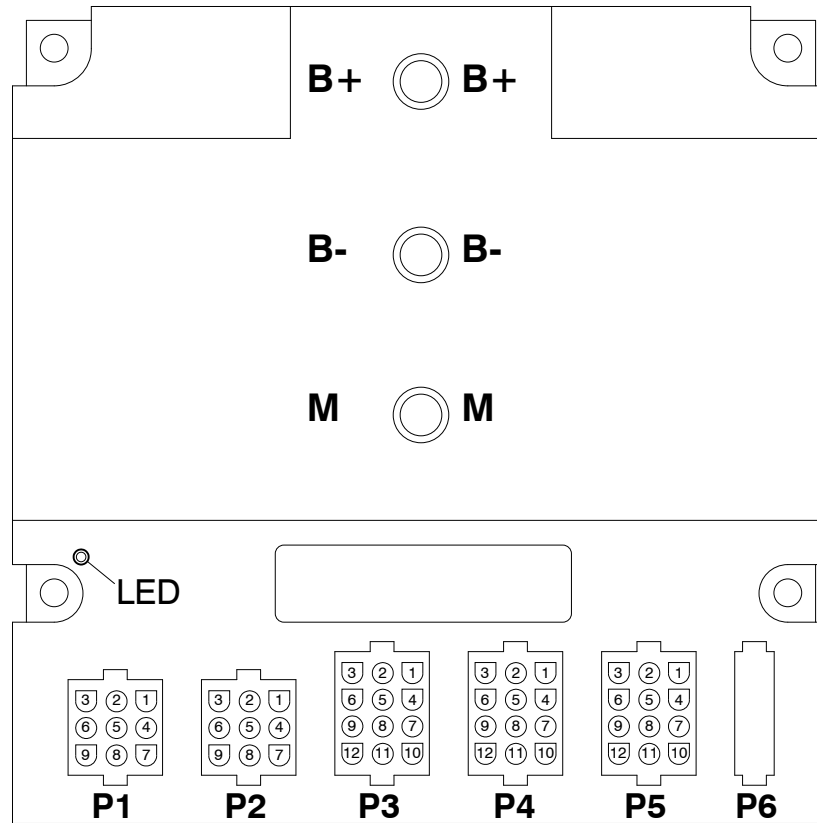
Skycoded controls - SETUPS



Skycoded controls - CALIBRATIONS/SERIAL NUMBER



5.5-2 Skycoded control module pin chart



Skycoded control module CM1

PLUG	PIN #	WIRE # AND COLOUR	PIN OUT
B+		03B Black	Lug for 24V supply voltage (from C1 Motor Contactor relay N.O. contact)
B-		00 Black	Lug for 0V reference from battery negative (negative bus bar)
M		M- Black	Lug for Output of Pulsed Negative (-) to initialize Pump Motor
Outputs and Analog Inputs			
P1	1	08B Green	5V supply to Joystick PCB P8
P1	2	59 Orange/Black	0-5V Proportional Input from Joystick Analog PCB Output P7
P1	3	00B White/Black	0V reference to Joystick PCB P6
P1	4	19D White/Red	Input for Shutdown signal from Elevate Trackunit Telematics option (if equipped)
P1	5	CAN H	Communication CANbus High (if equipped)
P1	6	CAN L	Communication CANbus Low (if equipped)
P1	7	Not Used	Not Used
P1	8	60 Red/White	0V Reference Output (pulsed) for PL-1 & PL-2 Overload Light when close to or exceeding capacity. 0V Reference Output (constant) for PL-1 & PL-2 Overload light when below capacity and both emergency stops are active.
P1	9	29 Blue/Yellow	0V Reference Output (pulsed) for BP-29 Beeper for All-Motion, Tilt and Overload

Skycoded control module pin chart (continued)







PLUG	PIN #	WIRE # AND COLOUR	PIN OUT
Connects to Sensors			
P2	1	Not Used	Not Used
P2	2	28 Green/Red	0-5V Proportional Input from AT1 angle transducer Analog Output signal (3.7 Volts when stowed)
P2	3	Not Used	Not Used
P2	4	60A Black/Red/Green	0-5V Proportional Input from PT1 pressure transducer Analog Output signal
P2	5	28A Green/Red	0-5V Proportional Input from AT1 angle transducer Analog Output signal (3.7 Volts when stowed)
P2	6	Not Used	Not Used
P2	7	910 Black	Output supply 24V (B+) for AT1, PT1 Transducers, Pothole Protection Limit switches LS1, LS2, and Beeper BP-29
P2	8	00C White	0V Reference Output to Holding Solenoids (2H-13-1 & 2H-13-2)
P2	9	22 Orange/Blue	0V Reference Output (pulsed) to FL-22 Flashing Light
Platform Controls			
P3	1	08C Purple/White	24V Input from S10 Idle/PLTF/Base Key Switch for Platform and/or Base signal ** required input for any movement **
P3	2	08 Blue/White	24V Input B+ Valve supply IF BOTH Emergency Stops are energized (supplies all valve outputs) ** required input for any movement from Platform **
P3	3	18 Red/Black	24V Input from S27 Torque Switch for High Torque signal
P3	4	120 Black	24V Input from S17 Indoor Select switch for Indoor signal (if equipped)
P3	5	10 Blue/White	24V Input from S10 Idle/PLTF/Base Key Switch for Base signal
P3	6	12 Blue	24V Input from S3 lift/off/drive switch for Drive signal
P3	7	09 Orange	24V Input from S3 lift/off/drive switch for Lift signal
P3	8	23 Black/White	24V Input from S7-2 Joystick PCB P3 Steer Right signal
P3	9	24 Blue/Black	24V Input from S7-3 Joystick PCB P1 Steer Left signal
P3	10	51A White	(KC built machines only) 24V Input from anti-overriding limit switches N.O. contacts
P3	11	51 Black	(KC built machines only) 24V Input from anti-overriding limit switches N.C. contacts
P3	12	08A Black	24V Input from S7-6 Joystick PCB P4 Enable signal
Base Control			
P4	1	13B Orange	24V Input from S51 Emergency Lowering Toggle Switch for counter
P4	2	Not Used	Not Used
P4	3	Not Used	Not Used
P4	4	13A Orange	24V Input from S2 Lift/Lower Toggle Switch for Down signal
P4	5	14A Black	24V Input from S2 Lift/Lower Toggle Switch for Up signal
P4	6	Not Used	Not Used
P4	7	71 Blue/Red	24V Input from LS1 & LS2 Pothole Protection Limit Switches closed (LS1 & LS2 contacts are in series)
P4	8	26 Green	24V Input from Power Deck Extend signal (if equipped)
P4	9	27 Black	24V Input from Power Deck Retract signal (if equipped)
P4	10	37 Green/White	24V Input for Charger Cutout Interlock switch

Skycoded control module pin chart (continued)

PLUG	PIN #	WIRE # AND COLOUR	PIN OUT
P4	11	Not Used	Not Used
P4	12	Not Used	Not Used
Valve Outputs			
P5	1	19 White/Red	24V Output for Motor Contactor Coil C1
P5	2	16 White/Black	24V Output for Forward Solenoid Valve 4H-16
P5	3	15 Blue	24V Output for Reverse Solenoid Valve 4H-15
P5	4	17 Blue/Red	24V Output for Brake Solenoid Valve 3H-17
P5	5	14 Black	24V Output for Up Solenoid Valve 3H-14
P5	6	24A Blue/Black	24V Output for Steer Left Solenoid Valve 4H-24A
P5	7	26B White	24V Output for Power Deck Extend Solenoid Valve 4H-26 (if equipped)
P5	8	23A Black/White	24V Output for Steer Right Solenoid Valve 4H-23A
P5	9	18A Red/Black	24V Output for Torque mode Solenoid Valves 2H-18A, 2H-18A-1 & 2H-18A-2
P5	10	27B Black	24V Output for Power Deck Retract Solenoid Valve 4H-27 (if equipped)
P5	11	13C Orange	(CE built machines only) Output for Proportional Lowering Solenoid Valve 2H-13C
P5	12	13 Orange	12V Output for Holding Solenoid Valves 2H-13-1 & 2H-13-2
HMI Connection (RS232)			
P6	1	B+ Black	24V B+ supply to Display Module
P6	2	Rx Red	Rx Receive signal to Display Module
P6	3	Tx Green	Tx Transmit signal to Display Module
P6	4	902 White	0V GND Reference to Display Module, PT1 & AT1 sensors

5.5-3 Skycoded control module menu table

Items highlighted in grey requires technician access level 2 to change. Otherwise, menus are locked as initial factory access level 1.

Menu	Selection	Sub-Menu	Description
HELP			
LOGGED HELP	HELP		Press ENTER when viewing the current HELP message to see a log of recent HELP messages Press  to see older messages, and  to see newer ones Press ESC to return to the current HELP message
	LANGUAGE	0=ENGLISH	Press  or  select language preferred on the display
DIAGNOSTICS			
SYSTEM	MODE	OPERATING mode	Displays current operating mode or interlock
		INTERLOCK	When current operating mode shows INTERLOCKED, press ENTER to see the reason for the interlock Press ESC to return to the current operating mode
	SUPPLY		Displays battery supply voltage
	VALVESUPPLY		Displays valve supply state
	MOTOR V		Displays motor voltage
	MOTOR I		Displays motor current
	TEMPERATURE		Displays temperature (°C)
	TILT		Displays tilt values (X°, Y°)
	TILTED		Displays whether system is in tilted mode (measured tilt exceeds tilt trip points)
	HEIGHT		Displays platform height, calculated from angle, pressure transducers and data stored during calibration. Angle transducers are installed, press ENTER when viewing the HEIGHT (which is the average of the two). To see the individual measurements of the two sensors, named HEIGHT1 and HEIGHT2 (press  and  to see both); press ESC to return to the average HEIGHT.
	LOAD		Displays Platform load (estimated from lift cylinder pressure measurement, platform height, and height/pressure curves stored during calibration).
	OVERLOADED		Displays whether system is in overload mode (Platform load exceeds load trip point, at/above overload height)
	LAST MOVED		Displays whether the most recent Platform movement was UP or DOWN; this is important if the lift cylinder pressure is affected by the direction of movement (during calibration, separate measurements are collected during lifting and lowering)
	ELEVATED		Displays whether system is in elevated mode
	AORcase		Displays Anti Over-Rise state
TELElock		Displays Telematics option	

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
PLATFORM	TRIGGER		Displays ON when Platform trigger pressed
	DLD		Displays drive / lift mode (from S3 lift/off/drive switch)
	JOYSTICK		Displays joystick position (%)
	FWD/UP		Displays ON when joystick is moved toward FWD or UP
	REV/DOWN		Displays ON when joystick is moved toward REV or DOWN
	LEFT		Displays ON when steer left button pressed
	RIGHT		Displays ON when steer right button pressed
	POSITRAC		Displays ON when traction switch is pressed
	EMSp		Displays ON, indicating Platform Emergency Stop circuit is active
GROUND	UP		Displays ON when UP switch pressed
	DOWN		Displays ON when DOWN switch pressed
	OUT		Displays ON when (optional) deck out switch pressed
	IN		Displays ON when (optional) deck in switch pressed
	EMSg		Displays ON, indicating ground base emergency stop is active
INPUT	P3-1		Shows P3-1 input status (S10 Idle/PLTF/Base Key switch active)
	P3-2		Shows P3-2 input status (valve supply, on with Platform E-stop active)
	P3-3		Shows P3-3 input status (S27 Torque switch select high torque)
	P3-4		Shows P3-4 input status (S17 indoor/outdoor switch select indoor) (if equipped)
	P3-5		Shows P3-5 input status (S10 Idle/PTLF/Base Key switch select Base)
	P3-6		Shows P3-6 input status (S3 lift/off/drive switch select Drive)
	P3-7		Shows P3-7 input status (S3 lift/off/drive switch select Lift)
	P3-8		Shows P3-8 input status (S7-2 STEER RIGHT from joystick)
	P3-9		Shows P3-9 input status (S7-2 STEER LEFT from joystick)
	P3-10		Shows P3-10 input status (KC Anti Override N.O. signal)
	P3-11		Shows P3-11 input status (KC Anti Override N.C. signal)
	P3-12		Shows P3-12 input status (S7-6 Enable switch from joystick)
	P4-1		Shows P4-1 input status (S51 Emergency Lowering Toggle counter)
	P4-2		Shows P4-2 input status (not used)
	P4-3		Shows P4-3 input status (not used)
	P4-4		Shows P4-4 input status (S2 Lift/Lower Toggle switch DOWN select)
	P4-5		Shows P4-5 input status (S2 Lift/Lower Toggle switch UP select)
	P4-6		Shows P4-6 input status (not used)
	P4-7		Shows P4-7 input status (LS1 & LS2 Pothole Protection limit sw's active)
	P4-8		Shows P4-8 input status (powerdeck extended) (if equipped)
P4-9		Shows P4-9 input status (powerdeck retracted) (if equipped)	

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
INPUT	P4-10		Shows P4-10 input status (charger cutout interlock switch)
	P4-11		Shows P4-11 input status (not used)
	P4-12		Shows P4-12 input status (not used)
	JOYSTICK INPUTS		Shows Joystick M3 input status CANBus (not used)
ANALOGS	P1-2		Displays voltage measurement of joystick analog input P1-2
	P1-4		Displays Trackunit Telematics option (if equipped)
	P2-2		Displays voltage measurement of AT1 angle transducer analog input P2-2 signal
	P2-4		Displays voltage measurement of PT1 pressure transducer analog P2-4 signal
	P2-5		Displays voltage measurement of AT angle transducer analog input P2-5 signal
	P2-6		Not used
	JOYSTICK ANALOGS		Displays Joystick M2 CANBus signals (not used)
OUTPUTS	PUMPMODE		Displays state of Pumpmode setting
	P1-5		Displays state of P1-5 CANbus High signal (if equipped)
	P1-6		Displays state of P1-6 CANbus Low signal (if equipped)
	P1-7		Displays state of P1-7 output (not used)
	P1-8		Displays state of P1-8 output (PL-1 & PL-2 Overload lamp)
	P1-9		Displays state of P1-9 output (BP-29 All-Motion, Tilt and Overload Beeper)
	P2-9		Displays state of P2-9 output (FL-22 Flashing Light)
	P5-1		Displays state of P5-1 output (C1 Motor Contactor)
	P5-2		Displays state of P5-2 output (Forward Drive)
	P5-3		Displays state of P5-3 output (Reverse Drive)
	P5-4		Displays state of P5-4 output (Brake release)
	P5-5		Displays state of P5-5 output (Lift UP)
	P5-6		Displays state of P5-6 output (Steer Left)
	P5-7		Displays state of P5-7 output (deck extend) (if equipped)
	P5-8		Displays state of P5-8 output (Steer Right)
	P5-9		Displays state of P5-9 output (Torque mode high speed select)
	P5-10		Displays state of P5-10 output (deck retract) (if equipped)
	P5-11		Displays state of P5-11 output (lower valve) (CE only)
P5-12		Displays state of P5-12 output (Holding Valves)	

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
OUTPUTS	FEEDBACK		Press ENTER to display this sub-menu to view feedback status of outputs
		P5-1	Displays P5-1 (C1 Motor Contactor) output status – LO when off, HI when on
		P5-x	Displays output status of all other P5 outputs (except P5-1 above) (ie: valves) – LO when all valves off, HI when any valve on
	JOYSTICK OUTPUTS		Displays output status of Joystick M1 CANBus signals (not used)
LOG	CALDATE		Displays date entered by operator at end of last calibration
	SOFTWARE		Displays software version of control module CM1
	POWERED		Displays total time that control module CM1 has been powered
	MAX.BATTERY		Displays maximum recorded battery supply voltage
	WORKTIME		Displays total time that the pump has been powered
ACCESS LEVEL			
	CODE xxxx		<p>ACCESS LEVEL” 3 prevents adjustments and calibrations (default)</p> <p>ACCESS LEVEL” 2 allows calibrations (requires correct code)</p> <p>“ACCESS LEVEL” 1 allows adjustments and calibrations (factory level)</p> <p>“PUMPMODE” allows troubleshooting without Hydraulic pump function</p> <p>When the Display Module is connected and powered on, the initial “ACCESS LEVEL” level 3 by default and adjustments cannot be altered and calibrations cannot be carried out.</p> <p>Before Calibrations can be done, the “ACCESS LEVEL” must be changed to level 2 using the correct access code. ACCESS LEVEL 2 allows calibrations and allows some adjustments to be changed.</p> <p>Adjustments should only be attempted by qualified individuals.</p>
SYSTEM OVERRIDE*			
			Press ENTER to ENTER into OVERRIDE mode.
RUN SYSTEM TEST			
	TEST VALVES		Press ENTER to run rolling test of all valves coils on at a time. Coils will be energized in a rolling pattern. Any short circuits or incorrect feedback will be displayed. Press ESC to skip to the next test.
	TEST LAMPS		Press ENTER to run rolling test of all lamps, Press ESC to skip to the next test
	TEST INPUTS		Press ENTER to run a rolling test of all inputs. This requires the tester to manually operate the switches when requested. Press ESC to skip to the next test.
ADJUSTMENTS (Access level 1 required unless highlighted in grey)			
DRIVE	FWD MIN		Determines the slowest drive speed in the forward direction (when the joystick is at 0% demand)
	FWD MAX		Determines the fastest drive speed in the forward direction (when the joystick is at 100% demand)
	REV MIN		Determines the slowest drive speed in the reverse direction (when the joystick is at 0% demand)
	REV MAX		Determines the fastest drive speed in the reverse direction (when the joystick is at 100% demand)
	ACCEL		Determines the rate of increase of drive speed when higher speeds are demanded

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
DRIVE	DECEL		Determines the rate of decrease of drive speed when lower speeds (or stop) are demanded
	MAX HEIGHT		Determines the height above which drive is prevented.
	HOLD-OFF		Sets a delay time to keep drive valve turned on after ramping to a stop (if needed to avoid locking wheels at stop)
	BRAKE DELAY		Sets a delay time for when the brakes are activated
	TORQUE SCALE		Sets the torque scale
DRIVE/ELEVATED	FWD MIN		Determines the slowest drive speed in the forward direction (when the joystick is at 0% demand) when elevated
	FWD MAX		Determines the fastest drive speed in the forward direction (when the joystick is at 100% demand) when elevated
	REV MIN		Determines the slowest drive speed in the reverse direction (when the joystick is at 0% demand) when elevated
	REV MAX		Determines the fastest drive speed in the reverse direction (when the joystick is at 100% demand) when elevated
	ACCEL		Determines the rate of increase of drive speed when higher speeds are demanded when elevated
	DECEL		Determines the rate of decrease of drive speed when lower speeds (or stop) are demanded when elevated
	HOLD-OFF		Sets a delay time to keep drive valve turned on after ramping to a stop when elevated
LIFT	UP MIN		Determines the slowest lifting speed (when the joystick is at 0% demand)
	UP MAX		Determines the fastest lifting speed (when the joystick is at 100% demand)
	UP ACCEL		Determines the time for acceleration of lifting
	UP ACCEL STOWED		Determines the time for acceleration from stowed
	UP DECEL		Determines the time for deceleration
	DOWN MIN		Determines the slowest lowering speed (when the joystick is at 0% demand)
	DOWN MAX		Determines the fastest lowering speed (when the joystick is at 100% demand)
	DOWN ACCEL		Determines the rate of increase of lift speed when higher speeds are demanded as well as lowering speed, if lowering is controlled by the pump or a proportional valve.
	DOWN DECEL		Determines the rate of decrease of lift speed when lower speeds are demanded as well as lowering speed, if lowering is controlled by the pump or a proportional valve.
	MAX HEIGHT		Determines the height above which lifting is prevented.

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description	
LIFT	ARMGUARD		Press ENTER to display sub-menu to access adjustments related to armguard	
		TIME	Determines the time delay when armguard triggers during lowering, before lowering is allowed to continue	
		@HEIGHT	Determines the height at which "soft armguard" occurs when lowering	
		DOWN MAXarm-guard	Determines the speed at which "soft armguard" occurs when lowering	
		VALVE CYLINDER	Determines the location of the Proportional Valve (Main manifold or Cylinder)	
	CUSHION@	CUSHION @ HEIGHT	Determines the height at which the cushion occurs	
		CUSHION DOWN MAX	Determines the speed at which the cushion is enabled	
STEER	SPEED		Determines the pump speed when steering is used on its own (without drive).	
	DRIVE COMP		Determines the additional speed to apply to the current drive speed when steering is used when driving while the platform is not elevated – it can be adjusted to minimize any slow down in drive speed due to steering demand.	
	ELEV DRIVE COMP		Determines the additional speed to apply to the current drive speed when steering is used when driving while elevated.	
	ACCEL		Determines the rate of increase of pump speed when steering is selected on its own (without drive)	
	DECEL		Determines the rate of decrease of drive speed when steering is selected on its own (without drive)	
LIFT (CONT.)	UP ACCEL		Determines the time for acceleration of lifting	
	UP ACCEL STOWED		Determines the time for acceleration from stowed	
	UP DECEL		Determines the time for deceleration	
	DOWN MIN		Determines the slowest lowering speed (when the joystick is at 0% demand)	
	DOWN MAX		Determines the fastest lowering speed (when the joystick is at 100% demand)	
	DOWN ACCEL		Determines the rate of increase of lift speed when higher speeds are demanded as well as lowering speed, if lowering is controlled by the pump or a proportional valve.	
	DOWN DECEL		Determines the rate of decrease of lift speed when lower speeds are demanded as well as lowering speed, if lowering is controlled by the pump or a proportional valve.	
	MAX HEIGHT		Determines the height above which lifting is prevented.	
	ARMGUARD			Press ENTER to display sub-menu to access adjustments related to armguard
		TIME		Determines the time delay when armguard triggers during lowering, before lowering is allowed to continue
		@HEIGHT		Determines the height at which "soft armguard" occurs when lowering
		DOWN MAXarmguard		Determines the speed at which "soft armguard" occurs when lowering
		VALVE CYLINDER		Determines the location of the Proportional Valve (Main manifold or Cylinder)
	CUSHION@	CUSHION @ HEIGHT		Determines the height at which the cushion occurs
		CUSHION DOWN MAX		Determines the speed at which the cushion is enabled

 Items highlighted in grey require access level 2.

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description	
STEER	SPEED		Determines the pump speed when steering is used on its own (without drive).	
	DRIVE COMP		Determines the additional speed to apply to the current drive speed when steering is used when driving while the platform is not elevated – it can be adjusted to minimize any slow down in drive speed due to steering demand.	
	ELEV DRIVE COMP		Determines the additional speed to apply to the current drive speed when steering is used when driving while elevated.	
	ACCEL		Determines the rate of increase of pump speed when steering is selected on its own (without drive)	
	DECEL		Determines the rate of decrease of drive speed when steering is selected on its own (without drive)	
DECK	OUT MIN		Determines the slowest deck out (extend) speed (when the joystick is at 0% demand)	
	OUT MAX		Determines the fastest deck out (extend) speed (when the joystick is at 100% demand)	
	IN MIN		Determines the slowest deck in (retract) speed (when the joystick is at 0% demand)	
	IN MAX		Determines the fastest deck in (retract) speed (when the joystick is at 100% demand)	
	ACCEL		Determines the rate of increase of deck speed when higher speeds are demanded	
	DECEL		Determines the rate of decrease of deck speed when lower speeds are demanded	
GROUNDMODE	UP		Determines the (fixed) lifting speed in Base mode	
	DOWN		Determines the (fixed) lowering speed in Base mode	
	OUT		Determines the (fixed) deck out (extend) speed in Base mode	
	IN		Determines the (fixed) deck in (retract) speed in Base mode	
	ACCEL		Determines the rate of increase of lift/lower/deck speeds in Base mode	
	DECEL		Determines the rate of decrease of lift/lower/deck speeds in Base mode	
TILT	Xtrip		Determines the amount of machine tilt needed to trigger the “tilted” condition; separate adjustments are provided for tilt in the two axis – the control module correctly combines tilt in each axis to determine an overall tilted/not-tilted condition.	
	Ytrip			
	DELAYtrip		Determines the time delay (“debounce”) to go from not-tilted to tilted, and from tilted to not-tilted – “DELAYtrip” determines the time delay to go in to a “tilted” condition and “DELAYclear” determines the time delay to exit the “tilted” condition.	
	DELAYclear			
	TILT#2			Press ENTER to display sub-menu to access adjustments related to second tilt trip points
		@HEIGHT		Determines the height above which second tilt trip points apply.
		Xtrip2		Determines the amount of machine tilt needed to trigger the “tilted” condition, when above the second tilt height.
	Ytrip2		The same DELAY settings are used as for the normal tilt trip points.	
OVERLOAD	TRIP@		Determines the Platform load estimate above which functions will be prevented. NOTE: Each machine must be calibrated with the Platform fully loaded and also empty before the platform load estimates can be made.	
	LAMP@		Determines the Platform load estimate above which the overload warning lamp will be active.	
	ALARM@		Determines the Platform load estimate above which the overload warning alarm will be active.	
	DYNAMIC		Determines the Platform load estimate when moving and not static.	
	SAFE@		Determines the Platform percentage of load which functions will be allowed.	
	@HEIGHT		Determines the height above which an overloaded Platform will prevent functions.	
	SAFE-DOWN		Determines the height below which an overloaded Platform can still be lowered – this is because when the platform is fully lowered, overload cannot be determined since there is no load on the lift cylinder; instead the first overload is determined according to @HEIGHT, and if the platform is overloaded, it must be able to be lowered again so the operator can reduce the weight.	

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
OVER-LOAD	DELAYtrip		Determines the time delay (“debounce”) to go from not-overloaded to overloaded, and from overloaded to not-overloaded.
	DELAYclear		DELAYtrip determines the time delay to go in to an “overloaded” condition. DELAYclear determines the time delay to exit the “overloaded” condition.
ALARMS	DRIVE		Determines when to sound the alarm – set to “NO” to not sound while driving, to “FWD” or “REV” to sound while driving in that direction, or to “BOTH” to sound for driving in either direction.
	LIFT		Determines when to sound the alarm – set to “NO” to not sound while lifting/lowering, to “UP” or “DOWN” to sound while lifting or lowering, or to “BOTH” to sound for lifting and lowering.
	TILT		Determines when to sound the alarm – set to “NO” to not sound depending on tilt, to “ELEVATED” to sound if tilted and elevated, or to “ALWAYS” to sound when tilted irrespective of platform height.
HEIGHTS	ELEVATION@		Determines the “elevation” point – the Platform height at which the machine is considered to be elevated.
	MAX DRIVE		Determines the height above which drive is prevented.
	MAX LIFT		Determines the height above which lift is prevented.
	ARMGUARD		Determines the height at which “soft armguard” occurs when lowering.
	OVERLOAD		Determines the height above which an overloaded platform will prevent functions.
	SAFE-DOWN		Determines the height below which an overloaded platform can still be lowered.
	POTHOLE		Determines the height at which the Pothole bar is engaged.
	TILT#2		Determines the height above which reduced overload trip points apply.
CUSHION		Determines the height at which the cushioning effect is applied.	
SETUPS			
MACHINE DEFAULTS	<i>See 5.5-7 Initial setup and change defaults procedure</i>		
	MODEL		Factory set to configure machine type; confirm that the correct customer code is displayed. Determines the initial default settings of all ADJUSTMENTS; Set to change to the correct model code for the machine.
	CURVE		Selects the proper preprogrammed load/height curve.
	BATTERY		Selects the type of battery installed in machine.
	VEHICLE		Selects the type of vehicle.
TILT SETUPS	<i>See 5.5-9 Calibrate level procedure</i>		
	CALIBRATE LEVEL		Calibrates control module CM1 tilt to zero degrees X and Y.
	TILT SHUTDOWN		Determines if control module CM1 will prevent functions when machine is tilted: NEVER – no functions prevented LIFT&DRIVE – lifting and driving prevented (lowering still allowed) LIFT – lifting prevented (lowering and driving still allowed) DRIVE – driving prevented (lifting and lowering still allowed)
	ELEV. TILT SHUTDOWN		Determines if control module CM1 will prevent functions when machine is both tilted and elevated.
HEIGHT SETUPS	ELEVATION@		Determines the “elevation” point – the platform height at which the machine is considered to be elevated.
	CALIBRATE HEIGHT		Calibrates platform height from 0% to 100%.
	MIN LIFT		Determines the minimum time between each static measurement during load calibration.
	SAMPLES@		Determines the time between samples during dynamic lifting load calibration.
	TILT CORRECTION		Configures how to correct machine tilt so that control module CM1 height measurement is correct.

 Items highlighted in grey require access level 2.

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
HEIGHT SETTINGS	SLOWDOWN		Determines whether to reduce lifting speed as platform height approaches MAX LIFT setting or not to make sure there is no overshoot.
	RED KNOB		Determines if machine was built with the "red knob" manual override in the Holding Valves for emergency lowering.
	ANTI OVERRISE		Determines if the machine has optional KC Anti Overriding switches. 1=disable, 2=enable.
<i>See 5.5-10 Calibrate load procedure</i>			
LOAD SETTINGS	CALIBRATE LOAD		Calibrates platform load estimation from 0% to 100% height, at rated load and empty, as measured by the lift cylinder pressure sensor.
	RESET OVERRIDE		Determines if the count for Override function can be reset to zero.
	FAULTY LOAD		Determines whether to prevent movement if load estimate is implausibly low (i.e. damaged pressure sensor).
	DYNAMIC SCALE		Determines sensitivity to stop at OVERLOAD @HEIGHT, if platform load estimate is close to trip point.
	FINETUNEup		Determines the percentage of fine tuning calculated during Calibration for UP movement.
	FINETUNEdown		Determines the percentage of fine tuning calculated during Calibration for DOWN movement.
	OL COUNT		HIDE or SHOW the count for Overload triggers made.(CE models only).
	OL SWITCH	HYST	Determines the version of Overload switches (CE model only).
INTERLOCKS	TRIGGERonly		Determines whether or not to trigger an interlock when the trigger is closed with no other function select and after what delay to do it in.
	TRIGGERwait		Determines whether or not to trigger an interlock when a function is selected without the trigger being closed and after what delay to do it in.
	FUNCTIONhold		Only applicable if drive/lift mode is selected with momentary push switches; when using a drive/lift toggle switch.
	TELEMATICS		Determines if the Telematics option is "Normal" or has a "Lockout" keypad option installed.
	IDLE TIMEOUT		Determines time until control module CM1 goes into sleep mode if no functions or operations have been requested for that time.
	C LIMIT		Determines the Current Limit of the motor before being derated. Set below the fuse amperage.
CALIBRATIONS (Access Level 1 required)			
	Temp		Factory set to calibrate heatsink temperature (motor power may be reduced if the heatsink temperature is too high).
	Current		Factory set to calibrate motor current.
	TiltGain		Factory set to calibrate control module CM1 tilt sensor.
	TiltXoff		
	FUNCTIONhold		Only applicable if drive/lift mode is selected with momentary push switches; when using a drive/lift toggle switch.
	TELEMATICS		Determines if the Telematics option is "Normal" or has a "Lockout" keypad option installed.
	IDLE TIMEOUT		Determines time until control module CM1 goes into sleep mode if no functions or operations have been requested for that time.
	C LIMIT		Determines the Current Limit of the motor before being derated. Set below the fuse amperage.
CALIBRATIONS (Access Level 1 required)			
	Temp		Factory set to calibrate heatsink temperature (motor power may be reduced if the heatsink temperature is too high).
	Current		Factory set to calibrate motor current.
	TiltGain		Factory set to calibrate control module CM1 tilt sensor.
	TiltXoff		
	TiltYoff		

Items highlighted in grey require access level 2.

Skycoded control module menu table (continued)

Menu	Selection	Sub-Menu	Description
	UserXoff		Set when the “CALIBRATE LEVEL” procedure is carried out, to correct for slight tilt offset due to mounting of the control module CM1 to machine chassis, and chassis to ground.
	UserYoff		
	Height1Min		Set when the “CALIBRATE HEIGHT” (or “CALIBRATE LOAD” dynamic) procedure is carried out, to determine the Angle Transducers measurements when the platform is fully lowered (0% height) and fully raised (100% height).
	Height1Max		
	Height2Min		
	Height2Max		
	ElevUp		Set when the “CALIBRATE HEIGHT” (or “CALIBRATE LOAD” dynamic) procedure is carried out, to determine the platform height.
	ElevDown		
	OVERLOAD CALS		This sub-menu provides access to the load calibration data created during the “CALIBRATE LOAD” loaded & empty procedure.
SERIAL NUMBER (Access level 2 required)			
	yy/mm/nnnnn		Displays the control module CM1 serial number

 Items highlighted in grey require access level 2.

5.5-4 Diagnostics, help messages and flash codes

Diagnostics

The display module shows the machine condition and operating information during operation.

Message	Description
INITIALIZING	Preparing to operate, immediately after power-on
SHUTDOWN	All operation prevented – for example both the PLATFORM & base emergency stop s inputs are active together
CHECK CANbus	All operation prevented – CANbus communications is not successful
PLATFORM, GROUND	Ready to operate, from the Platform or Base controls as indicated (selected by the two Emergency Stop inputs)
GROUND UP, GROUND DOWN, GROUND OUT, GROUND IN	A Base function is operating normally
GROUND UP LOCKED, GROUND DOWN LOCKED, GROUND OUT LOCKED, GROUND IN LOCKED	A Base function is selected but not allowed (for example, the switch was closed at power-on)
GROUND FAULTY	Multiple ground function inputs are active at the same time
WAITING FOR TRIGGER	A Platform function is selected, but the trigger Enable switch is not closed (close trigger switch to proceed)
TRIGGER CLOSED	The Platform trigger Enable switch is closed, but no function is selected (select a function to proceed)
TRIGGER LOCKED	The Platform trigger Enable switch was closed at power-on, or closed for too long with no function selected
FORWARD, REVERSE	A Platform drive function is operating normally
FORWARD (LEFT), FORWARD (RIGHT), REVERSE (LEFT), REVERSE (RIGHT)	A Platform drive function is operating normally, with steer also active
STEER LEFT, STEER RIGHT	A Platform steer function is operating normally (without drive)
UP, DOWN	A Platform lift/lower function is operating normally
OUT, IN	A Platform deck extend/retract function is operating normally
FORWARD LOCKED, REVERSE LOCKED	A Platform drive function is selected but not allowed (for example, the switch was closed at power-on)
POTHOLE -DRIVE LOCKED	The Pothole Protection switches have not engaged when raised Platform
LEFT LOCKED, RIGHT LOCKED	A Platform steer function is selected but not allowed (for example, the switch was closed at power-on)
CHECK JOYSTICK	Both Platform joystick directions are active at the same time
STEER FAULTY	Both Platform steer directions are active at the same time

Diagnostics (continued)

Message	Description
INTERLOCKED	An interlock shutdown is active, preventing one or more functions. The interlock can be due to many different causes – press <ENTER> from the display to see the precise cause of the interlock (listed below) – press <ESC> from that display to return to the mode display:
<ul style="list-style-type: none"> • ARMGUARD 	During descent, the control module CM1 can be configured to stop movement and provide an armguard delay (allowing time to check that everything is clear before continuing descent) Release and re-select DOWN to continue lowering (after the delay time has passed) If the armguard feature is not wanted,
<ul style="list-style-type: none"> • EXTERNAL ALL, EXTERNAL DRIVE, EXTERNAL LIFT 	An external cutout input is preventing functions – determine the cause of the external cutout
<ul style="list-style-type: none"> • NONE 	There is no interlock (the interlock has cleared while viewing the display)
<ul style="list-style-type: none"> • OVERLOADED 	The Platform is overloaded – reduce platform load
<ul style="list-style-type: none"> • TEST mode 	The control module CM1 test mode is active – switch power off and on again to clear
<ul style="list-style-type: none"> • TILTED 	The machine is tilted beyond limits, with the control module CM1 configured to prevent some functions when tilted (perhaps also elevated) – descend, then move machine to a more level location (see SETUPS/TILT SETUPS/TILT SHUTDOWN and ELEV.TILT SHUTDOWN)
<ul style="list-style-type: none"> • TOO HIGH 	The platform is too high to allow some functions – descend first (see ADJUSTMENTS/HEIGHTS/MAX DRIVE and MAX LIFT)
<ul style="list-style-type: none"> • TOO HOT 	The control module CM1 heatsink has reached 75°C, preventing all functions except lowering. Functions will be allowed again when the heatsink cools to below 70°C. The heatsink temperature can be viewed in the DIAGNOSTICS/SYSTEM/TEMPERATURE display.
<ul style="list-style-type: none"> • UNCALIBRATED 	The height and/or pressure sensors have not been calibrated and are required to measure platform height and/or load If overload functions are active (ADJUSTMENTS/OVERLOAD TRIP@, LAMP@ or ALARM@ set to a non-zero value) then both the height and pressure sensors must be calibrated If overload functions are not active, but height-based decisions are active (ADJUSTMENTS/ HEIGHT values set to between 1% and 100%) then the height sensors must be calibrated Calibration procedures are accessible from the SETUPS/HEIGHT SETUPS and SETUPS/LOAD SETUPS menus

Help messages

The display module shows help messages to show the machine conditions. Some messages cause the LED on the control module to flash so you can still do simple troubleshooting even if the display is not working.

IMPORTANT

Skyjack recommends reading the diagnostic messages from the display module and not the LED flash codes to troubleshoot the machine. The diagnostic messages give more detailed data.

LED flash codes

The diagnostic messages from the LED are shown as Dual Flash Codes. The LED flashes on/off a number of times, stay off for a short time, then flash on/off a number of times again then followed by a much longer off time. The sequence repeats.

For example, on/off/on/off/on/off-short-delay/on/off/on/off-long-delay/repeat

Flash Code	Description
LED on steady	There is no fault. All functions should be working normally.
LED off always	There is no power to the control module CM1. Check wiring to P3-1 and P4-1
LED flash code 1/x	The control module CM1 has not been properly calibrated. Check height and load calibration.
LED flash code 2/x	Something is preventing functions operating normally. check EMS inputs and all operator switch inputs (drive/lift mode, joystick, etc). Check for conditions which shut down functions (eg: tilted, too high to drive, platform overloaded, etc). NOTE: In base mode, only the base input switches are relevant. In platform mode the base input switches are ignored.
LED flash code 3/x	There is a problem with the line contactor or valve wiring, or with the motor power wiring. Disconnect connector P5 to see if the problem is caused by line contactor or valve wiring (if the fault clears, check for an illegal B+ supply in to P5). Check the motor power wiring. With the line contactor open, power terminals B+ and A should both be at 10V-15V (significantly lower than B+). If the LED is steady at power-on, and the fault (3/5) occurs after a delay when attempting to drive or lift, the motor may be stalled and causing an overload of the control module CM1.
LED flash code 4/x	There is a problem with battery supply, the height and/or pressure sensors, the supply to them, or the temperature sensor inside the Control Module CM1. Check battery supply to EMS inputs P3-1 or P4-1 (relative to the B- stud). The battery supply should be between 15V and 32V. Check the output from height and pressure sensors (P2/2, P2/4, P2-5). Check the 5V sensor supply (P2-1) If the control module CM1 heatsink is very hot then the controller has temporarily shut down – if so, platform lowering is still allowed. Wait for the controller to cool down.
LED flash code 6/x	There is a problem with load measurement – the height and/or pressure sensor measurements are out of range or the elevation switch disagrees with the height sensor. Check that the output from height and pressure sensors (P2/2, P2/4, P2-5) is in range (between 0.5V and 4.5V),
LED flash code 7/x	There is a problem with the power wiring – the voltage on the B+ stud is too low (it should be at least 10V at all times). Check for a short-circuit to the B+ stud.
LED flashing fast and continuously	This indicates that “factory override” is active – this special controller mode is intended for use during machine manufacture only (see OVERRIDE procedure) IMPORTANT: Never use a machine that is still in “factory override” – all safety and shutdown features are disabled!

Help messages and fault codes

Code	Message	Description	Flash Code
101	21510202 MENU	This is the part number of the control module CM1.	N/A
102	ACTIVE		N/A
103	CHARGING		N/A
104	CHECK DRIVE/LIFT SELECT SWITCH!	There is a problem with the platform drive/lift select switch – both modes are selected together.	2/2
105	CHECK GROUND INPUT SWITCHES!	There is a problem with the Base function select switches – more than one is active at the same time.	2/2
106	CHECK JOYSTICK SWITCHES!	There is a problem with the platform joystick switches – both directions are selected together.	2/2
107	CHECK RED KNOB	There is a problem with the red “manual holding valve” knob (if equipped).	N/A
108	CLOSE TRIGGER	A Platform function is selected but the trigger switch is not closed.	N/A
109	DRIVE LOCKED - POTHOLE!	The Pothole Limit switch(es) are tripped. Check limit switch(es) at P4-7.	N/A
110	DRIVING!		N/A
111	ENTER PINPAD CODE	Telematics input code required to unlock.	N/A
112	EVERYTHING OK	The control module CM1 is ready to operate in Platform mode when a function is selected. NOTE: If this is the HELP message when a function is selected, check for open-circuit switches or wiring.	N/A
113	EXTENDING DECK!		N/A
114	FACTORY OVERRIDE	When the controller is first shipped, prior to initial calibration, it is configured in a special “factory override” state. In this state, none of the normal shutdowns or interlocks will occur – the MEWP can be freely raised/lowered and driven irrespective of any calibration needs, tilt, etc. IMPORTANT: Never use a machine in factory override. This state is ONLY intended for use during manufacture! While factory override is active, the LED rapidly flashes on/off.	Fast Flashing
115	FAULT: B+ STUD VOLTAGE TOO HIGH - CHECK LINE CONT!	The voltage on the B+ stud of the controller (connected to an internal voltage stabilization capacitor bank) is close to B+ when the line contactor is off. Check the line contactor tips are not welded; check the power wiring for errors.	3/3
116	FAULT: B+ STUD VOLTAGE TOO LOW!	The voltage on the B+ stud of the controller (connected to an internal voltage stabilization capacitor bank) is too far from B+ when the line contactor is off (a pre-charge circuit in the module normally applies a voltage to the capacitor bank).	7/7
117	FAULT: BAD 5V SENSOR SUPPLY - CHECK P2-1 WIRING!	Check the power wiring for errors.	4/5
118	FAULT: BAD INTERNAL 12V!	The internal “12V” supply is out of range; if the fault remains, the controller may have to be replaced.	4/3
119	FAULT: BAD INTERNAL 5V!	The internal “5V slave” supply is out of range; if the fault remains, the controller may have to be replaced.	4/2
120	FAULT: BAD INTERNAL SLAVE!	The internal “slave” is not operating correctly; if the fault remains, the controller may have to be replaced.	4/2

Help messages and fault codes (continued)

Code	Message	Description	Flash Code
121	FAULT: BAD INTERNAL TEMPERATURE SENSOR!	The heatsink temperature is out of range. If the fault remains, the power controller may have to be replaced.	4/1
122	FAULT: BATTERY VOLTAGE TOO HIGH!	The battery supply is too high – check that the correct battery and charger are installed.	4/4
123	FAULT: BATTERY VOLTAGE TOO LOW!	The battery supply is too low – the battery must be re-charged.	4/4
124	FAULT: CAN BUS!	CANbus messages expected from one or more modules are not being received, or messages intended to one or more module cannot be transmitted. Check for open- and short- circuit problems with the CANbus wiring. Make sure that the CANbus is wired correctly pin-to-pin. Make sure that the machine chassis is not incorrectly shorted to the motor wiring (for example, due to insulator breakdown in the motor).	6/6
125	FAULT: CHECK ELEVATION SWITCH	This message does not apply to this machine. If this message shows on the Skycoded display, make sure the machine is calibrated correctly. If the message continues, contact the Skyjack service department.	6/3
126	FAULT: CHECK HEIGHT SENSORS	During calibration, both signals from the height sensor are giving an out-of-range voltage (below 0.5 V or above 4.5 V). Check for open or short circuit wiring; replace the height sensor if necessary.	6/1
127	FAULT: CHECK HEIGHT1 SENSOR	A height sensor is giving an out-of-range voltage (below 0.5V or above 4.5V). Check for open- or short-circuit wiring; replace height sensor if necessary.	6/1
128	FAULT: CHECK HEIGHT2 SENSOR		6/1
129	FAULT: CHECK PRESSURE SENSOR	The pressure sensor is giving an out-of-range voltage (below 0.5V or above 4.5V). Check for open- or short- circuit wiring. Replace pressure sensor.	6/2
130	FAULT: CUSTOMER	The control module has been configured to the incorrect VEHICLE (see SETUPS/MACHINE DEFAULTS/VEHICLE).	1/1
131	FAULT: ENERGIZED LINE CONTACTOR - CHECK P5 WIRING!	There is a voltage on the line contactor coil output when it should be off. Check wiring to line contactor coil.	3/4
132	FAULT: ENERGIZED VALVE - CHECK P5 WIRING!	There is a line voltage on a valve output from coils wired to P5. Check for a short circuit or illegal wiring.	3/2
133	FAULT: MOTOR OVERLOAD!	The control module CM1 power protection circuits have activated to protect from extreme overload. Check for short-circuit power wiring. Check for a seized motor.	3/5
134	FAULT: VALVE FEEDBACK HIGH - CHECK VALVE WIRING!	There is a voltage on one or more valve outputs, when all outputs should be off. Check wiring to each valve coil.	3/2
135	FUNCTIONS LOCKED - ARMGUARD	During descent, the control module CM1 can stop movement for a configurable time (see ADJUSTMENTS/ LIFT/ ARMGUARD), to allow a safety check that no-one is close to the machine. The operator must release and then re-select DOWN to continue lowering (after the delay timeout).	2/2

Help messages and fault codes (continued)

Code	Message	Description	Flash Code
136	FUNCTIONS LOCKED - EXTERNAL SHUTDOWN	An external shutdown is preventing functions – check DIAGNOSTICS/SYSTEM/MODE/ INTERLOCK to see which external interlock is active.	2/2
137	FUNCTIONS LOCKED - LOW BATTERY!	Battery voltage is low. Charge batteries and check wiring.	N/A
138	FUNCTIONS LOCKED - NO VALVE SUPPLY!	Valve supply has not been supplied. Check wiring and emergency stop switches to P3-2.	N/A
139	FUNCTIONS LOCKED - NOT CALIBRATED	If platform overload functions are active (ADJUSTMENTS/OVERLOAD TRIP@, LAMP@ or ALARM@ set to a non-zero value) then both height and load must be calibrated. If overload functions are not active, but height-based decisions are active (ADJUSTMENTS/ HEIGHT values set to between 1% and 100%) then height must be calibrated. Calibration procedures are accessible from the SETUPS menu.	1/1
140	FUNCTIONS LOCKED - OVERLOADED	The platform is loaded too high to allow operation – the platform load must be reduced.	2/2
141	FUNCTIONS LOCKED - TEST mode SELECTED	When the control module CM1 test mode has been activated (see DIAGNOSTICS/OUTPUTS), no functions are allowed. Switch power off/on to reset to normal operation.	2/2
142	FUNCTIONS LOCKED - TILTED	The machine is tilted too much to allow some functions. (see SETUPS/TILT SETUPS/TILT SHUTDOWN and ELEV.TILT SHUTDOWN).	2/2
143	FUNCTIONS LOCKED - TOO HIGH	The platform is raised too high to allow some functions. (see ADJUSTMENTS/HEIGHTS/MAX DRIVE and MAX LIFT).	2/2
144	FUNCTIONS LOCKED - TOO HOT!	Control module CM1 heatsink temperature exceeds 75°C, preventing all functions except lowering. Check for excessive motor current draw; check for good heatsinking to machine chassis.	4/2
145	FUNCTIONS LOCKED - UNDERLOADED	Platform overload features are active, and the platform load is too low to be valid – this could be caused by erroneous calibration, a sensor fault, or a change in the machine mechanics/hydraulics. (see SETUPS/LOAD SETUPS/ FAULTY LOAD).	2/2
146	GROUND mode ACTIVE!	The control module CM1 is ready to operate in Base mode when a function is selected.	N/A
147	HEIGHT NOT CALIBRATED	Height based functions are required (for example MAX DRIVE is configured), but height has not been calibrated. Calibrate height (see SETUPS/HEIGHT SETUPS) (see CALIBRATE HEIGHT procedure).	1/1
148	HELP:PRESS ENTER		N/A
149	IDLE TIMEOUT	Control module CM1 is in standby mode after no functions have been requested in some time.	N/A
150	LIFT LOCKED - OVERRISE	KC Only - check anti-override limit switches to P3-10 and P3-11.	N/A
151	LIFTING!		N/A

Help messages and fault codes (continued)

Code	Message	Description	Flash Code
152	LOGGED HELP		N/A
153	LOWERING!		N/A
154	NOT CALIBRATED	Height and load based functions are required (for example platform overload is configured), but height and/or load has not been calibrated.	1/1
155	OVERRIDE mode	MEWP is in Override mode. Do not operate in this mode, for servicing only. Cycle power to reset.	N/A
156	OVERRIDE=		N/A
157	OVERRIDE FAULTY	KC only - check anti-overrise limit switches to P3-10 and P3-11.	N/A
158	RELEASE GROUND SWITCHES!	Base function switches were closed at power-on (or a wiring error is causing an input to be active always).	2/2
159	RELEASE JOYSTICK SWITCHES!	Platform joystick S7 switches were closed at power-on (or a wiring error is causing an input to be active always). Platform joystick switches were closed for too long without trigger switch (see SETUPS/ INTERLOCKS/TRIGGERwait).	2/2
160	RELEASE TRIGGER!	Trigger switch S7-6 Enable was closed at power-on (or a wiring error is causing the input to be active always). Trigger switch was closed for too long with no function selected (see SETUPS/ INTERLOCKS/ TRIGGERonly).	2/2
161	RETRACTING DECK!	All the above HELP messages indicate that a function is active – the machine should be moving as requested by the operator.	N/A
162	S/N=		N/A
163	SELECT DRIVE/LIFT mode!	There is a problem with the platform S3 Drive/Lift select switch – neither mode is selected. Check wiring from S3 Drive/Lift select switch.	2/2
164	SHUTDOWN - CHECK EMS SWITCHES!	The platform and base EMS inputs indicate the mode in which the control module CM1 must operate. If neither input is active, or if both are active together, the control module CM1 does not know how to function. Check EMS switch wiring to P3-2 and P3-5.	2/1
165	STARTUP!	The control module CM1 has just been powered on and is carrying out some initialization steps prior to being ready to operate. If you select a function during this time, it may be locked out until you release then re-select it.	N/A
166	STEERING!		N/A
167	VEHICLE TILTED	The machine is tilted beyond the limits set by ADJUSTMENTS/TILT/Xtrip and Ytrip; some functions may be prevented	N/A
N/A	FAULT OUTPUTS	An output has detected a short circuit or over current.	N/A
N/A	LO OUTPUTS	There is a short circuit (or over current) to one or more of the low-side outputs.	N/A
N/A	HI OUTPUTS	There is a short circuit (or over current) to one or more of the high-side outputs.	N/A

5.5-5 Change the language

You can change the language of the messages shown on the Skycoded display.

1. Make sure the display is on the home page. If not, push and pull the emergency stop button on the base to cycle the power.
2. Press and hold the **↑** button for 3 to 4 seconds.
3. The display shows the language selection.
4. Press **↑** or **↓** to change the language.
5. Wait 3 to 4 seconds. The display automatically goes back to the home page with the new language.

5.5-6 Override mode procedure

The control module CM1 prevents machine movement if not calibrated correctly. This can make it difficult to move a machine with faulty sensors to a service location.

When you put the control module CM1 in an “OVERRIDE” mode, none of the usual shutdowns or interlocks occur. You can lift, lower and drive the machine freely regardless of calibration.

1. Press and hold the ESC button for 3 to 4 seconds.
2. Type in the “ACCESS LEVEL” 2 code to go into technician level 2 (see [5.5-8 Access levels procedure](#)).
3. Press **←** or **→** to get to “SYSTEM OVERRIDE.”
4. Press ENTER to place the MEWP into the “OVERRIDE” mode.

DANGER

Risk of death or severe injury. NEVER operate a machine for normal use that is still in “OVERRIDE” mode – all of the safety and shutdown interlocks are disabled! If the LED is flashing on/off rapidly, do not use the machine.

After you do the repairs and services and calibrate the machine again, push the emergency stop button on the base and then pull it out to disable the “OVERRIDE” permanently. The machine can now be operated normally.

5.5-7 Initial setup and change defaults procedure

The model of the MEWP and battery type used must be set in the control module CM1 to configure the machine size and capabilities. Do this procedure only if the control module CM1 was replaced.

1. Park the MEWP on level ground.
2. Press and hold the ESC button for 3 to 4 seconds.
3. Enter the “ACCESS LEVEL” 2 code to enable calibrations.
4. Press **←** or **→** to get to “SETUPS” and press ENTER to select.
5. The display shows “MACHINE DEFAULTS”. Press ENTER to select.
6. Press ENTER to run the “MODEL” option.
7. The display shows “1=3219 NA” for example, which is the machine type in North America.
8. Press **↑** until it displays the correct machine type and geographical region (NA, KC, CE, AS, etc.).
9. Press the ESC button to exit the “MODEL” option when the correct machine type is listed to load all the preprogrammed ADJUSTMENTS and LOAD curves for that machine type.
10. Press **←** or **→** to get to “BATTERY” and press ENTER to select.
11. The display shows “1=LEAD CELL.” Press **↑** to cycle between the following:
 - A. “1=LEAD CELL” if standard lead cell type of batteries are installed.
 - B. “2=AGM” if AGM type of batteries are installed.
12. Press ESC to exit the “MACHINE DEFAULTS” option.
13. Push and pull the emergency stop button to cycle power to the control module CM1 to save the changes.

5.5-8 Access levels procedure

1. “ACCESS LEVEL” 1, (CODE XXXX) - FOR INITIAL FACTORY USE ONLY.
2. “ACCESS LEVEL” 2, (CODE 1122) - To access the setups and adjustments.
 - A. Make sure the display reads “EVERYTHING OK.”
 - B. Press and hold the ESC key for 3 to 4 seconds.
 - C. Press ◀ or ▶ to find the “ACCESS LEVEL” menu. Press ENTER to and select it.
 - D. The display shows 0000. The first 0 flashes.
 - E. Set the first digit of the code using (↑ and ↓).
 - F. Press ▶ to move to the next digit. The first 0 stops flashing and the second 0 starts flashing.
 - G. Set the second digit of the code.
 - H. Repeat steps D and E to set all the code digits. If a digit is entered incorrectly, press ◀ and ▶ to select it again and ↑ and ↓ to select the correct digit.
 - I. Press ENTER to confirm the code. The “ACCESS LEVEL” changes if the correct code is entered.
3. “ACCESS LEVEL” 3 - For daily normal operation level defaulted after cycling power.

PUMPMODE

4. “PUMPMODE” (CODE 1234) - Allows all electrical function to operate with P5-1 C1 motor contactor output disabled for troubleshooting without the pump motor engaging.



NOTE

Cycling power to the control module will restore you to “ACCESS LEVEL” 3.

5.5-9 Calibrate level procedure

The integral tilt sensor of the control module CM1 must be calibrated to compensate for errors due to installation or replacement of the control module CM1. Do this procedure only if necessary.

1. Park the MEWP on level ground.
2. Enter the “ACCESS LEVEL” 2 code to enable calibrations (see [5.5-8 Access levels procedure](#)).
3. Press ◀ or ▶ to get to the “SETUPS” menu. Press ENTER to select it.
4. The display shows “MACHINE DEFAULTS”.
5. Press ◀ or ▶ to get to the “TILT SETUPS” menu. Press ENTER to select it.
6. Press ENTER to run the “CALIBRATE LEVEL” option.
7. The display shows “YES: ENTER, NO:ESC”, asking for confirmation that the machine is level.
8. Press ENTER to confirm that YES calibration is required.
9. The display now shows the current tilt measurements. If the leveling procedure was successful then both the “X” and “Y” tilts should be about zero.
10. Press the ESC button to exit the “CALIBRATE LEVEL” option.
11. If the tilt measurements are not zero in step 9, try the procedure again – press ESC then ENTER and repeat from step 4.
12. If the tilt measurements still cannot be zeroed, check that the machine is correctly parked on level ground, and check that the control module CM1 is correctly and securely installed on a vertical surface of the machine base with the connectors at the bottom.
13. Push and pull the emergency stop button to cycle power to the control module CM1 to finish.

5.5-10 Calibrate load procedure

The control module CM1 needs calibration before it can calculate the platform load.

NOTE

This procedure is completed during factory build of the machine and ONLY needs to be done if the control module CM1 is replaced.

IMPORTANT

Any changes to the machine mechanics, hydraulics, etc. may require recalibration!

Calibration of the MEWP automatically stops and starts the platform at different points and records the lift cylinder pressure and scissor angles to enable the load sense:

- A. **LOADED** calibration – a fully loaded platform raised and lowered with stops to take measurements.
- B. **EMPTY** calibration – an unloaded platform raised and lowered with stops to take measurements.

The following procedure must be followed COMPLETELY to calibrate the control module CM1. Throughout the procedure different checks are made. If a problem is detected the procedure stops and the module displays a FLASHING failure message.

NOTE

If the calibration procedure is interrupted, completed phases do not need to be repeated. A “REDO” prompt appears – answer “NO” if there is no reason to repeat the phase, or “YES” if you need to repeat the phase (for example, a significant mechanical or hydraulic change is made).

Calibration Load Procedure

1. Park the MEWP on level ground.
1. Make sure the Level Calibration is done (see [5.5-9 Calibrate level procedure](#)).
2. Enter the “ACCESS LEVEL” 2 code to enable adjustments and calibrations (see [5.5-8 Access levels procedure](#)).
3. Press **←** or **→** to get to “LOAD SETUPS”. Press ENTER to select it.
4. Press ENTER to run the “CALIBRATE LOAD” option.
5. Hold the base keyswitch in the base position through the rest of the procedure.

NOTE

If you release the base keyswitch switch during calibration, the process cancels and you have to start again from the beginning!

6. The display shows “PLATFORM DOWN?”, asking for confirmation that the platform is completely lowered.
 - A. Press the ENTER button to confirm.
7. The display shows “PLATFORM LOADED?”, asking for confirmation that the platform is loaded.
 - A. Toggle between LOADED and EMPTY with the **↑** and **↓** buttons.
 - B. If a rated load is available, add the rated load on the platform then press the ENTER button to confirm that calibration is done LOADED.
 - C. If no load is on the platform, make sure the platform is empty then press the ENTER button to confirm that calibration is done EMPTY.
8. The display shows “PLEASE LIFT ...”.
9. Turn the lift/lower switch to the lift position, and hold it there. The platform starts to lift.
10. After a delay the system automatically stops the platform lift and takes height and pressure measurements. The display shows “MEASURING #xx”.
 - A. When the measurements have been taken, the platform resumes lifting.

NOTE

If you release the lift switch switch during calibration, the process cancels and you have to start again from the beginning!

11. The lift/stop/measure/lift process continues automatically until the platform reaches full height.
12. When the platform reaches full height and the display shows a height of 100%, release the lift switch.
13. The display shows “TOTAL DATA: xx” to indicate the number of measurements taken, then shows “PLEASE LOWER ...”
14. Turn the lift/lower switch to the lower position and hold it there.
15. The display shows “LOWER LOADED” with the current height (from 100% to 0%).

16. After a delay, the system automatically stops the platform lower and takes height and pressure measurements. The display shows “MEASURING #xx.”
- A. When the measurements have been taken, the platform resumes lowering.

**NOTE**

If you release the lower switch during calibration, the process cancels and you have to start again from the beginning!

17. The lower/stop/measure/lower process continues automatically until the platform is fully lowered.
18. When the platform is fully lowered and the display shows a height of 0%, release the lower switch.
19. The display shows “TOTAL DATA: xx” to indicate the number of measurements taken.
20. The load calibration “LOADED” phase is complete.

Calibration date

21. The display shows “CALDATE: mm/dd/yy” with the “mm” value flashing.
22. Enter the current date here to provide easy tracking of the last calibration. The date can be seen in the “LOG” menu available in the “DIAGNOSTICS” menu.
- A. Use ↑ and ↓ to set the month, then press → to move to the day. Set the day and year in the same way.
- B. Press ENTER to complete date entry. The system stores it.
23. The display shows “FINISHED!”

IMPORTANT

Press the ESC button a few times to exit the “CALIBRATE LOAD” option and return to the home screen. The MEWP is not usable until you do this.

24. The control module CM1 is now fully calibrated.

5.5-11 All motion alarm

1. Make sure the display is on the home page. If not, push and pull the emergency stop button on the base to cycle the power.
2. Press and hold the ESC button for 3 to 4 seconds.
3. Enter the “ACCESS LEVEL” 2 code to enable adjustments and calibrations (see [5.5-8 Access levels procedure](#)).
4. Press ← or → to get to “ADJUSTMENTS” and press ENTER to select.
5. Press ← or → to get to “ALARMS” and press ENTER to select.
6. Press ← or → to get to “DRIVE”.
7. Press ↑ or ↓ to change the value to 4. Press ENTER to select it.
8. Press ← or → to get to “LIFT”.
9. Press ↑ or ↓ to change the value to 4. Press ENTER to select it.
10. Push and pul the emergency stop button to cycle power to the MEWP and save your settings.

5.5-12 Calibration fault codes

During calibration, the control module CM1 repeatedly checks for possible problems which might prevent successful calibration, or subsequently give inaccurate platform load estimates.

If problems are detected, a flashing error message immediately displays and calibration terminates. The problem must be resolved, and then calibration must be restarted.

Fault code list

Most calibration error messages have an “Fxx” number as well as a description, to aid in troubleshooting.

Fault Code	Description
F01:CANNOT RUN	Something is wrong, preventing the control module CM1 from running – check the HELP message (causes include line contactor, valve, or motor wiring errors).
F02:NOT GROUND mode	Calibration can only be carried out from base control!
F03:NOT STOPPED	The machine must not already be moving when calibration started.
F04:TILTED	The machine must be on level ground when calibration started.
F05:BAD HEIGHT1	At the start of calibration, the Angle Transducers are out of range (output must be between 0.9V and 4.1V with Platform fully lowered).
F05:BAD HEIGHT2	
F06:CHECK ELEV	At the start of calibration, the Angle Transducers require calibration with Platform fully lowered.
F07:BAD HEIGHTS	During calibration, the two Angle Transducers disagreed too much.
F08:CHECK ELEV	The Angle Transducers require calibration with the platform fully raised.
F09:BAD HEIGHT1	The Angle Transducers are out of range when fully lowered (0%) calibration is recorded (output must be between 0.9V and 4.1V with platform fully lowered).
F09:BAD HEIGHT2	
F10:BAD HEIGHT1	The Angle Transducers are out of range when fully raised (100%) calibration is recorded (output must be between 0.6V and 4.4V with platform fully raised).
F10:BAD HEIGHT2	
F11:NOT UP	When instructed to go up (raise the Platform) the DOWN switch was activated.
F11:NOT DOWN	
F12:TOO MANY	More than 500 samples are recorded during dynamic lifting – the machine lifts too slowly. Increase the value of SETUPS/HEIGHT SETUPS/SAMPLE@ to delay longer between each sample (do not increase too much, as this will cause inaccurate dynamic load estimates).
F13:LOW HEIGHT RANGE	There is not enough difference between the Angle Transducers output when fully lowered, and fully raised (minimum allowed difference is 1V). Make sure the UP switch is not released before the platform is fully raised.
F14:BAD HEIGHT1	The Angle Transducers output is bad during dynamic lifting (must be between 0.6V and 4.4V always).
F15:CHECK ELEV	The Angle Transducers is open with platform fully lowered at the end of the dynamic raising / lowering cycle – or the switch changed state more than once.
F16:LOW ELEV.OPEN	The point at which the Angle Transducers are open while the platform was lifting, is too low (it should open between 5% and 20% height).
F17:HIGH ELEV. OPEN	The point at which the Angle Transducers are open while the platform was lifting, is too high (it should open between 5% and 20% height).

Fault code list (continued)

Fault Code	Description
F18:LOW ELEV. CLOSE	The point at which the Angle Transducers are closed while the platform was lowering, is too low (it should open between 5% and 20% height).
F19:HIGH ELEV. CLOSE	The point at which the Angle Transducers are closed while the platform was lowering, is too high (it should open between 5% and 20% height).
F20:HEIGHT1<>0%	After fully raising and fully lowering the Platform, during dynamic or static calibration, we should always be back at 0% height!
F20:HEIGHT2<>0%	
F22:HEIGHT1<>100%	After fully raising the Platform, during static calibration, we should always lift to 100% height!
F22:HEIGHT2<>100%	
F24:TOO MANY	During static (loaded or empty) calibration, no more than 20 measurement points can be recorded! A properly working machine with lift cylinder pressure reliably indicating platform load, should not require more than 10 measurement points.
F27:BAD HEIGHT	During static (loaded or empty) calibration, the platform height is out of range (below 0% or above 100%, or below 0.4V or above 4.6V).
F30:BAD HEIGHTS	At the end of static (loaded or empty) calibration, the sequence of recorded height measurements is invalid!
F34:REJECT CURVE	At the end of dynamic calibration, the recorded height/pressure curve is checked – the expected curve has a high pressure peak near the bottom (due to maximum lift needed when the scissor arms are nearly horizontal), a low pressure trough near the middle, and a higher peak near the top.
F40:REJECT DELTA DOWN @	At the end of all static calibrations, the loaded and empty height/pressure curves are compared – the loaded curve should be higher than the empty curve, due to the additional platform load. IMPORTANT: Make sure that loaded calibration is done with rated load in the platform, and empty calibration is done with no load in the platform!
F40:REJECT DELTA UP @	
F42:LOW PRESSURE	When the platform is fully lowered, the lift cylinder pressure cannot be checked – therefore soon after lifting begins during static (loaded and empty) calibration, the lift cylinder pressure is checked. This make sures that a hydraulic problem is discovered early, instead of waiting till calibration has been completed but with bad data! The lift cylinder pressure transducer output must be between 0.4V and 4.6V at all times.
F43:HIGH PRESSURE	
F44:LOW PRESSURE	During static (loaded or empty) calibration, the lift cylinder pressure is out of range (below 0.4V or above 4.6V).
F45:HIGH PRESSURE	
F46:CHECK ELEV	During dynamic calibration, the angle transducer changed state (closed to open, or open to closed) more than once!
F47:CHECK ELEV	
F48:BAD PRESSURE	At the start of calibration, the pressure sensor is out of range (output must be between 0.3V and 4.8V at all times)
F49:TOO FEW	At the end of static (loaded or empty) lifting or lowering calibration, too few measurements were taken (a minimum of 4 measurements is required). Check that SETUPS/HEIGHT SETUPS/MIN LIFT is not set too high. Recommended values are between 1s for fast lifting machines, and 3s for slow lifting machines.
F52:NOT CALIBRATED!	Something happened to cause calibration to fail – it is recommended to check all sensor wiring for loose connections, then repeat calibration.

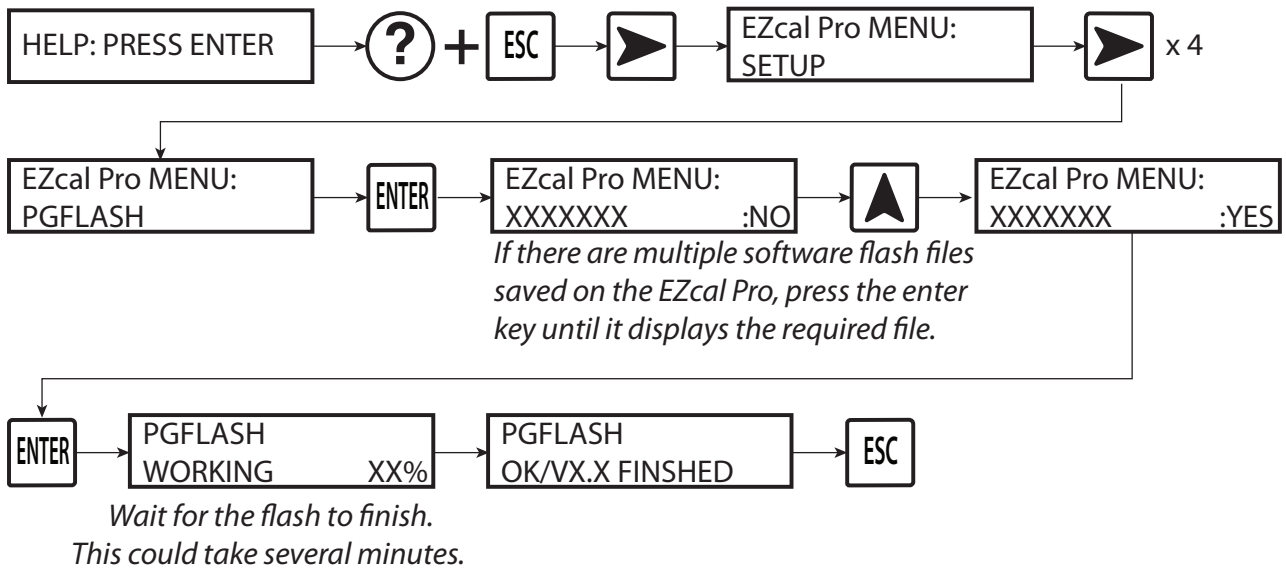
Fault code list (continued)

Fault Code	Description
F98:OUT OF RANGE	During static or dynamic calibration, the lift cylinder pressure is out of range (below 0.4V or above 4.6V)
FINISHED!	<p>This display occurs when all calibrations (dynamic, loaded up, loaded down, empty up, empty down) have been completed, and the CALDATE has been entered.</p> <p>Be sure to press <ESC> on the display module to exit calibration, before attempting to use the machine.</p>
GO UP MORE!	During calibration, the operator needs to close the UP or DOWN switch as required to lift or lower the platform – if the switch is closed in the wrong direction, no fault occurs but the machine does not move! This display clarifies the error.
GO DOWN MORE!	
IGNORING	During static (loaded or empty) calibration, it may happen that a second measurement is taken very close to the previous measurement (for example if the operator lets go the UP/DOWN switch – no fault occurs, and this display indicates that the new measurement is being ignored.
PLEASE WAIT	During calibration, the control module CM1 sometimes delays while waiting for sensor values to stabilize – this display indicates why nothing appears to be happening.

5.6 Software Updates

5.6-1 Flash the controller

1. Plug the red EZcal Pro device into a USB port on your computer.
2. Open the EZcal device folder on your computer.
3. Copy the new software flash file to this folder. Note the name of the file.
4. When the file is copied, eject the EZcal Pro. Unplug the USB cable.
5. Plug the EZcal Pro into port P1 on the Skycoded controller board.



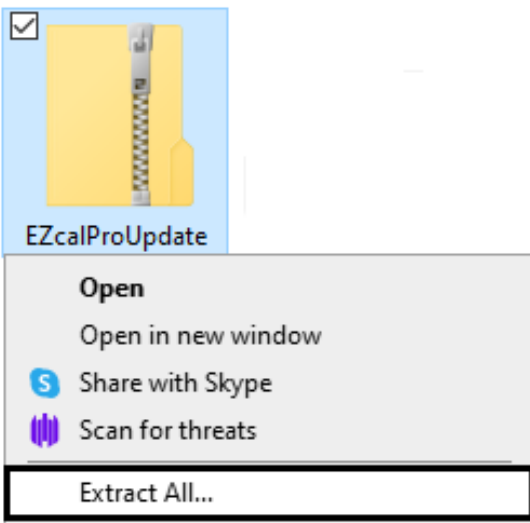
5.6-2 EZcal pro update

1. Download the latest EZcal Pro update file to your computer from <https://ezcaltools.com/ezcal-pro-update/>
2. Locate the folder where the zip file was downloaded. Right-click on the zip file and select “Extract all”.

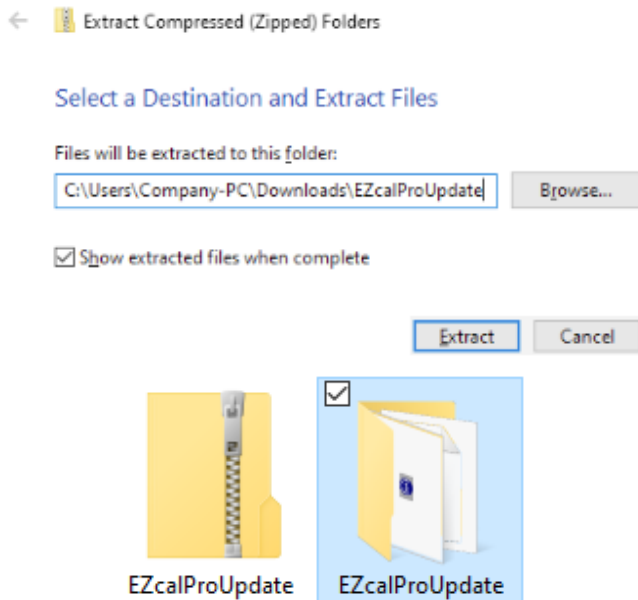


NOTE

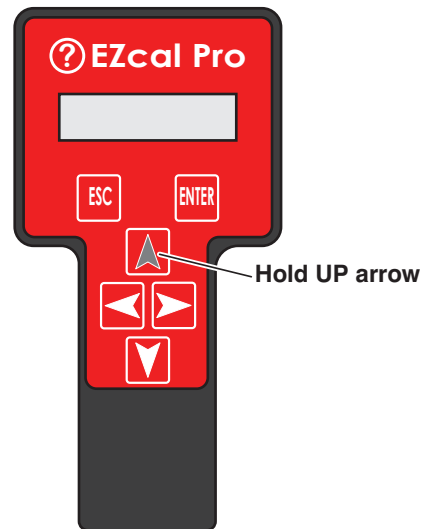
The folder contains an executable file which may be blocked by some computers. Contact your IT department for assistance.



3. Select the destination folder and click “Extract”. A new folder “EZcalProUpdate” is created.



4. Connect EZcal Pro to the computer while holding the UP arrow. After connecting, the EZcal Pro backlight flashes rapidly.

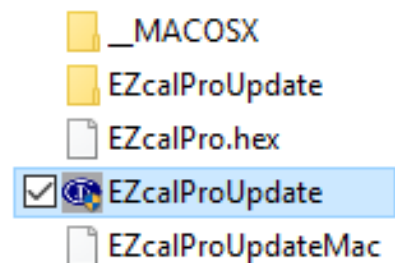


5. Open the new “EZcalProUpdate” folder and double-click on the “EZcalProUpdate.exe” file.

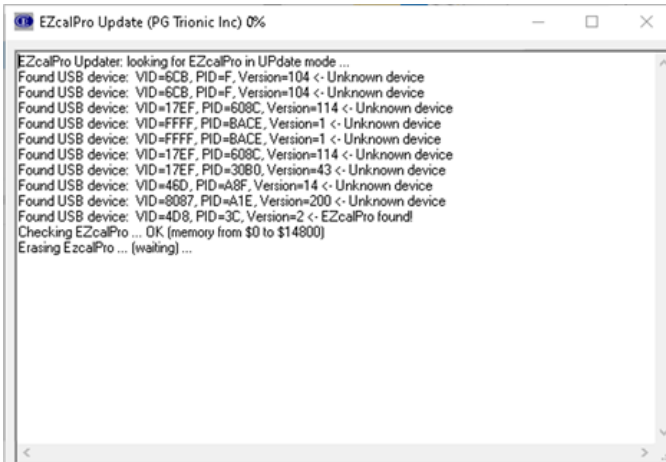


NOTE

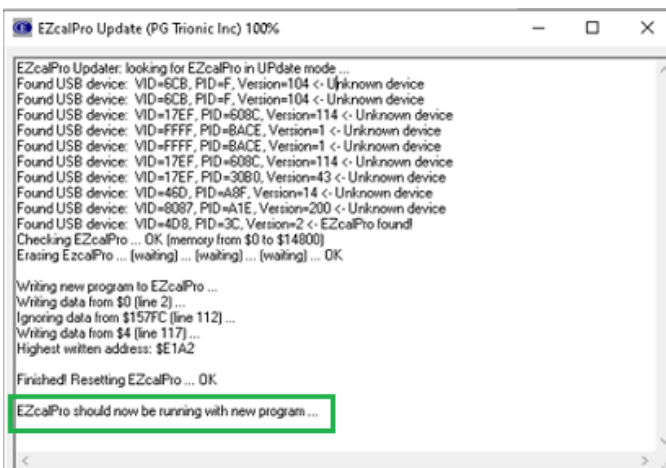
EZcalPro.hex file should be in the same folder as the EZcalProUpdate program. The update file will not execute if the file is moved to another location.



- An EZcalPro update window appears and starts updating the EZcal Pro device.



- Once the EZcalPro update window displays “EZcalPro should now be running with new program...”, the update is completed. The EZcal Pro device restarts.



- Close the EZcalPro update window and disconnect the EZcal Pro device.

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